

Flush Type Wire EDM Operation Manual



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I. Introduction



Introduction

1.Model

This operation manual is suitable for the following models:

Model/MFG	Model	Wire I	EDM	Control Unit	Spark Unit
KENT USA ROBOSTAR Wi-200	Wi-200	Submerge Type		SY	
KENT USA ROBOSTAR Wi-30E	Wi-30E	Flush Type	×	5	Ø
KENT USA ROBOSTAR	Wi-50E	Flush Type	WJS2 (Machine	WIS1 B box	WISLC box
Wi-50E	Wi-50ES	Submerge Type	WJS3 (Water Tank)	WJ51-D 00X	WJ31-C 00X
KENT USA	Wi-430	Flush Type			
R Wi-430	Wi-430S	Submerge Type			
KENT USA	Wi-640	Flush Type			
ROBOSTA R Wi-640	Wi-640S	Submerge Type			

2.Manuals

The following manuals are applicable to the KENT USA ROBOSTAR series :

• KENT USA ROBOSTAR Series Operation Manual

This manual describes the operations of Wi-430 · Wi-530 · Wi-640 which is divided into 3 major parts as given in following :

- Basic operations and practical operations
- Graphic setting and problem prevention
- Program instructions and functions

• KENT USA ROBOSTAR Series Maintenance & Service Manual Describes how to carry out maintenance for Wi series.



KENT USA ROBOSTAR Series Machining Parameters List Lists the machining conditions, cutting feed speed and other data in relation to machining when Wi series. are used. This machining parameter list can be referred when selecting and setting machining conditions.

3.How to use this manual

This manual uses the following symbols :

Symbol	Description	
⊠Warning	This symbol indicates improper operation which will result	
	in dangers to the operator.	
! Note	This symbol indicates improper operation which will lead	
	to machining errors or machine damages.	
A Hint	This symbol provides useful information and describes	
	convenient operation methods.	

Cautions during operation

l≫ Warning	1.	Never come into contact with the cutting wire while machining.
		There is very high voltage on the cutting wire during machining,
		so never come into contact with the cutting wire; otherwise
		electric shock may be resulted.
		When power to the machine is switched on, never open the door
		of the digital controller. There is high voltage at certain parts of
		the digital controller, therefore when power to the machine is
		switched on; never open the door of the digital controller,
		otherwise electric shock may be resulted.



! Note

Please back- up the programs, machining conditions, parameters and other data. The programs, machining conditions, parameters and other data need to be saved in the CNC. Usually these data can still be kept when power is off. However, all the data may have to be removed due to the operation errors or failures in order to restore the new data or repair errors. The basic data are stored in the back- up disk of the machine. Programs and machining conditions that are designed by the operator can only be saved in the CNC.

Please back- up the programs, machining conditions as well as other important data for storing the accumulated data. To understand more about backing up data, please refer to Part IV in Chapter8.

Hint

Parameters :

Please setup the required values for operating the machine. If wrong parameters are set, then the machine may result in failure of operation or abnormal operation. For the machine itself, the parameters are very critical data.

Back- up :

The text back- up is an auxiliary tool. But in this manual, a back- up means a data back- up. The disk containing the back- up data is called the back- up disk.



Wire EDM Structure

ROBOSTAR WI series are C NC Wire EDM Machine. This machine uses cutting wire as electrode and machining workpiece on XY table. XY table is controlled by CNC controller. KENT USA Wire EDM contains 5 major parts, including Machine base, NC controller Spark Unit, Water system and Optional accessories coolant unit.



Fig 1-1ROBOSTAR Wire EDM structure



2 Specification

2.1 Machine Specification

Machine Base

Item		Wi-200	Wi-30	Wi-430	Wi-50
Max.	Submergible	550*470*115	660*525*300	660*525*300	830*540*295
Workpiece	Type WEDM			6	
dimension	Flush Type		790*520*300	790*520*300	870*520*295
	WEDM				0.
Max.	Submerible Type	500kg	500kg	500kg	700 kg
Workpiece	WEDM		Ç		\mathbf{D}
weight	Flush Type		500kg	500kg	700 kg
	EDM				
Table travel		210×200 mm	400×300 mm	400×300 mm	400×300 mm
WT. Of Machine Base		1700kg	2000kg	2000kg	2000kg
Z axis travel		120 mm	300 mm	300 mm	300 mm
UV axis travel		30*30 mm		100×100 mm	
TT 7 (X				
water sy	stem				

Work Fluid		Pure water			
Water tank	Submergible	450L	580L	580L	580L
Capacity	Туре				
	Flush Type		270L	270L	270L
Filtration	rate	40L/min	40L/min	40L/min	40L/min
Filter Submergible		Paper FilterX2			
	Туре				
	Flush Type		Paper F	FilterX2	
ION -	Submergible	5L×1	5L×2	5L×2	5L×2
exchanger	Туре				
	Flush Type		5L×1	5L×1	5L×1
Control of water		$(2.5 \sim 5.0) \text{X} 10^4 \Omega.\text{cm}$			
conductivity					



2.Specification

ITEM		Wi-640	Wi-A70	Wi-A90
Max.	Submergible	920*725*350		
Workpiece	Type WEDM			
dimension				
	Flush Type	1040*775*350	1165*680*295	138*760*295
	WEDM			
Max.	Submerible	1000kg		
Workpiece	Type WEDM			
weight	Flush Type	1000kg	1000kg	1300 kg
	EDM			5
Table travel	I	640×450 mm	750×450 mm	900×500 mm
WT. Of Machine Base		3500g	4000kg	5000 kg
Z axis travel		350 mm	300 mm	300 mm
UV axis travel			100×100 mm	
			0	
Water syst	em			
TTT 1 TT1 ' 1			DIT	

Work Fluid		Pure Water		
Water tank	Submergible	900L		
capacity	Туре			
	Flush Type	350L	360L	360L
Filtration ra	ite	40L/min	40L/min	40L/min
Filter	Submergible Type		Paper FilterX2	
ION-	Submergible	5L×2		
exchanger	Туре			
C	Flush Type	5L×1	5L×1	5L×1
Control of water conductivity		$(2.5 \sim 5.0) \text{X10}^4 \Omega.\text{cm}$		
Servo motor X/Y axis		AC Servo Motor		
	U/V/W axis			
	Z axis	A	C Servo Motor + brea	ker
Max. Table fe	ed rate	800 mm/min		
Wire Diameter	r	0.1 ~ 0.33 mm		
Wire tension		200 ~ 2400gf		
Wire feed rate		0 ~ 15m/min		
Tolerance		0.001 mm/0.0001inch		
Max.	STD. accessories	$\pm 15^{\circ}$		
Taper OPT. accessories		±22.5°		
Guide		Diamond Guide		
Max. wire load		6kg		



2.2 Sparking Power

Category	Description
Power MOS loop	Power MOS transistor
ON TIME	24 Steps (0.05~0.9 μ sec)
OFF TIME	43 Steps (8~50 μsec)
Max. Current	25A
No load voltage	96V
AC power	AC POWER
neric control unit	× ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~

2.3 Numeric control unit

Code	Item	Description		
(1)	Control Axis	X,Y,U,V,Z		
(2)	Min. Increment	0.001mm/0.0001inch		
(3)	Min. Command Increment	0.001mm/0.0001inch		
(4)	Insert Function	Line · Arc		
(5)	Max. program setup dimension	±999.999mm		
(6)	Position Command	REV and ABS coordinate		
(7)	Display device	15"LCD touch screen		
(8)	Position Display	5 axis included(X, Y, U, V, Z)		
(9)	EDM DATA	0 ~ 999(1000 groups)		
(10)	Data Input Device	Flash drive 、Network transmission 、		
		RS-232		
(11)	Graphic Zooming	0.001~99.999		
(12)	Rotation	±0.001°~±360°		
(13)	Mirror	Mirror on X and Y axis		
(14)	Graphic Simulation	3D display on X, Y, U, V axis		
(15)	Feed rate speed	Fast moving: 400mm/min		
		Manual : 100, 200, 300, 400mm/min		
	·	Dry Run : 0 ~ 400mm/min		
(16)	Wire diameter compensation	±99.999mm		
(17)	Working History · 100Coordinate system · Perpendicular rectifier · Retract to original			
	point · Screen saver · Taper Cut · Maintained history · Axis exchange · Back slash			
	compensation · Pitch compensation · Parallel compensation · Software limit · Safety			
	zone · Dry Run · Single block execute · Machine lock · Selected block executed ·			
	Selected hold · Auto Positioning (Hole · Center · Slit · Edge Side · Board Width ·			
	Arc)			



2.4 Environmental Condition

Main Power	AC • phases50/60Hz		
Power required	11KVA(without chiller)		
	13KVA(with chiller)		
Environment	Temperature 5°~40°C • * Room temperature 25±1°C and no dust is		
	necessary for high accuracy machining.		
	Humility : Lower than 75%RH		
	Vibration : Lower than 0.6 mm/S ² (0.06G)		
Ground	To keep the stability of machining, machine grounded is necessary. Use10		
	Ω for grounding.		
Protection	Avoid Noise. Prevent the interference of electric wave		

2.5 Standard and Optional Accessories

Standard accessories			
Perpendicular rectifier		l set	
Diamond Guide(ϕ 0.25mm)	1	l set	
Wire(ϕ 0.25mm,3kg)	1	l set	
Water tank(without chiller)	1	l set	
Remote Control	1	l set	
Tool Box	1	l set	
ION- exchanger(5L)	1	bag	
Filter	2	2 pcs	
Optional a	accessories		
$\phi 0.10 \sim \phi 0.33$ mm Diamond guide	22.5° Wide angle flush head		
CAD/CAM	Voltage stabilizer		
3Ror EROWA holding jig	MPG		
Chiller			
Water conductivity meter			
Wire tension meter			
Wire speed meter			



B Components

3.1 component Name



Figure 3-1.1 Wire Cut Component



3.2 Function of Components

Hint 🔎



Figure 3-2.2 Lower section of wire guide



Diamond Guide: It is used to support cutting wire. Diamond guide contains hi-precision ceramic guide. It can be used for the wire size of the wire size of 0.1mm~0.33mm. Please select the suitable wire guide for the cutting wire.

Flushing Head: Fluid would flush from flushing head. The design of the flushing head helps the working fluid to the cutting area efficiently. Larger flushing head is designed for larger taper machining.

Power contactor: Power contactor provides the voltage on cutting wire. Because the power contactor will contact with cutting wire frequently, the erosion marks will appear on the contactor and cause to break the wire easily. Thus please replace power regularly.

Flush fixed base: Flush base use water to send the cutting wire from lower machine head to waste wire tank.

Upper Support Arm: Upper support arm can adjust the height of upper machine head base on the thickness of workpiece. Press +Z or -Z on the control panel to adjust the height of machine head. On the Z axis, a piece of table place stop plate on the holder, may be used to install the Alignment tool.



Figure 3-2.3 Upper support arm



Work Table Work Table contains a table and overhanging bridge. Adjust the corrective device base on the size of workpiece.



Jig tool

Figure 3-2.5 Jig tool and screw

Screw

Jig







Figure 3-2.6 Lower support arm

Water seal board and supporting water guard can prevent water leaking from water tank. Supporting water guard is fastened on water seal board.

Water pressure gage:Water pressure gage is used to detect the water pressure on upper and
lower flush head. Water pressure is increased when the Pressure increase
setting is activated in Parameter setting. Actual pressure is determined
base on the distance between flush head and surface of workpiece.



Figure 3-2.7 Water pressure Gage



Work Tank: Control the amount of the work fluid.

- (1) Water Pump will pump the fluid to Mechanical device. The amount of fluid sent by Water tank is depending on the setting.
- (2) Filtrate the debris.

After dump the waste water in waste water tank, machine will filter the waste water through the filtration system and back to clear water tank

(3) ION- exchanger contains resin, which can use to adjust the water resistance . While the machine is ON, the water resistance detected begin to function. If the water resistance is lower than 25KΩ, Water Pump will pump the water to ION- exchanger unit and back to water tank until the water resistance is reach 50KΩ.

Water system control 0 0 POWER 咼瀇馬: Ο 參相器 高壓馬 VERTER 7300 柏 0 0 stem √ater 5 POWER : Water system power LED light. When 《E.STOP》 is ON, LED in ON. FILTER : LED of Water Filtration System Pump. While the LED is on, it means system error I.E. RESIN : LED of ION-Exchanger. While LED is ON, it means system error. INVERTER : LED of High Pressure Pump. While LED is ON, it means system error. H.P.: LED of Fast speed water inlet pump. While LED is ON, it means system error

Figure 3-2.8 Wi-A30E Flush Water Tank

devic



! Note:

When Work Fluid is too low, please add pure water in water tank.



Figure 3-2.8 Wi-A60E Water Tank

! Note:

When Work Fluid is too low, please add pure water in water tank.



3.Components

Coolant Unit: This unit is used to control the temperature of working fluid (Chiller). Temperature of Working Fluid is important to the stability and the precision of workpiece. (Chiller: optional accessories)





4 Axes and Moving Direction



Figure 4-1 Axes and moving Direction

- The moving direction of each axis is defined by the position of upper and lower section of wire guide.
- Work Table is moved follow by the X and Y axis instead of lower wire guide.
- U axis and V axis are paralleled with X and Y axis.

U axis and V axis movement is used for Cone Shape machining. It's not suitable for Vertical machining.

! Note

The movement of X,Y axis is on work table, not on the lower wire guide.

The movement of U, V axis is on upper wire guide.







D Moving

5.1 Machine

(1) Use Forklift to move machine (shown as below)





5.2 Power Generator

(1) Use Eye Bolt to lift Power Generator. (There are 2 eye bolts on the top of Power generator).



(2) You can push to move the power generator on the ground.

- * Be sure the ground surface is smooth and the path is clear while moving Power generator.
 - * To prevent the power generator tumble, be sure there are people on each side of power generator.

5.3 Water Tank

(1) Use Forklift to move the water tank unit, (Shown as below)



(2) Water tank can be pushed while it's on the ground.

! Note



6 Location

CNC EDM is a precision machine. Please carefully select an installation site according to following points :

 Install the machine at less dust and bright place, but avoid being exposed under direct sunlight.

 The machine must be installed at a wellventilated and temperature regulated place (Suggested work temperature to be 25°C). Avoid air conditioner to blow air directly to the machine.





3. The machine must be installed on a novibration and solid ground.



- The machine surroundings should be reserved a sufficient space (at least 300mm) for the convenience of loading workpiece and machine service.
- 5. The path where the machine will pass should be safe and wide enough.



6.1 Requirement

- (1) Provide enough power for the power supplier, voltage stabilizer is recommended; Protection is necessary during the installation.
- (2) For safety reason, machine needs to be grounded and operator is suggested to stay on a wooden plane.

6.2 Leveling

(1) Put Level on work table





6. Location



(3) Repeat the leveling procedures to make sure having the best leveling on work table.

6.3 Clean grease

In order to prevent rust on parts of machine during transportation and storage, put the grease on the surface of parts is necessary. Remove the grease before using machine. After grease is removed, please inject lubricant oil.

Mobil No2. 68 Stork 70087 P



Installation

Before install machine, make sure the power source is stable and reach the requirement voltage. If the voltage provide is not sufficient and unstable, it will impact the working efficiency or cause the controller malfunction. Voltage stabilizer is recommended.

7.1 Remove the lock block

(1) Remove the metal cover on upper machine head and on lower machine base.





7. Installation

(2) Remove the lock block on X, Y, U, V axis.



7.2 Connect all connectors

Connect all connectors from machine base to power generator and water filtration unit. Shown below:





- (1) Electrical Control Box
 - 1. Connect USB line to controller USB2 ${\scriptstyle \circ}$ USB3 ${\scriptstyle \circ}$
 - 2. Connect CN8 cable properly
 - 3. 5mm wire has to contact the ground
 - 4. Connect 0.75mm*2c(AC110V) to 4pin cable



(2) Connect AC servo motor ENCODER cable and power cable to DRIVER \circ





(3) Connect the electrode cable from machine base to the copper piece on box C of power generator. The connection method is shown as bellow:

> OConnect the black electrode cable on upper machine head to the copper piece "P" on Power generator. Connect White cable to the connect point "WHP_WIRE" on Power generator.

⁽²⁾The connection method of lower machine head is the same as upper machine head.







7.3 Add water to water system

Please use the pure water as working fluid. The working fluid need to be add into both clear water tank and sewage tank. To understand more about the water requirement, please refer to two. 2. specification - water tank capacity and next table

	Clear water tank	Sewage tank
Submerge Type	Full	Half
Flushing Type	Full	Half

% Please add the water into the water system until the water level meter is at the full position.



When the water level meter is dirty, please clean from the steel cover (one of the hole you could put your head to clean inside) to inner surface.


III. Operation Panel



1 Key-Board / Monitor

1.1 Screen display

The screen is placed on the top of the control box, 15" LCD panel. It is used to display all function buttons screen including coordinates, program, path compensation, spark parameters setting. Shown as Figure 2-1:



LCD touch screen



1.2 Screen Function Key













Information on the monitor

Messages and Status are shown on the screen





0.

3 Machine Operation Panel

Since the machine is controlled by touch screen, all of the function keys are shown on the monitor. Some functions can be operated by the remote, however most of them need to be worked on the touch screen.

Hot key area can be divided into 4 parts [Manual] · [Auto1] · [Auto2] · [KeyPad] . 4 of them have their specific function.

1.1 Manual

Go Pos.	Go Pos.	Position the coordinate. (REV. & ABS) provides operators to setup their own coordinates. The machine can move multiple directions, not just moving in one direction. Please refer to Chapter4 Section5.7.
Go Vert	Go Vert.	Press the button to make U, V axes back to perpendicular position. Light will be ON after re- positioning.※ Please do AUTO or Manual VERT first.
Z-LMT Go Lmt.	z. LMT Go Lmt.	Press the key, Z axis will automatically go downward to the setup point. %Point need to be setup to run this function.
S.Pt Retn (Go straight)	S.Pt Retn	Start Point Return. When some abnormal functions occurred, such as "REVERSE ALARM", press this button to return the wire back to start point base on the
Org.S.Pt	Org. S.Pt	coordinates on POSITION screen.
H.Pt Retn (Go straight)	H.Pt Retn	(HOLD POINT RETERN). When the wire breaks during cutting, press this button to return the table back to hold coordinate after threading. Or when cutting a taper hole and the debris is too big to be removed from workpiece, or when the workpiece is too thick to get it
Org.H.Pt		out from below because of the short distance between the head and the lower plane of the workpiece, PRESS THIS BUTTON to return to the hold coordinate after the debris is removed.



Go G92	G o G92	Press the button, machine will go straight to the last G92 point.					
Software Limit.		Press the key to cancel the software limit, press again to enable the software limit.					
Set/Cancel		Press the key to cancel the Z axis downward limit Press					
Z axis downward	Set/Cancel Z limit	the key again to resume the function. This function is to prevent the machine collides with the workpiece when the height of the Z axis is not set up properly.					
		Press this function and the light will be ON. It means					
Manual Threading	Manual	this function is activated. Press this button again to cancel this function. Don't press this button to cancel this function unless the wire threading function is completed					
		Prose the key, the machine will be at the neuse status					
Hold	Hold	Pressing HOLD on the remote control will result the same.					
	X	IncJog : Press \[Inc. Jog \], select \(\lambda *1\) \(\lambda \lambda \\ \lambda *10\) \(\lambda \\ \lambda *100\) one of them to assign the moving speed of machine. Press one of the direction to move the machine, however the machine will only move one unit at a time.					
		Cartinua : Press Continue and select #1 #10					
Manual Moo	de	(*100) < (*1000) one of these to assign the moving speed of machine. Press the direction key to move the machine. Release the key,					
Manual Mode		to stop the movement.					
O Inc. Jog O Continue	• Off	Close : Press $\ Close \ $, the machine head will stop					
		at this time, click other options to run your					
O MPG O FUN		process.					
		MPG : This function needs to work with the hand wheel.					
· ·		Please refer to Chapter4 section 5.5 to learn					
		more.					
		FUN: This function is under the Manual Imode, it needs					
		to be operated with the MODE key on the remote					
		control. Select the FUN key on the controller, when the					
		light is on press MODE. The function under Manual					
		Mode will switch in order. (Ex: Find Reference \rightarrow Edge					
		Find \rightarrow Find Arc.)					



1.2 Auto1

1.3 Auto2

Inverse interpreted	The machine cannot Trace to SI Block when there is M code. Click						
M code function	the function to remove the status.						
Display the	When the functions under [Manual] is completed or M code appears						
machining status	during the machining, a message will show on the screen. Check the						
	message, the alert message will not show again next time.						
Check the gap	This function will operate automatically during the machining. It						
voltage during	cannot be setup.						
machining							
Start discharging	When the function	is on, the machine will move only when the value					
short protection	of gap voltage is	above the discharging short protection voltage.					
Fly Cut Length	Here only display	the setup Fly Cut Length. To learn more about the					
(mm)	setup, please refer	to Chapter 4 section 10.5.2 $\[\]$ Fly Cut setting $\]$.					
Hold Time (s)	If there is a M21 edited in the NC Program, the hold time between						
	every block will be enabled. (Unit : s)						
Retreat distance	When running the	Retreat Distance during machining, the length of					
length (mm)	retreating can be setup over here. (Unit : mm) 【Auto1】→Z axis arise Distance value can be setup right						
Z axis arise							
distance (mm)	here(Unit : mm) •						
Org. Path to Start		This function has the same operational method as					
Point(Under	Org. Path	$ Auto 1 \rightarrow \ \Box Org.S.Pt $. Please refer to					
displacement	Start Pt.	$\lceil \text{Org.S.Pt} \rfloor$ operational method.					
mode)							
Org. Path to Brake		This function has the same operational method as					
Point(Under	Org. Path	[Auto 1] \rightarrow \Box Org.H.Pt $_{\Box}$. Please refer to					
displacement	Break Pt.	$^{\sqcap}$ Org.H.Pt $_{\perp}$ operational method.					
mode)							
Org. Path Retreat	Org. Path	Original path retreat to G92 position					
G92	Retreat G92						
Restart	Restort	$ [Auto2] \rightarrow \ \ Restart \] $					
(Re-cut)	Rostati						



Retreat Block		If there are some errors occur during					
(Machining)		machining (short circuit, unable to thread,					
		etc.), please trace to the last block by pressing					
	Retreat Block	"Retreat Block". The machine will retreat a					
		single block, every time you press the button.					
		The system will also record the latest point as a					
		hold point at this time					
		When Detrost Place process is done, process					
Feed Block		when <u>Retreat Block</u> process is done, press					
(Machining)		Freed Block to go forward. The machine will					
	Feed Block	go forward a single block, every time you press					
		the button. The system will also record the					
		latest point as a hold point at this time.					
Retreat Distance		If there are some errors occur during					
(Machining)		machining (short circuit, unable to thread,					
		etc.), trace original path away from the					
		workpiece is required. However the retreat					
	Retreat Distance	distance needs to be set. Each time vou press					
		the Retreat Distance button, the machine will					
		retreat a single unit. The system will also					
		record the latest point as a hold point					
		The cord the fatest point as a flotd point.					
Org. Path Retreat	Org. Path	when operating Org. Path Retreat G92					
G92	Retreat G92	runction, the machine will trace to the nearest					
(Machining)		G92and then record it as a hold point.					
Move to Break		When the machining is paused , the machine will					
point	Move to	move to the break point. The break point is					
	Brk. pt.	defined based on Feed Block Retreat					
		Distance Org. Path Retreat G92 					
Clear total cutting		Select the button, a conformational message					
time(Under	Clear Total	will appear. Click OK to set zero the working					
displacement or	Cutitng Time	time, click Cancel to cancel.					
machining mode)		, <u> </u>					
Start point(Under		This function has the same operational method					
displacement	Start Point	as $[Auto 2] \rightarrow [S \text{ Pt Retn}]$ Please refer to					
mode	Blattionit	S Pt Retn , operational method					
Break point(Under	D. h.D. i.i.	This function has the same operational method					
displacement	Break Point	as [Auto 2] \rightarrow 'H.Pt Retn]. Please refer to					
mode)		H.Pt Retn j operational method.					



3. Machine Operation Panel



1.4 KeyPad

The rest of the functions are as same as the ones on the KeyPad.



IV. Basic Operation



Tools

Following tools are used often while operating WEDM. Please place the tool near to the table or place where operator can reach the tool easily.

(1) Allen Wrench

Sized from M3 to M8. It is used to fasten screws in order to hold workpiece, or to adjust upper/lower machine head.



(2) Blade Feeler Gauge (0.1mm and 0.2mm) is used to measure the distance between workpiece and flush cup.



(3) Gage Meter for Power Contactor

This meter is used to measure the position of power contactor.





(4) Boride Engineering Abrasive

It is used to remove the bur on the edge of workpiece and the debris on the table.



(5) Lighter (Abandon the lighter when the fuel is empty)Lighter is used to heat the copper wire for straighten or burn off.Make sure there is enough fuel inside the lighter to process your work.



(6) 10mm Wrench or small adjustable wrench. It is used to check or change wire guide.



- (7) 30mmWrench or large adjustable wrench.
 - It is used to change filters.





Following measure tools are very useful during operation.

(1) Test indicator (Unit 0.002mm)

Test indicator is used to level workpiece.



(2) Micrometer

Micrometer is used to measure the dimension of workpiece.

(3) Tension meter

Tension meter is used to measure wire tension.



(4) Depth Micrometer

Depth Micrometer is used to measure the height of lower machine head during Taper Cutting





2. Operating Procedure

Power On	$_$ $_$ $_$ $_$ $]$ Turn Power Switch \rightarrow Press $\langle ON \rangle \rightarrow$ Release Emergency
	Button when the screen appears.
✓ Origin Return	Under [Manual] mode → Choose selected axis→ Select
	[Origin Return], the machine will start to process
Manual Movement	\rightarrow Press the button on control panel, moving alone axis.
Check power Contactor and Flush head ——-	\rightarrow Check upper and lower power contactors and Flush head.
\downarrow	
Install Cutting Wire and Workpiece ——-	Install Cutting wire on rollers, and install workpiece on
\downarrow	work table. Level worpiece.
Input Program	\rightarrow Input program · EX : From Flash drive or NET WORK \circ
\downarrow	
Parameters Setting	\rightarrow Input parameters base on the workpiece and working
	circumstance.
\downarrow	
Graph Simulation	$ \rightarrow$ Check the program and do graph simulate.
\downarrow	
Select Sparking Condition	\rightarrow Select the suitable Sparking Condition form computer.
\downarrow	
Adjust location of cutting wire	\rightarrow Adjust the wire position base on the installed workpiece.
\downarrow	
Preparation before EDMing	$ \rightarrow $ Check the gap between flush head and workpiece and the
	wire inside storage box.
Start machining	$____$ Switch to [Machining] Mode \cdot Press (START) to start
	machining •
End Machining	\rightarrow Remove workpiece when machining is complete.
\downarrow	
Check workpiece	\rightarrow Check the result.
\downarrow	
Machine cleaning	Clean all the components from the machine.
\downarrow	
Power Off	\rightarrow Power Off when the mission is done.



3

Connect Power

(1) Turn the Main Power switch to ON position.



(2) Push the green $\langle ON \rangle$ button on the right side of panel.



System Screen will be appeared after 30 seconds.

		<u> </u>					W US	BH	USB	MI	JSB	18	35:32
	白水完美·土於东非	Coordinate	Manual	Machir	ning	Message	Sy	stem	Manual	Autol	Auto2	KeyPad	Tool
	X 0.0000	Origin Return			Orig	gin Return Msg			-Cutting No	PARAM	F	unction G95 Block o	ntting
.00	Z 0.0000 U 0.0000 V 0.0000 W 0.0000	÷		Direction of Retu Pos. D Neg. E	un A	xes of Origin Retu X Axis Y Axis Z Axis	un U A U A U A U A	xis xis Axis	DM On Off AOn AOff	2 10 10 8 9		Corner Arc dec Run M Pos Fly Cut Don't w Dry Ru	decel. el.)1 rait gap
	Stat Brix G92 Set Coor. Disc. Status Total Paci			Sele All A	ect Axes				WF WF WR SV FS	9 6 3 15 10		Mac. lo Paral. o Start Point G92	cked omp. Break Point Restart
	5 -50 -25 0 25 50 ; Deion(K ohm) 50 L 65 H	Oriş	Stop gin Returi	n	(Sta Origin 1	art Returr	1	Feed F.D% C.Len Save	20 100 % 0.5 paramet		Wi Wa ED	re ter M
)-20-10 0 10 20 3 Idle	Origin Ed Return Fin PARAL. Co COMP. Ta	lge Slit ding Finding wr. MDI	Arc Center Original Path	Out Circle Center Pitch COMP.	Side Center Orth. COMP.	Edge Corner Polar Correct	Vert. Adjust	F H	eed old		Cyc Sta	ele Irt
	Gap Break Para Servo Limit Spec	al. Pitch Prot. c. Orth. Lmt.	Z Vert. ST. 1 Z E.Stop Brk F	t. Short F	Run Fa	il to connect H)13/4/22_08:24	ARD KEY U :12)	SB			Res	et	Feed Hold



(3) Release the 《EMGY STOP》 switch on the right side of panel to start operation.



! Note

《EMGY STOP》: Machine is under(NOT_READY) status if EMGY STOP is pulled. After the EMGY STOP button is pressed, machine can operate normally.



After machine is assembled, engineer has to do the laser alignment to the back slash of ball screw. The laser alignment is base on the machine's reference point. After the alignment, the compensation value is input in the controller. When machine is start, it is under none compensate status. Homing procedure has to be done to active compensation value.

Procedures are shown as below:
(1) Select [¬]Origin Return _→ under the 【Manual】.



(4) Press $\langle\!\langle X \rangle\!\rangle \cdot \langle\!\langle Y \rangle\!\rangle \cdot \langle\!\langle Z \rangle\!\rangle \cdot \langle\!\langle U \rangle\!\rangle \cdot \langle\!\langle V \rangle\!\rangle \cdot \langle\!\langle W \rangle\!\rangle$ to start Origin Return.



4. Homing





Movement

Use any of the three methods below to move $X \mathrel{\scriptstyle{\checkmark}} Y \mathrel{\scriptstyle{\vee}} Z \mathrel{\scriptstyle{\vee}} U \mathrel{\scriptstyle{\vee}} V$ axes.

 ${\rm \textcircled{O}}$ Use the hand controller to move to the designated location \circ

- ^② Press the "moving key button" under [Manual]
- ③Press "Go Pos." under [Manual] to move the axes to the designated position.

5.1 Continually Hand Move

(1) Press 《JOG》 Button





5. Movement

(3) Direction Key



5.2 Jog in certain

distance



EX: $\langle HIGH \times 100 \rangle$ button, jog distance is 0.1mm per press



5. Movement

(3) Direction Key



5.3 Move cutting

wire back to vertical position

When upper machine head is moving alone U or V axis, cutting wire is not in vertical position anymore. Press 《VERT》 button to move wire back to vertical position.

(1) To move the machine head alone U or V axis please operate under JOG or INC JOG mode.



 $\langle JOG \rangle$ or $\langle INC_JOG \rangle$ $\langle +U \rangle$ or $\langle -U \rangle$ or $\langle +V \rangle$ or $\langle -V \rangle$



(2) Press 《VERT》 button to move cutting wire back to vertical position.



《 VERT 》

J Hint

Please refer to section 5, Chapter 1 for Vertical Position setup.

5.4 Motorized Z axis movement

Press the direction key to move the machine head alone Z axis. Machine head is moving alone under JOG or INC- JOG mode.





5.5 (MPG) Coordinate GOTO

(1) Press $\langle\!\!\langle MPG \rangle\!\!\rangle$, light will appear when the function is on.



(2) MPG only allows one axis to move each time. Press $\langle\!\langle +X \rangle\!\rangle$, $\langle\!\langle +Y \rangle\!\rangle$, $\langle\!\langle +Z \rangle\!\rangle$, $\langle\!\langle +U \rangle\!\rangle$, $\langle\!\langle +V \rangle\!\rangle$ to move each axis, lights will appear when the functions start.



(3) When turning MPG axis, clockwise represent position direction and counter clockwise stands for negative direction. LCD Monitor can help you move the coordinate position accurately.





Check Power Feed Contactor and Flush Head

Check power feed contactor and flush head before machining.

6.1 Check Power feed Contactor

Power feed Contactor provides voltage on cutting wire.

Wear and tear on Power feed Contactor might damage the wire.

6.1.1 Check upper Power Feed Contactor

(1) Remove the fastening screw on upper machine head.



(2) Insert a small hexagon wrench and push out the Power feed Contactor. The L- Shaped small ruler can be used to remove the contactor too.



contactor.



Clean the contactor with detergent.

Make sure there is no dirt on the surface of contactor.



Mint 🖉

- 1. If the wear mark is too deep and effecting the machining efficiency, use the L-shape ruler and push the contactor in a little bit(2.5mm)
- 2. If there are lots of wear marks, please replace the power contactor.
- (4) Use the L-shape Ruler to install power contactor.





(5) Tighten the fastening screw



! Note



6.1.2 Check Lower Power Feed Contactor

(1) Remove the fastening screw on lower Machine head.



(2) Insert a small hexagon wrench and push out the Power feed Contactor. The L-Shaped small ruler can be used to remove the contactor too.



(3) Check Power feed Contactor

Is there any wear mark or dirt on the surface of power contactor?



Clean the contactor with detergent.

Make sure there is no dirt on the surface of contactor.

If there are lots of wear marks, please replace the power contactor

J Hint



(4) Use the L-shape Ruler to install power contactor.





6.2 Check Flush Nozzle

The broken or scratched Flush Cup will case the working fluid flushes not consistence and reduce the cutting speed.

6.2.1 Check Lower flush Cup

(1) Turn the flush nozzle clockwise and open it.





! Note Turn the flush head by hand

Do not use wrench or other tool to turn Flush Cup, otherwise it Might damaged the upper machine head.

6.2.2 Check Upper Flush Cup

(1) Remove Upper Flush Cup by turning



(2) Check upper Flush Cup. If there is just a small scratch, grind it with millstone/abrasive.



Replace a new flush cup if there is scratch or crack after the grinding.

X Suitable upper Flush Cup

Standard upper Flush Cup : WA42

Taper upper Flush Cup: WA87

(3) Use Teflon to seal the base of guide (screw parts)



J Hint

! Note

Don't seal the upper screw parts of guide.

If the tape is not used to seal the guide, it will cause the flush cut vibrate and the water pressure is not stable.



(4) Install upper Flush Cup by turning.



! Note

Install the flush head by head. Other tools, such as wrench, might damage the parts.



Cutting Wire and Workpiece Installation

7.1 Wire Selection

Cutting wire recommended.

Table 7.1 Cutting wife recomme							
Application	Furkawa Electric Co., Ltd	Hitachi Cable., Ltd					
Standard	FKH (Hard Wire)	HBZ-B (Hard Wire)					
	FKA (Soft Wire)	ABZ-B (Soft Wire)					
Large taper cutting		ABZ-T (Ultra Soft Wire)					
AWF	FKH (Hard Wire)	HBZ–U (Hard Wire)					
Prevent Stock	—	HTF (Hard Wire)					
		ATF (Soft Wire)					

Table 7.1 Cutting Wire recommended

Select suitable cutting wire, especially for taper cutting. * Taper = 3° :

- Furkawa's FKH Hitachi's HBZ-B
- * Taper > 3° and < 10° :

Furkawa's FKA · Hitachi's ABZ-B

* Taper > 10° :

Hitachi's HTF (Taper $< 3^{\circ}$) , ATF (Taper $> 10^{\circ}$) \circ

7.2 NOTE!

Cutting Wire is very brittle. Please handle with care, otherwise it might damage or break the wire and cause the machining unstable.

* If the wire put in the box too long, it will make the wire curly.

* Take out the wire from the box with hand, do not drop it to the floor.

* Don't open the PVC packing before using the wire, otherwise the wire will be rusted.



* Hold the tip of wire and pull it. Cutting Wire cannot be pulled out if it is curly.



* Pull the wire slowly to prevent it twisted.



* Pull 10cm of wire out and break the wire with lighter fire. • It will sharpen the tip of the wire and make the wire threading easier.



* The end of wire is tapped on the core. If the wire keep feeding, upper machine head be stuck by the tap.





7.3 Install cutting Wire

WB · WI Automatically Wire Threading System :

(1) Remove the Taper cap from wire support arm.



(2) Put the wire on Core support armThe wire spool's open side is on the left.(Wire is rotate by clockwise direction)



(3) Install the wire as follow





(4) Pull the wire $150 \sim 200 \text{ mm}$ and break with lighter fire.



(5) Push the handle "C" up (counter clockwise) and turn the tension roller clockwise and make the wire through point B and lead the wire into guide tube about 10 cm. Then push down the control handle C clockwise.



(6) Press AUTO wire threading till action complete.




Appendix 1: WB v WI Auto Wire Threading diagram



Feed the wire by the following steps: from (A) to (G)













- * Install the wire follow by the sequence of A to I
- * After (I) section, press Manual Wire Threading Button to lead the wire via flushing. Press the button to stop it when wire is pulled.
- * From (D) to (H), roll the wire from outside to inside to prevent wire overlap.



7.4 400*300mm Work Table



Figure 7.4 400*300mm work table and leveling Jig

As shown above, the maximum traveling range of working table is 400×300mm. There are 2 rows of screw holes- outside and inside rows. Operation can put the Holding Jig or Leveling Jig base on the shape of workpiece.

Changing the Shape of the workpiece by adjusting Leveling Jig.

Fixed the Leveling Jig to the designated position by using inside/outside and ellipse screw holes

(1) Fasten the Level Jig by using outside screw holes.



(2) Fasten the Level Jig by using inside screw holes.





7.5 600*450mmWork Table



Figure 7.5 600*450mm work table and leveling Jig

7.6 Caution

Install the workpiece by the following methods, the workpiece is loose during the machining process, and will reduce the accuracy of machining.



Fasten the Workpiece on both sides by using 2 or more holding jigs to hold Workpiece on table.

Please utilize the Level Jig properly.





7.7 Jig holder





J Hint

Work table and leveling jigs are made of stainless steel. If the corner is too sharp, it might scratch the Workpiece. Therefore, while install the Workpiece, put it on plastic pad



7.8 Procedures of installation

(1) Hold the workpiece slightly



(2) Put the test indicator on the Z Column and measure the Workpiece. There is a M8 screw hole on the Z axis column. Shown as below:



(3) Put the tip of test indicator on the surface of Workpiece.

Move the upper head on X axis and Y axis to level the Workpiece.

Change Jig position or insert the shim to level Workpiece.





《JOG》 《HIGHX100》 《-X》 or 《+X》 《-Y》 or 《+Y》

If the Workpiece is tilted, it should be moved alone axis direction to change the distance between flush head and Workpiece. The distance changed might cause the cutting wire feeds inconsistently or unexpected touch of flush head and Workpiece.

(4) Using one side as the base surface for indicating. Put the tip of test indicator on this side and level the Workpiece.

If the workpiece is tilted, use the screw drive to tap the Workpiece for leveling.





《JOG》	$\langle HIGH \times 100 \rangle$
$\langle\!\!\langle -X \rangle\!\!\rangle$	or $\langle\!\!\langle +X \rangle\!\!\rangle$
$\langle\!\!\langle -\mathbf{Y} \rangle\!\!\rangle$	or $\langle\!\!\langle +Y \rangle\!\!\rangle$

(5) Tighten the fastening screw



! Note

When workpiece is installed on leveling jig, do not over tight the jig screw, otherwise it will tilt the workpiece.



NC Program Input

NC Program Input

There are 5 methods to input NC program:

- (1) Call the saved program.
- (2) Input NC program by key in and edit.
- (3) Input NC program via I/O device.
 - (Input through Flash drive)
- (4) Input NC program via I/O device.(Input through NET from PC)
- (5) Input NC program via I/O device.
 - (Input through RS-232 from PC)

8.1 Call the saved program

(1) Select [Machining] \rightarrow (Edit Prog.) mode.

			W USB H	USB	M	USB	14	48:25
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V 0.0000				S	T	<u> </u>	V V	
W 0.0000				Y	Z	<u>-</u>	<u>: U</u>	<u> </u>
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Stt Brk G92				1	@ 2	# 3	\$ % 4 5	6
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-Gap Volt.(V) 0.00					Xrl			
5 -50 -25 0 25 50 ;				Caps	Lock		Enter	
Deion(K ohm)						<u> </u>		
	File name: 0402-1.nc		INS	7	8	9	+ Ho	ne PgUp
ափախախուղու	Open Save/ Create R File Delete New File R	RS-232 Search Undo text modify	Redo Retn Main modify Prog.	4	5	6	- Er	d PgDn
D -20 -10 0 10 20 3	GM Code			1	2	3	*	
Idle	Edit Prog	ting Cut Param, Smart F	unc. Cut Record		0		1	Enter
Gan Break Par	Pitch Prot 7 Vert ST Pt	Work Rup -						E.d.
Cap Dieak Fai	a Orth I mt 7 E Stan Brk Dt	Short E Hold (2013/4/22 08:24	g :20)			Re	set	Hold



(2) Open/delete file

- 1. Work : Choose the assign drive, and then select the pre- processing program by moving the mouse or $\langle\!\langle \leftrightarrow \rangle\!\rangle$, $\langle\!\langle \rightarrow \rangle\!\rangle$, $\langle\!\langle \uparrow \rangle\!\rangle$, $\langle\!\langle \downarrow \rangle\!\rangle$ keys.
- 2. USB ∶Insert the flash drive and press refresh to show the display USB drive. Next choose the assign drive, and then select the pre- processing program by moving the mouse or ((←)), ((→)), ((↑)), ((↓)) keys. To remove the flash drive, press 「Remove Flash Drive」. Remove the flash drive after a message is shown otherwise the data may vanish as the result.
- 3. Delete Content/File : Press \[Delete Content \] or \[Delete File \], a confirm message will appear. Click \[OK] to delete, click \[Cancel to cancel the move. \]





8. NC Program Input

(3) Click the assign file to open it.

07 5

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Idla							_				-1
Iule	Edit Prog. Sim	ulation	Cutting	Cut Pa	am. Smart F	unc. Cut Rec	ord		<u> </u>		

Select the assign NC



8. NC Program Input

*Open the file by using graphic preview.

追求完美・止於至善	Coordinate	Manual	Machining	Message	System	Manua	l Auto1	Auto2	2 Ke	yPad	Τo
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Set Coor.			USB	19941.NC					R	5	6
. Status	(max = 1.540 Ymax = 2.333 Grin = -1.555 Ymin = -0.622		00100		X						
		00002	N100 G21 G90 N102 G92 XO.	YO. I100. JO.						s	hift
Volt.(V)		00004	N106 S101 D1 N108 G41 G1 X	.1704 ¥1.5453					F	·	
արութողը		00006	5 N110 G3 X-2.3	086 Y1.1064 I2	.5021 J-21.354				En	iter	
D -25 (1 25		00000	8 N114 G1 X-2.6	676 ¥1.956	.0340 0.1439						
on(K ohm)		00009	9 N116 G2 X-2.5 0 N118 X1.2596	938 ¥2.0767 I. ¥2.657 I5.2663	0972 J.0235 J-21.8853						
L 65		00011	L N120 X2.248 Y	2.5407 I.1745	J-2.7745				+	Home	Pg
		00012	8 N122 G1 X2.87	92 ¥2.4086 N7 ¥2.216 TO	586 J1912			-	\Box	End	Pa
0 -10 (0 10	Remov	/e Flash	Delete				Clas		Н		
	Reliesii Dr	ives D	Nicectory		Open rile		CIUS	e	*	Fr	iter
Idle	Edit Prog	ulation C	utting Cut P	aram Smart F	unc Cut Reco	rd	0		7		
					inc. [carneed	<u> </u>			_		
ap Break Para	I. Pitch Prot. Z	Vert. ST. Pt	Work Kun	Fail to connect M((2013/4/22, 08:24:)TION USB 12)			Res	set	F	eec
TVO Limit Spe	c. Orth. L.mt.Z.	3.Stop Bik Pt.	Short F.Hold						_		.010
				A simulate	d graph will	appear	when	mov	ving	the	
					- 0r						~
										time	fe
				mouse to the	ne program	name. T	his sa	ves t	he	unne	
				mouse to the operator	ne program	name. T he prog	'his sa [.] ram.	ves t	he	unne	
			5	mouse to the the operator	ne program	name. T he prog	'his sav ram.	ves t	he	unne	
.0			5	mouse to the operator	ne program	name. T he prog	'his sa ram.	ves t	he	unne	
Jote	2	2	5	mouse to the operator	ne program	name. T he prog	'his sav ram.	ves t	he		٦
Note	Be	efore usin	g the grap	mouse to the operator	ne program for to search to we function	name. T he prog	his sav ram.	wes t	lati	on	
Jote	Be	efore usin	g the grap	mouse to the operator	w function	name. T he prog	his sav ram.	mul	lati	on	
Jote	Be	efore usin	g the grap	mouse to the operator the operator hic previet	ne program i or to search t w functior ere is no g	name. T he prog n, grap raphic	his sa ram. hic si to pr	wes t mul evie	ati	on	



8.2 Key in and Edit program

8.2.1 Add New Program

- (1) Select [EDIT] Mode.
- (2) Press 「Create a new file」, and then key in the file name.(Example is shown below : ABCD)
- (3) File Extension
 - NC : KENT USA-EDM machine processing file extension. • Subprogram : File extension for

machining subprogram.



J Hint

- The NC program can be read as long as it matches to the file extension above, but the program may not able to be performed. This is because the G&M Code was being created by different company.
- * When edit the program, G92 cannot be edited. Main program needs to be edited first in order to simulate the graph.



(4) Press INPUT and enter Edit Screen.



- (5) Contents of new program.
- (6) When the program edit is complete, press
 - Save/Delete Save or the program won't be saved

in	the	Worl	c file.
			L IIIV.

Controller	Work File Name 🗠	Modify Date
	120224.nc	2012/02/24 08:54:26
Work	120229.nc	2013/03/14 16:46:08
USB	0980402.NC	2009/04/03 10:00:02
	120321.nc	2012/03/20 14:11:06
	O9960	2003/05/05 10:19:02
	120416.nc	2012/04/16 15:52:00
	09960.nc	2013/01/23 08:23:22
	120426.nc	2012/04/26 10:36:50
	O9961	2013/01/21 09:35:14
	09998.nc	2011/09/19 13:12:26
	09999.nc	2011/09/19 13:12:38
	120426-1.nc	2012/04/26 11:54:28
	123.NC	2012/05/04 11:19:06
	120702.nc	2012/07/03 10:25:56 💌
	File Name:	USB
Free space:3,140,312 KB	120224	
	File Type	
Refresh Remove Flash Drive	es	Subprogram
Dele	te	



8.2.2 Input via RS-232

- (1) Connect RS-232 to PC.
 - ※ RS232 cable should be made by customer. Please refer to Appendix (I).



- (2) Select [EDIT] to enter the code.
- (3) Press 「Input via RS-232」 to setup Communication
 Setting. The content needs to be same with the CAM setting. Next press Connection Test to test the connection. A message will appear when connect successfully. If not, check the setup data and do the re-test.





8. NC Program Input

Disk path		Send buffer	
- Controller		File Name:	Communication
Work		00001	Connection test
Free space:	Remove Flash Drives		Exit
Work File Name	Modify Date	Receive buffer	
120224.nc	2012/02/24 08:54:26		
120229.nc	2013/03/14 16:46:08		Clear data
0980402.NC	2009/04/03 10:00:02		Cicar data
120321.nc	2012/03/20 14:11:06		Ptart to
O9960	2003/05/05 10:19:02		receive
120416.nc	2012/04/16 15:52:00		
09960.nc	2013/01/23 08:23:22		STOP Stop receiving
120426.nc	2012/04/26 10:36:50		
O9961	2013/01/21 09:35:14		
09998.nc	2011/09/19 13:12:26 🗸		
Open File	Refresh		Save File
	Message		JSEDM

- (4) Press Start Receive to send the data from CAM, at this point in the buffer zone will begin to receive the program until it ends.
- (5) Press Save file and save the receive program to the Work file
- (6) To receive new program, press Clear Document to delete the recent document.

8.2.3 String Search Function

String Search Function is to "Find", "Replace" or "Block Copy", "Move" in program. In Edit Screen, press String Search to enter "String Search".

- (1) Search : 1. Under 「String Search」, input the string and do the search. Press Next if everything is corrected.
 2. Cursor is moved to the search result.
 - 3.To find a same string, press Search next.



8. NC Program Input





J Hint



8.2.4 Undo Edit Function

When input the wrong G &M code or coordinate, press Undo Edit and return to the initial set.

00001	G95		00001	G95
00002	G92X0.YO	Corrected	00002	G92X0.YO
00003	G41G01X2.0D20	\rightarrow	00003	G41G01X2.0D10
00004	Y10.		00004	Y10.
00005	X6.O		00005	X6.0
00006	Y-20.0		00006	Y-20.0
00007	X-6.0		00007	X-5.0
00008	MOO	Press Undo	00008	моо
00009	¥10.	Edit to resume	00009	¥10.
00010	G40G01X-2.0	to the original.	00010	G40G01X32.0
00011	MO2		00011	M02

8.2.5 Repeat Edit Function

Press Repeat Edit to return to the last program.



8.2.6 Return to Main Program Function

Open the subprogram and press this function, the system will return to the main program rapidly.

(1) Open the subprogram processing program, after operate the processing simulation click scroll key. At this point, the file name will appear on the main program and the subprogram.



Scroll Key

- (2) Select name of subprogram "TESTSUB1", "TESTSUB1"NC program will display on the programming area.
- (3) Click Return to main program or click the file name of the main program to return to main program.

8.2.7 Programming area edit function

Block copy, cut, paste, delete function :

① Select the edit block and then right click the mouse.Show as follow :





8.2 Reading NC programs from I/O devices

8.3.1 Input the program for flash drive

- (1) Insert the flash drive.
- (2) Setup controller :
 - 1. Press 《Edit》 under 【Machining】
 - 2. Picture of flash drive will appear after pressing Refresh
 - 3. Select the flash drive or the content below to show the files from the flash drive.
 - 4. Press Open File to read the program on the controller.

To save the program in the controller, press save/delete under $\langle Edit \rangle$.

Controller Work	Work File Name 4 De02.nc V 0402-1.nc V 0403-1.nc	Modify-Date 2012/02/02 1859:10 2011/06/30 10:31:29 2008/08/19 15:52:26
JSWI_PC板測 埃及 得鈺螢幕驅動軟 mycamdiek7.01	 ✓ 1.nc ✓ 10.nc ✓ 111.nc ✓ 111.nc ✓ 112 ✓ 120125.nc 	2011/09/29 07:07:04 2012/03/01 14:57:42 2012/02/14 08:42:40 2012/02/14 08:43:34 2013/01/25 10:35:54
Implementation 00001 Implementation 00005	Elle Name: 111.nc 392 X0.Y0. 391 301 Y1. 198 P112 L10 102	
Refresh Remove Flash Dires Dir	elete Delete File Open File	e Close



8.3.2 Import/Export via Networking

	(1) Connect the machine to PC via networking.
	(2) Controller setting :
	While using Net drive setting, the PC networking has to be set too. Please refer to FAppendix 2 PC setup.
/ Hint	%Network cable has to be done by customer. The network cable can be found in PC store too. (Spec. : RJ-45) °
/ Hint	*NC program can be created via the following methods :
	① Input and Edit program via KENT USA Wire EDM
	Operating System.
	② Use CAD ∕ CAM program such as TCAD/CAM,
	MASTER CAM, ESPRITE CAM, etc. Generate
	drawing to NC program.
	※ KENT USA EDM provides Optional Accessories:
🖋 Hint	MY CAM •





(2) When the network setting is reference from **Appendix 2**, two computer user name will appear under the work group. Hence, copy the processing program to the "Work" file from the controller. Please refer to Chapter 8, section 8.1.

Appendix I. : RS-232 Cable

The wiring of RS - 232C cable is different from one to another, it

is

base on the COM1 or COM2 connector on each PC. (There are 25PIN and 9PIN connectors) .





9 Parameter Setting

Actual parameter setting can be setup in 《Simulation》 under [Machining].

Press Parameter Setting after call NC Program (Figure is shown below) Is divided into three simulation options





9.1 Parameter Setting

	(1)	Scale Factor (Range : 1000)						
		Enlarge or scale down the actual workpiece machining base on						
		the same NC program.						
	(2)	Rotating Angle (Range : $-360 \sim 360$)						
		Rotate the angle for actual machining in program.						
	(3)	Hold time (Input Range : 0~1000)						
		Add M21 to the single block of NC program to hold (Unit: s).						
		To cancel the hold, ass M22 in the program.						
J Hint	ıt	* M21-Single Block Hold ON						
		* M22-Single Block Hold OFF						
	(4)	Workpiece thickness (Input Range : -1000~1000 mm)						
		Input the thickness value of the workpiece. During machining,						
		the workpiece will result differently base on the machining						
		mode and program plane. Taper machining has the most						
		obvious result.						
	(5)	Program plane (Input Range : 0 ~1000 mm)						
		Base on XY plane which the program desires and the thickness						
r		of workpiece						
	Assigned surface	Assigned surface Cut by cutting knife						
		Tace up —Program-set surface						
	60	60 Program-set surface						
		Bed platform surface						
	=Bed platfor	m surface Surface Surface						
	Thickness =	Thickness $=$ -60.000 Thickness $=$ -60.000						





(6) Corner Radius G48-Rxy

G48-Ruv (Range : -1000~1000) This setting should be worked with G code in NC program. (G48

M Hint

* Operate[¬]Background simulation _and then run[¬]Machining simulation _in order to let corner radius valid.

(7) Notch path correction Mode (Option : 0-intersection \ 1-<90°
(Tangent line) \ 2-<90° (Around Circle) \ 3-Tangent line \ 4-Around Circle)

Main function : When the cutting angle of exterior angle and acute angle are small, a longer cutting path will be created during the correction. However, these cutting path will affect the cutting efficiency.





Unset the compensation value, notch path correction mode =0–intersection

Set Compensation value as 0.2mm \cdot Notch path correction Mode =1-<90° (Tangent line)



Set compensation value as 0.2mm \cdot Notch path correction Mode =2–<90° (Around Circle)



9. Parameter Setting



Set compensation value as 0.2mm . Notch path correction Mode

=3–Tangent line



Set compensation value as 0.2mm
Notch path correction Mode =4– Around Circle.



The machine will operate around circle process on every exterior angle of the cutting path PS : This function is not appropriated for Taper-B



9. Parameter Setting

(8) Cutting Mode (range : 0-Vertical \ 1-Taper \ 2-Taper B)Setup the cutting mode based on the program simulation setting.

Cutting Mode=0 Vertical machining- (No Taper)

Cutting Mode=1-Taper (Angle assigned)

Cutting Mode=2–Taper B (Different Shapes on Top and Bottom area)





(9) Display Mode $(0-\text{cursor } 1 \cdot 1-\text{cursor } 2)$

Main function : When using Taper > Taper B NC program, the limit height of upper/lower guide can be checked based on the simulation screen.





1-Cursor 2 : Display the path of workpiece and upper > lower guide





Cutting Mode

Upper guide path

Ymax = 19.500 Ymin = 0.000 Zmax = 30.810 Zmin = 0.000



- (10) X axis mirror (Input format : OFF \cdot ON) Mirror the setting alone X and u axis.
- (11) Y axis mirror (Input format : OFF ON) Mirror rhe setting alone Y and V axis.
- (12) X axis and Y axis exchange (Input Format : OFF
 ON)
 Switch the X/U axis movement to Y/V axis movement.
 Switch the Y/V axis movement to X/U axis movement.

Original	X mirror	Y mirror	X&Y mirror
Axis Exchange	Axis Exchange and X mirror	Axis Exchange and Y mirror	Axis Exchange X&Y mirror
	L,O		

(13) Restore Working Setting

During the machining, if the background simulation has been utilized and the parameter for [Compensation value], [Machining Parameter] and [Simulation Function] have been changed; click Restore Working Setting to resume to the original setting.

(14) Restore Background Setting

When operating background simulation, to resume the background simulation parameter, select Restore Working Setting.



(15) Edit default compensation value : The condition of the workpiece (such as: material, thickness, etc) will affect the compensation value. Hence, user should save the value in laptop or PC. For the user's convenience, a region in the system is designed to save these values.

Using Methods :

- 1. Click "Edit Default Compensation Value", a password required window will appear at this time.
- 2. A setup window will appear when entered the password.
- 3. "Simulation Compensation Table" is used for the machining simulation. Move the cursor to the assign value and press Save, the compensation value will also change.
 - "Default Compensation Table" is the value for recording. Move the cursor to the assign value and press Save, the compensation value will also change.
- 5. Under the non-save situation if the file has been changed accidently, press Re-load to resume to the previous value.
- 6. Select the assign value and press Copy single line

to simulation to copy the default compensation value to the Simulation Compensation Table.

- 7. To copy all of the default compensation value to the Simulation Compensation Table, press Copyall to the simulation.
- To copy all of the Simulation Compensation Table to the default compensation value, press Copy all to the simulation.
- 9. To edit the value in the table, please press <u>Save</u> right after you done with your process. Otherwise, Everything will resume to the last setting.



Edit default offset											
	Wire di	ameter offset tak	le	N	/ork offset tab	le	- C £1-				
	Simulate (Comp. table		-Default Co	mp. table		Save me				
	D value	Offset	^	D value	Offset	^					
	000	0.225		000	0	=	Re-load				
	001	0.185		001	0.23						
	002	0.144		002	0.147						
	003	0.138		003	0.14		Copy S.block				
	004	0.147		004	0.138		To simulation				
	005	0		005	0.15						
	006	0.2		006	0.2		Conv all				
	007	0.0		007	0.0		to simulation				
	008	0.0		008	0.0						
	009	0.0		009	0.0						
	010	0.0		010	0.0		Copy all				
	011	0.0		011	0.0		from simulation				
	012	0.0		012	0.0						
	013	0.0		013	0.0						
	014	0.0		014	0.0		***********				
	015	0.0		015	0.0						
	016	0.0		016	0.0		************				
	017	0.0		017	0.0		*************				
	018	0.0	*	018	0.0	~	Clara				
							5201.7				

(16) Height of upper guide (Parameter will be inputted automatically after the vertical alignment.)

The distance between upper guide and work table. The parameter will change base on the movement of Z axis.

(17) Height of lower guide (Parameter will be inputted automatically after the vertical alignment.)

The distance between lower guide and work table.

* To change the height of upper/lower guide, please input the password. The password is included in the CD rom.



9.2 Interpretation Setting

- (1) Input Range:
 - Auto-Correct : This function is used to correct the tolerance which is caused by the connection between two segments. The tolerance will occur when the CAM Resolution is too low or the segments are overlap.
 - Uncorrected : The correction will not be operated when there is an interfere or over cut between the segments. However, these error messages will still show on the screen. Machining can still be operated even though the error message is not solved.
 - ③ Alarm: Error message will appear when there is an interfere or over cut between the segments. Error messages need to be solved to re-operate machining.
 - (1) Single Block Drawing : This function has to cooperate with the block draw time. Select "Single Block Drawing" and then click Step Drawing , the program will stop at every single block based on the block drawing time and then move to the next block.
 - (2) Block draw time : By adding M21 command in NC program, single block can be hold in a period of time. (Unit : Second). Use M22 command in program to cancel this function or select "Single Block Drawing"

! Notice

* If the error is too big when transforming CAM to G&M code , please contact with CAM manufacture to adjust the resolution.
* Adjust the program if excessive interference the interpretation.



9.3 Compensation options

Main Function : Use the function below to cancel the machining controlling function such as arc, corner and wire consumption. This function avoids the workpiece from over machining. When the function is ON, the arc and corner compensative will start based on the D value.

🖋 Hint

- * Internal and External Arc

 Corner Compensation Unit =
 Metric/English

 * Wire Consumption Compensation Unit=Degree
- (1) Launch arc Comp. function : When the program interpreted to the arc ring and Launch arc Comp. function] is on, the program will start to compensate the arc radius automatically.

D value	Offset	^	Compensati	on options				
000	0.225		D value	Cylindrical	Inner circle	Corner offset	Wire	1
001	0.185		000	0.02	0.02	0.04	0.003	
002	0.144		001	0	0	0	0	_
003	0.138		002	0	0	0	0	
004	0.147		003	-	0	0	0	ъ
006	0.2		004	0	0	0.0	0.0	
007	0.0		005	0	0.0	0.0	0.0	
008	0.0		006	0.0	0.0	0.0	0.0	
009	0.0		007	0.0	0.0	0.0	0.0	
010	0.0		008	0.0	0.0	0.0	0.0	-1
011	0.0		000	0.0	0.0	0.0	0.0	-1
012	0.0		009	0.0	0.0	0.0	0.0	-1
013	0.0		010	0.0	0.0	0.0	0.0	-1
014	0.0		011	0.0	0.0	0.0	0.0	_
015	0.0		012	0.0	0.0	0.0	0.0	
018 017 018 019	0.0 0.0 0.0 0.0	~	☑ Launch	arc Comp. fu	Compensation D Edit Correction			
<<	3/3 >		⊡ Launch	wire consump				

Ex 1 : Punch Cut Compensation Value=0.02

Unselect "Launch arc Comp. function"

Select "Launch arc Comp. function"



9. Parameter Setting



% The parameter is the absolute value.

- (2) Launch corner Comp. function : When the program interpreted to corner, and
 Launch corner Comp. function is ON, the program will start compensate automatically.
- Ex 1 : Punch Cut Comp. Value=0.04

Unselect "Launch corner Comp.

Select "Launch corner Comp. function"


9. Parameter Setting

Xmax = 6.763 Xmin = -2.837	Ymax = -3.307 Ymin = -12.907	Zmax = 60.000 Zmin = 0.000	-	Xmax = 0.852 Xmin = -0.660	Ymax = -9.105 Ymin = -10.617	Zmax = 60.000 Zmin = 0.000
					外角補償(0.04mm
, ,			7	<u>S</u>	5	

J Hint

- Need to set G41
 G42 and D value in the machining program to operate this function.
- Suggest Setting : First cut= 0.04 \ Second cut= 0.02 \ Third Cut close
- When this function is ON , comp. value need to be added when the range is between 0-180°.
- % This parameter is an absolute value.
- (3) Launch wire consumption Comp. : If the cutting mode is set as taper or polygon and Launch wire consumption Comp. is ON. The machining will start to compensate the angle based on the height of upper and lower diamond guide

Ex1: Punch Cut Comp. Value=0.003 degree

- 1. Unselected "Launch wire consumption Comp."
- 2. Cutting Mode = Vertical Mode
- 3. Compensation Value = 0 degree





- The parameter can input both positive and neo
- % The parameter can input both positive and negative value.



- (4) Compensational adjustment value : This function is used to compensate the error when cutting the workpiece. The compensation value needs to be adjusted depends on the condition of every machine.
 - EX : Main machine cutting workpiece dimension=10.00mm • sub machine cutting dimension=9.97mm. However, there is a -0.03 error when cutting the same workpiece. Input 0.03 as compensation adjustment value

M Hint

- * Please input the password to run the function. The password is included in the CD Rom.
- * If workpiece thickness, material....etc changed too much, we recommend not to use this function.



9.4Error Message

If the error message "NC Program Interference" appears after the graphic simulation, the system will display the following figure below. Please exclude the message and re-simulate.

Column No.	Messages	
58	(5)Interference< Arc intersect interfer	ence >,Program[[0]]

- (1) Message List : Search and correct the wrong NC program based on the list.
- Message : Let the operator notices the error and correct it. In the list,

 Program[0] _represents main program error. If there is a first level subprogram, [1] will be present. [2] is the second level subprogram and so on.



9.5 Cutting & Background simulation

Cutting Simulation : After the parameter is setup, it is necessary to check if there is interference or not and then input the condition to the NC Program. The system will enter the 《Cutting Program》 automatically.

Background Simulation : During machining, to operate other functions please select the function to run the simulation.

JISEDM	W USB	HUS	в	M	Use	0	3:13:2
□求完美·止於王莽	Coordinate Manual Machining Message System	M	anual	Autol	Auto	2 KeyF	ad Too
X 0.0000	Xmax = 25.730 Ymax = 8.865 Zmax = 60.000 , Xmin = -0.230 Ymin = -12.095 Zmin = 0.000 X 4 0000		A	в	с	D	E F
Y 0.0000	Y 4.0000		G	н	тÌ	J	K L
Z 0.0000	U 0.0000		м	N		P	
U 0.0000	V 0.0000						
V 0.0000	241.822		<u> </u>	\rightarrow	\rightarrow		
W 0.0000	Cutting Taper(Degree)		Y	2	-		ĻĹ
• Rel 🔿 Abs 🔿 Mac	Wire compensation(mm,			\mathbf{i}	Ľ	<u>. </u>	
J Strt () Brit () G92	G501 (Inside) G501 (Outs	ide 🚶	ίι į	2	3	\$ 4	
Set Coor.			8. 7	8	(9)	
xal Anno		M	Bac	*	Та	b	Shift
Volt.(V)	Color of XY Plane Color of UV Plane		Ctr	1			
10000000000000000000000000000000000000		,	Cans I	.ock		Ente	r
)eion(K ohm)	(親巴設定						
i0 <u>L</u> 65 <u>H</u>	Step 7:Draw simulated graph(Completed)		7	8	9	+ H	ome Pgl
պապատարողու	Backgrnd Step CONT Overlook SIMU Draw Draw Graph Full Graph SIMU Error PARAM Messages Setting		4	5	6	. E	Ind PgD
-20 -10 0 10 20			1	2	3	*	
Idle			0			$\overline{}$	Enter
	Edit Prog. Simulation Cutting Cut Param. Smart Func. Cut Recor						
Gap Break Par	I. Pitch Prot. Z Vert. ST. Pt Work Run Fail to connect HARD KEY USB (2013/4/24 08:19:26)				Re	eset	Feed
JSEDM	Coordinate Manual Machining Message System	USB Manua	1 Anto		B	09: () GevPad	9:29 Tool
X 0.0000	Simulation	Telanoo))	7 7	γ γ)	
Y 0.0000	Amax - 30,230 Amax - 30,695 Amax - 30,000 X 4,0000 H Xmin - 0,230 Ymin - 17,095 Zmin = 0,000 X 4,0000		B	↓ c		E	F
Z 0.0000		G	<u>н</u>	I	Ļ.	K	L
0.0000	V 0.0000	М	N) o	P		R
0.0000	The Length of Path(mm)	S	Т	U	V	W	X
0.0000	Cutting Taper(Degree)	Y	Z	=	+ =		?
Rel 🔿 Abs 🔿 Mac	0 Wite commensation(mm)	ł	}		и ,	(<u>}</u>
Stat OBak OG92			2	#	\$	% 5	â
Set Coor.	G301(hasde) G301(Outsde) 0 0	8		Ì	$\frac{1}{2}$	Ť	Ĩ
sc. Status tal	G503 G505	É	J <u>°</u> Jack	, •	Tah		
P.scl Gap Volt.(V)	Color of XY Plane		011	╆──]	
		-			E	Enter	
	颜色設定	Cap	is Lock		_	_	
50 -25 () 25 50 ; ion(Kohm)					Y		
50 -25 () 25 50 ; ;ion(K ohm)) L 65 H	Step 7:Draw simulated graph(Completed)	7	8	9	+	Home	PgUp
-25 () 25 50 ; Kohm) L 65 H	Step 7:Draw simulated graph(Completed) Backgrind Step CONT Overlook SiMU Error PARAM SIMU Draw Draw Graph Cutting Messages Setting	7	8	9	+	Home End	PgUp PgDn
-25 0 25 50 ; n(K ohm) L 65 H -10 0 10 20 ;	Step 7:Draw simulated graph(Completed) Backgrad Step CONT Overlook Full Graph SIMU Error PARAM SIMU Draw Draw Graph Full Graph Cutting Setting GM Code Gatcole Gate Gate	7	8 5 2	9 6 3	+	End	PgUp PgDn
-50 -25 0 25 50 ; Deion(K ohm) 10 L 65 H -20 -10 0 10 20 ; Idle	Step 7:Draw simulated graph(Completed) Backgrad Step CONT Overlook Full Graph SIMU Error PARAM Draw Graph Full Graph Cutting Messages Setting CMCcde	7 4 1	8 5 2	9 6 3	+	Home End En	PgUp PgDn ter
-50 -25 0 25 50 : Deton(K okm) 50 L 65 H -20 -10 0 10 20 5 Idle	Step 7:Draw simulated graph(Completed) Backgrad Step CONT Overlook Full Graph SIMU Error PARAM. SIMU Draw Control Overlook Full Graph SIMU Error PARAM. Messages Param. Edit Prog. Simulation Cutting Cut Param. Smart Func. Cut Record	7	8 5 2 0	9 6 3 .	+	Home End En	PgUp PgDn ter
-50 -25 0 25 50 3 Decen(K ohm) 50 L 65 H -20 -10 0 10 20 5 Idle	Step 7:Draw simulated graph(Completed) Backgrud Step CONT Overlook Full Graph SIMU Error PARAM Silku Draw Overlook Full Graph Silku Error PARAM GMCode Draw Cutting Cutting Cutting Messages PARAM Edit Prog. Simulation Cutting Cut Param. Smart Func. Cut Record Pitch Prot. Z Vert. ST. Pt Work Run Fail to connect HARD KEY USB Orab Lat Z Estep Br& Pt Shart Funct Stat	7	8 5 2 0	9 6 3 F	+ - * / Reset	Home End En	PgUp PgDn ter



9.6 Full & Overlook

Full : When moving or zooming the graph, to move the graph to the center press the button to resume to the initial status.







Overlook : When the graph is rotating, in order to resume it to second dimension, press the button and restore to the initial status.

J Hint

* Area zoom in : Press <u>Ctrl</u> + right click the mouse, select the assign region. Move the mouse to zoom the area.
* Graph zoom in : Move the mouse to the assign graph, right click the mouse without releasing it and then move the mouse to zoom the graph.
* Graph rotate : Move the mouse and press the assign graph.

* Graph rotate : Move the mouse and press the assign graph without releasing, move the wheel on the mouse to rotate the graph.



9.7 Continuously Draw & Step Draw

Continuously Draw : Click CONT Draw then the graph simulation will start to operate. Time for every block can be setup under Parameter Setting "SI Draw time".

Step Draw : Each time Step Draw has been pressed, the system will only simulate one block of the graph. To complete the entire simulation, please press CONT Draw.



10 EDM DATA Setting

EDM DATA selection is base on the material and thickness of workpiece, feed rate and surface finish.

The Data chart comes with machine can help the operator choose the suitable parameter for machining, and save it in the table. Operator can also input the data base on his/her experience.

10.1 EDM DATA setting in MONITOR mode

At the Machining section under the [Hot Key] and click Auto1 to let the operator to set EDM DATA. Besides, operator can also use the mouse to adjust the EDM DATA.

- (1) Use the keyboard to input the value.
- (2) Use the arrow key $[\land] \cdot [\lor]$ to adjust the value.
- (3) Use the wheel on the mouse to adjust the value.
- (4) Click the small box on the right, a key broad will come out.Adjust the value by pressing the keyboard or moving the scroll.

Figure show as below :



- * To adjust the EDM DATA during the machining process, click Enter or right click the mouse, or the machining process will not match with new EDM value.
- * Press Save Parameter to save the changed condition.





10.2 Processing parameters described conditions

- (1) NO (Number) :
 - \Rightarrow Assign a number for each EDM DATA and save to CNC.
 - ⇒ Number between 0~9999
 - \Rightarrow Call or save Data.



- (2) DM (Skim Cut OV Power AC to DC Power) Range : 1~212
 - \Rightarrow 001~004: Normal discharge circuit

```
(1:80V,2:90V,3:100V,4:120V),AC Power •
```

⇒ 005~008: Normal discharge circuit

(5:80V,6:90V,7:100V,8:120V),DC Power, negative

⇒ 009~016: Normal discharge circuit (9~16),90V AC Power

* EDM DATA only sets for steel materials currently.



\Rightarrow 017~048: Refinement Loop , Skim power equal energy mode(ON) , AC POWER(ON)
⇒ 049~080: Refinement Loop, Skim power equal energy mode (OFF), AC POWER(ON)
\Rightarrow 081~112: Refinement Loop , Skim power equal energy mode (ON) ,
AC POWER(ON), negative
\Rightarrow 113~144: Refinement Loop , Skim power equal energy mode (OFF)
AC POWER(OFF), negative
\Rightarrow 145~176: Refinement Loop , Skim power equal energy mode (ON)
AC POWER(OFF), positive
\Rightarrow 177~208: Refinement Loop , Skim power equal energy mode (OFF)
AC POWER(OFF), positive
\Rightarrow 209~212. Super Refinement Loop, Skim power equal energy mode (OFF),

12: Super Refinement Loop', Skim power equal energy mode (OFF),

	F 1		17~24	25~32	33~40	41~48
AC	Equal	OV Voltage	80V	90V	100V	120V
POWER	Power	Resistance	1~8parts	1~8 parts	1~8 parts	1~8 parts
	Non		49~56	57~64	65~72	73~80
AC	Equal	OV Voltage	80V	90V	100V	120V
AC POWER AC POWER DC POWER negative DC POWER negative DC POWER positive DC	Power	Resistance	1~8 parts	1~8 parts	1~8 parts	1~8 parts
DC	F 1		81~88	89~96	97~104	105~112
POWER	Equal	OV Voltage	80V	90V	100V	120V
negative	Power	Resistance	1~8 parts	1~8 parts	1~8 parts	1~8 parts
DC	Non		113~120	121~128	129~136	137~144
POWER	Equal	OV Voltage	80V	90V	100V	120V
negative	Power	Resistance	1~8 parts	1~8 parts	1~8 parts	1~8 parts
DC	F 1		145~152	153~160	161~168	169~176
POWER	Equal	OV Voltage	80V	90V	100V	120V
positive	Power	Resistance	1~8 parts	1~8 parts	1~8 parts	1~8 parts
DC	Non		177~184	185~192	193~200	201~208
POWER	Equal	OV Voltage	80V	90V	100V	120V
positive	Power	Resistance	1~8 parts	1~8 parts	1~8 parts	1~8 parts

AC POWER(ON) • 209~212 Not available recently

X Caution when exchanging DM,

The level of the resistance and the Anti- resistance is inversely proportional. Due to this reason, if the rougher the surface of cutting product is, the more you have to be careful when replacing the DM condition.



(3) ON (ON TIME)

Range: 1~24 (AC POWER)

- ⇒ Sparking pulse width
- ⇒ The bigger ON time, the larger sparking pulse width. And the average current flow is increase
- ⇒ The more ON TIME will increase the cutting speed. On the other hand, it will cause the wire broken easily, rougher surface and larger sparking gap
- (4) OFF (OFF TIME)

Range : 8~50

- \Rightarrow Interval time between sparking pulses.
- ⇒ The bigger OFF Time, the larger interval time. And the average current flow is decreased.
- (5) AON (ARC ON TIME)

Range : $1 \sim 20$ (AC POWER)

- ⇒ When arc is detected during EDMing, controller will adjust the ON TIME to the assigned value.
- ⇒ When this value is increased, the cutting speed is increased too, but it will cause the wire broken easily.
- \Rightarrow The value should be lower than ON TIME to prevent broken wire.
- (6) AOFF (ARC OFF TIME)
 - Range : 8~50
 - ⇒ When ARC is detected during EDMing. Controller will adjust the ARC OFF TIME to the assigned value
 - Increase this number can prevent broken wire, but it will reduce the cutting speed.
 - \Rightarrow This value should be higher than OFF TIME.
- (7) WT (Wire Tension)

Range: 1~15

- ⇒ The flushing pressure will vibrate the cutting wire and affect the machining accuracy. To prevent wire vibration, increase the wire tension is necessary.
- \Rightarrow The higher WT value input, the better cutting accuracy. On the



other hand, it will cause wire broken easily.

(8) WF (Wire Feed Rate)

Range: 1~15

- \Rightarrow Assign Wire Feed Rate.
- ⇒ Lower wire feed rate is suitable for thin workpiece. Higher rate is suitable for thick workpiece.
- ⇒ If the value is too low, the finish workpiece has different dimensions on upper and lower area.
- (9) WR (Water Pressure)

Range: 0~7

- \Rightarrow Working fluid flush rate.
- ⇒ Working fluid is used to reduce the heat produced during EDMing and make the sparking stable.
- ⇒ The value of WR is proportional to the value of the fluid flush rate.
- ⇒Increase the flush rate will increase the cutting speed, but will reduce the accuracy.
- (10) SV (Servo Voltage)

Range: 0~120

- ⇒ Reference data for assigned working feed rate.
- \Rightarrow If the actual servo voltage is smaller than the setting, it means the sparking is not stable.
- ⇒ The higher value will make the machining more stable, but it will reduce the cutting speed.

Gap Voltage (Actual voltage):

Gap voltage is the voltage between wire and electrode, then compare with servo voltage and determine the Servo Feed Rate. If the Gap Voltage drop to "0V", it means it is under short circuit status





(13) FS (G95 sensibility)

Range : 0~1000

- ⇒ Assign the working sensibility in G95
- \Rightarrow The higher value assigned, the more sensibility created.
- (10) FEED (F value in G94)

Range : $0 \sim 30$

- \Rightarrow F value of G94 in new program can be re- assigned
- \Rightarrow This value can be worked with FEED% \circ
- (12) FEED% (Feed Rate)
 - Range : 0~500
 - \Rightarrow Assign the feed rate while EDMing
 - \Rightarrow This value is assigned by G94 in NC program.
 - EX (1) : G94 F2.0
 - Default Value 90 Maximum Speed 1.80 (mm/min)
 - Default Value 200 Maximum Speed 4.00 (mm/min)

EX (2) : G94 F0.6 Default Value 75 Maximum Speed

- Default Value 75Maximum Speed0.4 (mm/min)Default Value 400Maximum Speed2.40 (mm/min)
- (13) C.LEN (Length of Corner Machining)

Range : $0 \sim 5$

 \Rightarrow Assign the length of corner machining.



10.3 Processing Functions

(1) G95

⇒Assign G95 for machining.

 \Rightarrow The setting can be modified in program.

(2) Single Processing

⇒ When the feature is running, it will only execute a single processing. To instruct other machining, pause the function and then press the Start button.

(3) CORNER (Corner Machining)

⇒ Assign Corner Machining function ON/OFF.

(4) ACR (Arc Machining)

⇒ Assign Arc Machining function ON/OFF

(5) Assign M01

⇒ When the wire travels to M01, the machining process will stop automatically.

(6) POS

⇒During the machining process, SHORT light will appear when wire contact to the workpiece, hence the machine will stop. To continue the machining process, press 《POS》 and then select the 《Start》 button.

(7) Fly Cut

⇒ When it is necessary for the operator to start machining from the edge of the workpiece, flushing issue will occur at this time. The upper flush lid is not able to cover the upper surface of the workpiece completely; hence water pressure cannot be too high. Due to this reason, low water pressure, discharge energy and machining speed is required during the machining. When the upper flush lid has covered the upper surface of workpiece completely, all the conditions can go back to normal. However, this causes a trouble for the operator by changing the working condition very often. Fly Cut is a function which sets a range for the sparking parameter and helps the operator to save lots of trouble.



(8) Gap Voltage Detect System

⇒To avoid short circuit, "Gap Voltage Detect System" will pause the machining process when the gap voltage is shortage.

(9) Dry Run

This feature is used to simulate the shape of the workpiece created by the graphing program. Cutting process will not run at this time. Dry Run needs to be canceled in order to start the machining.

(10) Mechanical Lock

⇒ This function only allows the computer program to run at this time. (Mechanical Processing will not operate.)

The purpose is to check the program itself. During the checking process, test the program by changing the value of the Absolute coordinates (under [Position], at the top of the screen).

% the value of Mechanical Coordinate should be fixed

(11) Parallel Compensation

⇒ Assign Parallel Compensation function ON/OFF

- (12) Z axis Rise
 - ⇒ When the machining is completed, select this key, the Z axis will rise to the assign height.
 - Go to \langle Auto2 \rangle to assign the rising distance of Z axis.
- (13) Reset
 - ⇒ When selecting the Reset Key, everything will restart from the beginning.
- (14) Starting Point

 \Rightarrow Return to the starting point.

(15) Breaking Point

 \Rightarrow Return to the Breaking point.

(16) G92

 \Rightarrow Return to the last G92 point.



- (17) Restart
 - ⇒When power failure during the machining process, the monitor will back to the main manual which show 《WIRE》、《WATER》、 《EDM》. Press the restart button, the machine will continue at the part it stops.
- (18) WIRE
 - ⇒ Press the key, the machine will start to feed the wire and increase the tension of the wire. The instruction will stop when pressing the key again.
- (19) WATER

⇒Press the key, the Working Fluid will be sent. The instruction will stop when pressing the key again. Water pressure can adjust through the button on the water system panel.

(20) EDM

⇒This key represents Power ON. The machine is standing by at this time, however voltage won't pass through the cutting wire in this moment.

(21) Start

 \Rightarrow Press the key, the machine will begin to machining.

(22) Pause

 \Rightarrow Press the key, the machine will stop to work at this time.



10.4 Factors effect working efficiency

(1) Wire Tension

Different material of wire has different wire tension. For higher accuracy machining, higher tension wire is required. If the higher wire tension affects the cutting rate, the wire broken easily. On the other hand, lower wire tension will cause short circuit. High tension is suitable for lower current machining (small ON TIME) and Low tension is suitable for higher current (large ON TIME).

(2) Wire Feed Rate

Wire will wear out and become thinner because of the high temperature produced by EDMing. For thick workpiece, the wire feed rate should be increased, otherwise the wire will be broken easily. Even though the wire is not broken, it will cause the sized different on upper and lower parts of workpiece.

(3) Working Fluid

 Water resistance: The water used for Wire EDM should be through ION- exchanger and become pure water. The water resistance is between10K ~ 100KΩ cm. The figure is shown below.

For tool steel machining, water resistance should set between 10~20 K Ω cm. For Carbide or Mn Alloy steel, water resistance should be 20K~ 100 K Ω cm. If the condition is not matched, it might cause the sparking unstable or rougher finish.

	KENT USA			WEDM	Operation 1	Manual	10. EDM	1 data s	Setting
	100Meg	10Meg	1Meg	100K	Rar 10K	nge for Win 1K	re EDM 100	(10	Resistance) 1Ω.cm
Γ	0.01	0.1	1	10	10 ²	10 ³	10^{4}	10 ⁵	$10^6\mu\mathrm{s/cm}$
	Ideal S pure	Super	Ultra	Pure Water R	Tap esistance/ (0, 5% NaCl Conductivit	Sea ty		(Conductiv
						X	5	6	3

- ② Flush Flow Rate: Flush Flow Rate plays an important role for the cutting process. General speaking, machine can have higher cutting efficiency when flush flow rate is increased.
 - (1) But end of the machining
 - (2) Skim cut
 - (3) Workpiece thickness changed

③ Working fluid will be vaporized in water tank. Water should be added or replaced if the water level is too low or too dirty. (Order of water quality: Distilled water, Tap water, groundwater)



10.5 Parameter Setting

10.5.1 Parameter Setting

This function helps operator to find a suitable sparking parameter or the current processing program.

 Press 《Smart func.》 under Machining Mode, so that the parameter can be adjusted.



search Condition		☑ SC1	SC2	SC3	✓ SC4	SC5
	NO	1640	1641	1642	1643	
SKD	DM	2	2	2	2	
Thickness	ON	16	6	4	2	
20 🔻	OFF	8	12	12	12	
Wire Diameter	AON	14	4	2	1	
0.25 💌	AOFF	10	14	14	14	
Cutting Counts	WT	8	11	12	12	
Cutting Counts	WF	11	10	11	11	
	WR	3	0	0	0	
Priority	SV	30	45	50	50	
Precision Prio 💌	FS	2	2	2	2	
	Feed	4.50	6.00	7.00	12.00	
Search	F.D%	140	150	150	120	
	OFFSET	0.219	0.148	0.143	0.141	
Pre	ss "Save" b	outton after i	modified cor	nditions,ther	they will e	ffective.
C	Com		opy One	Copy A		n er D Walna



- (2) Search Condition : Search condition including workpiece material, thickness, wire diameter, Machining tool time and other conditions. These conditions need to be setup by the operator.
- (3) Press Search, to find a suitable sparking parameter.
- (4) Choose the needed machining condition, then select Copy. A window will appear, type in the group number and then check SC1~SC5. SC1 will be imported to No. 53, SC2→NO.54、SC3→NO.55、SC4→NO.56、SC5→NO.56.

Shown as below :

									C	
							W	USB	USB MUS	B 1342:11
	追求完美·止於至善	Coordinate	Manual	M	lachining	Messa	ge	System	Manual Autol Au	to2 KeyPad Tool
x	0.0000	S-Code Search							Cutting PARAM	Function
		Search Condition		⊴ sc1	SC2	SC3	SC4	SC5	No 53	G95
Y	0.0000	Material	NO	1640	1641	1642	1643			Block cutting
z	0.0000	SKD	DM	2	2	2	2			Corner decel.
	0.0000	Thickness	ON	16	6	4	2		On 16	Arc decel.
U	0.0000	20 💌	OFF	8	12	12	12		Off 8	Run MUI
V	0.0000	Wire Dismeter	AON	14	4	2	1		AOn 14	Pos
w	0.0000	0.25	AOFF	10	14	14	14		10 m	Don't wait our
	0.0000	Cutting Catanta	WT	8	11	12	12			Don't wait gap
• R	kel 🔿 Abs 🔿 Mac		WF	11	10	11	11		VVT 8	Mac locked
O S	tet OBrk OG92	4	WR	3	0	0	0		WE 11	Paral comp
	Set Coor.	Priority	SV	30	45	50	50			I arai. comp.
Disc	Status	Precision Prio -	FS	2	2	2	2			Start Break
Total	. 		Feed	4.50	6.00	7.00	12.00		SV 30	Point Point
P.scl	Malk GD	Search	F.D%	140	150	150	120		FS 2	G92 Restart
-Сар	Volt.(V) 0.00		OFFSET	0.219	0.148	0.143	0.141		Food 45	
5 -50	0 -25 0 25 50 ;	Pre	ss "Save" bi	utton after	modified co	nditions,the	n they will a	effective.		Wire
Deio	on(K ohm)	Cour	Course		Copy One	Copy A		any D Value	F.D%	
50	L 65 H	evec	Сору		Group	Group	s C	opy D value	C.Len 0.5	Water
Ľ		S- ELC		opy PAR/	(MA				Saura and the	TDM
With	mhuu uuluu luu	Code Fly Cut	Arc	Please in	inut target gro	μα(Νο Ω~Νο	999)		Save parameter	EDM
J -20	0 -10 0 10 20 5	GM Code G	W Code	l recise m	partaigergio	ap(140.0 140.	.555)			
					; : : : : : : : : : : : : : : : : : : :				Feed \	Cycle
	Idle	Edit Prog. Sim	ulation		ОК	Cancel	\supset	ut Record	Hold	\ Start
G	ap Break Para rvo Limit Spec	I. Pitch Prot. Z c. Orth. Lmt.Z H	Vert. ST. E.Stop Brk	Pt Wor Pt. Sho	rt F.Hold	Warning:Wi (2013/4/24 (re break)8:19:32)		R	eset Feed Hold
		<u> </u>								
										\mathbb{N}

Find the machining parameter by using parameter setting and then sent it to machining monitor screen.

(4) Utilized Copy, then select one of the options from SC1~SC5, otherwise the message "Select one parameter group only" will appear. When SC is setup successfully, SC condition will be sent to 《Auto1》 automatically.



- (5) Utilize Copy All, the entire SC1~SC5 condition will be sent to
 NO.995~999 doesn't matter if SC1~SC5 is checked or not. Setup the
 S code in order to run the condition through NC program.
- (6)Press (D value export), to sent the OFFSET value to the D value which being used during the G41 or G42 machining.

10.5.2 Fly Cut Setting

(1) To setup the Fly Cut, press \lceil Fly Cut ightharpoonup under the Condition Setting.

-S-Code Sea	rch				Cutting PARAM	Function	
-Fly Cut I	Discharging Condition Setting				No 53	G95	
	a	Ţ					cutting
	Start-up state	Le	mgth of Fly cut(mm)			Corner	decel.
	OFF	3			On 16	🗌 Arc de	cel.
					Off 8	🗌 Run M	101
No	050	AOff In				🖾 Pos	
NU	900	AOII 120			AOn 14	🗌 Fly Cu	t
DM	2	WT 3	Feed 10		AOff 10	🗌 Don't v	wait gap
					мл 8	🗌 Dry Ru	ın
On	18	VVF 5	F.D% [5	%		🗌 Mac. le	ocked
Off	50	WR 4			VVF 11	🗖 Paral. (comp.
A.O.p.	16	SV 20	Save		WR 3	Start	Break
AOII		54 [20			SV 30	Point	Point
					FS 2	G92	Restart
					Feed 45		
						W	ire
					F.D% [140 %		
					C.Len 0.5	Wa	ter
S-	Else Cast Are	Corner DN	A AWT BurPace		Saue narameter		A.C.
Code (Fly Cut Aic	SE	T AWI Dyrass			EL	M

(2) Fly Cut condition setup:

- 1. Setup the Fly Cut length (approx. Radius of flush lid)
- 2. Setup the Fly Cut sparking parameter NO.950 (The sparking

parameter No. cannot be changed.) then press Save Parameter 3. Click $\[\]$ Fly Cut $\[\]$ under $\[\]$ Auto1 $\[\]$, Status will change from Disable to Enable which means the function is ready to work.



10.5.3 Arc Control Setting

Our machining provides Arc and Corner Control setting to avoid corner gets deformed. While the function is operating, CNC will check the setup conditions and adjust the sparking condition of the corner and arc machining automatically.

Code Search					Cutting PARAM	Function	
Arc Radius Setting					No 53	G95	
Start up stata	. ть	a usa of group				🔄 Block	cutting
Start-up state		e use of Storb	Group 0			Corne:	r decel.
OF	r	•	0n 1	× 1	On 16	🗌 Arc de	ecel.
Input Ranges	5			(-)	Off 8	🗌 Run M	401
Group	Radius >	Radius <=	Off 1	(+)		🗖 Pos	
0	0.0	30.5	AOn 1	(-)	AOn 14	🗆 Fly Ci	ut
1	30.5	30.5		XiX	AOff 10	🗆 Don't	wait gap
2	30.5	35.0		(+)		🗌 Dry R	un
3	35.0	36.0	WT 1	(+)		🗌 Mac. I	locked
4	36.0	37.0	W/F 1	(+)	WE 11	🗆 Paral.	comp.
5	37.0	38.0					
6	38.0	39.0	WR 2	(-)	VVR D	Start	Break
7	39.0	40.0	sv 1	(*)	SV 30	Point	Point
8	40.0	45.0					
9	45.0	45.7	Feed 0.8	(*)	F5 Z	G92	Restart
					Feed 4.5		·
		Default	Save		F.D% 140 %	W	ire
	X				C.Len 0.5	Wa	ater
S- Code Fly	Cut Arc	Corner DM SET	AWT ByPass		Save parameter	EI	DM

(1) Press Arc to enter the mode.

(2) Arc condition setting :

 Machining Condition setup : Setup 10 groups of parameter NO.960~NO.969. Press Save Parameter to save the parameter into the table below.

NC Program S Code	– ON	- AON	+ WR	– WT
Radius	(%)	(%)	(Section)	(Section)
$0.0\!<\!r$ (radius) $\leq\!0.3$ mm	60	60	2	2
$0.3 < r (radius) \leq 1.0$ mm	50	50	1	1
$1.0 < r (radius) \leq 2.5 mm$	40	40	0	0
$2.5 < r (radius) \leq 5.0 mm$	30	30	0	0



- Arc machining range : r 0.1~5.0mm ∘ Arrange the minimum r with machining parameter NO. 960. When 『Radius ≤ 』 setup is completed, the next group 『Radius > 』 will be produced automatically.
- 3. There are 2 ways to operate Arc Deceleration : Method I : Before starting the machining, click ^T Arc decelerate <u>under</u> «Auto1». The entire setup radius in NC Program will start the Arc decelerate process.

Method II : In S code, set CS ON to run the Arc deceleration. In addition, $\[\]$ Arc decelerate $\]$ under $\[\]$ Auto1 $\]$ will click on automatically. On the other hand, $\[\]$ Arc decelerate $\]$ will be canceled if CS is OFF.

10.5.4 Corner Control Setting

(1) Press Corner to enter the mode.

-S-Cod	le Search					Cutting PARAM	Function	
-Co	omer Working Ang	le Setting				No 53	G G95	
	Start-up state	The	use of group			DM 2	Block	cutting
	OFF		-	Group 0			Corne	r decel.
				On 1		On 16	🗌 Arc de	ecel.
	Exterior angle s	etting(0~180):	Default			Off 8	🗌 Run M	101
	Group	Angle >=	Angle <	Off 1	_ (+)		🗌 Pos	
	0	0	81	AOn 1		AOn 14	🗌 Fly Ci	ıt
	1	81	90			AOff 10	🗌 Don't	wait g
	2	90	100		_ (+)		🗌 Dry R	un
	3	100	110	WT 1	(+)	VVI 8	🗌 Mac. I	locked
	4	120	180	VVF 1		VVF 11	🗖 Paral.	comp.
	🖸 Cancel inter	ior angle decelerati	on	WP 2		WR 3		
	Interior angle se	etting(0~180):	Default			ev 30	Point	Poi
	Group	Degree >	Degree <=	SV 1				
	5	0	10	Feed 0.8	(*)	FS 2	G92	Res
	6	20	25			Feed 4.5		
	7	30	35	Save			W	ire
	8	40	45			F.D% 140 %		ΠŲ
	9	50	60			C.Len 0.5	Wa	ater
	S-		DM					
Ċ	ode Fly Ci	at Arc	Corner) SET	AWT ByPass		Save parameter	E EI)M

(2) Corner Condition Setting :

Machining Condition Setup : Setup 10 groups of parameter NO.970~NO.979. Press Save Parameter to save the parameter into the table below.



NC Program S Code	– ON	- AON	+ WR	- WT
Radius	(%)	(%)	(Section)	(Section)
$0\!<\! ext{deg}\!\leq\!3$ mm	60	60	2	2
$3 < \deg \le 12$ mm	50	50	1	1
$12 < \deg \leq 35$ mm	40	40	0	0
$35 < \deg \le 110$ mm	30	30	0	0

 Corner machining range 0~180° (Exterior and Interior Angle) :

Arrange the minimum exterior angle to machining parameter NO. 970. When $\[Angle \leq \]$ is setup completed, the next group $\[\[Angle > \]$ needs to be setup manually.

Arrange the minimum interior angle to machining parameter NO. 975. When $\[\] Angle \leq \] is setup completed, the next group <math>\[\] Angle > \] needs$ to be setup manually.

3. 2 ways to operate Corner deceleration :

Method I : Before starting the machining, click [©] Corner decelerate <u>under</u> «Auto1». The entire setup radius in NC Program will start the Corner decelerate process. Method II : In S code, set CS ON to run the Corner deceleration. In addition, [©] Corner decelerate <u>under</u>«Auto1» will click on automatically. On the other hand, [©] Corner decelerate <u>will</u> be canceled if CS is OFF.



Corner Machining

The angle of this figure is 90° , 1.5 mm is the length of both sides corner. The length is shown on the sparking parameter C LEN=1.5

10.5.5 DM SET

This feature is used for the manufacturer to adjust the sparking parameters, the user is not able to operate it.



10.6 Cut Parameter

EDM Table					EDM Database				
NO	DM	ON	OFF	AON	AOFF	WT	WF	WR	^
0	2	4	20	6	18	10	3	5	
1	2	10	10	8	9	9	6	3	
2	2	17	10	14	8	9	12	7	
3	2	16	8	14	10	8	11	3	
4	2	16	8	14	10	8	11	3	
5	2	6	12	4	14	11	10	0	
6	2	6	50	12	50	6	6	6	
7	2	7	50	14	50	7	7	7	
8	2	8	50	8	50	8	8	4	
9	2	9	50	9	50	9	9	6	
10	2	10	10	10	10	10	10	0	
11	2	11	10	2	15	7	7	0	
12	2	12	20	6	18	8	8	5	
13	2	10	50	8	50	3	15	4	
14	2	5	50	8	50	3	5	4	*
<									>
NO. 0 Search									
Save Copy Upload Restore									

(1) Press 《Sparking Parameter》 under 【AUTO】 to enter the mode.

M Hint

Under $\langle \text{Sparking Parameter} \rangle$, press $\langle \uparrow \rangle$, $\langle \downarrow \rangle$, $\langle \text{PgUp} \rangle$, $\langle \text{PgDn} \rangle$, mouse, or $\lceil \text{Search} \rfloor$ etc. in order to change the sparking parameter.

(2) When modify the «Sparking Parameter», move the light bar to the assign condition. Press Enter to key in the value and press Enter again to complete the procedure.



(3) User Parameter Archive

When the modification of sparking condition is completed, press Save so that the data can still be used next time.

(4) User Parameter Upload

Move the light bar to the assign sparking parameter and then press Upload to send the data to the recent Auto Screen.

(5) Sparking Parameter saved

Setup the sparking parameter on the Auto Screen, and then press 《Save Parameter》 to save the parameter into the data table.

(6) Cover User Parameter

Move the light bar to the assign sparking condition and then press \boxed{Copy} , a window will appear. Input the NO. of the parameter and press \boxed{OK} .





10.7 Cut Recrod

Press 《Cutting history》 under 【Machining】 to enter the mode. Two types of History display mode.

Working	; History						
	Time	File name	Column number	×	Y	Z	~
001	2013/4/24 08:19:31	0402-1.nc	0	0.0000	0.0000	0.0000	
002							
003							
004							
005							
006							
007							
008							
009							
010							
011							
012							
013							
014							
015							
016							-
						7	
				S Brea	et k PT.	Move to Record poi	int
Brk. Reco	Pt. Cutting rd history						

10.7.1 Brk. Pt. Record

- (1) Broken Wire Point History list
 - 1."Broken Wire Point History list" records 100 Broken wire Point History. 001represents the last broken wire point and 100 stands for the first broken wire point. The record will update automatically.



- 2. To return to any broken wire point, move the light bar to the assign value and press Set Break PT. The system will set the point as the broken wire point.
- Ex I : 1. Operate O9960program cut, record the 3 broken wire point coordinates during the operation.
 - 2. To set the first broken point as the current broken point, machining program needs to be reset. Next move the light bar to 003 and then press Set Broken PT. Start the Broken Wire Point return function, the machine will move to the first broken point position.
 - 3. Press 《Wire》、《Water》、《EDM》、《Restart》 Machining position will start from the first broken point.



! Note

To recall the original program, the content of parameter setting has to be same as the previous setup. Otherwise it may cause the damage of workpiece.

(2) Move to Record point

Based on the workpiece requirement to setup the broken point.

When returning to different broken point, be caution of the height of the Z axis needs to be taller than the height of the work table.

! Note



10.7.2 Record

(1) Under [Machining] screen, press 《Cut Record》 and then select 「Cutting history」 to enter the mode.

No.	Program Name	Date	Start Time	Cutting	Total	Cutting
1	13018-305-03.NC-003.NC	04/22/2013	10:33:19	00:01:56	02:33:07	262.255
2	13018-305-03.NC-003.NC	04/22/2013	10:31:26	00:01:51	02:31:10	258.411
3	13018-305-03.NC-003.NC	04/22/2013	10:30:02	00:01:22	02:29:19	254.729
4	13018-305-03.NC-003.NC	04/22/2013	10:24:57	00:05:03	02:27:56	254.255
5	13018-305-03.NC-003.NC	04/22/2013	10:23:04	00:01:51	02:22:52	244.261
6	13018-305-03.NC-003.NC	04/22/2013	10:21:40	00:01:22	02:21:01	240.578
7	13018-305-03.NC-003.NC	04/22/2013	10:16:36	00:05:02	02:19:38	240.105
8	13018-305-03.NC-003.NC	04/22/2013	10:14:43	00:01:51	02:14:35	230.117
9	13018-305-03.NC-003.NC	04/22/2013	10:13:19	00:01:23	02:12:44	226.433
10	13018-305-03.NC-003.NC	04/22/2013	10:08:14	00:05:03	02:11:21	225.959
11	13018-305-03.NC-003.NC	04/22/2013	10:06:22	00:01:51	02:06:18	215.960
12	13018-305-03.NC-003.NC	04/22/2013	10:04:58	00:01:22	02:04:26	212.276
13	13018-305-03.NC-003.NC	04/22/2013	09:59:52	00:05:04	02:03:03	211.802
14	13018-305-03.NC-003.NC	04/22/2013	09:57:59	00:01:51	01:57:59	201.807
15	13018-305-03.NC-003.NC	04/22/2013	09:56:35	00:01:22	01:56:07	198.122
16	13018-305-03.NC-003.NC	04/22/2013	09:51:31	00:05:03	01:54:44	197.649

Brk. Pt. Cutting Record history

- (2) Machining record display data :
 - Work number : The number increases from number 1.
 Press START to start or pause the machining. Each time when pressing the START button, the number will increase by 1.

Clear

- 2. Program name : Name of Processing Program.
- 3. Date : Date of machining.
- 4. Starting time : Start machining time.
- 5. Machining time : Display the Start and Stop time of the machining. Machining hold including M02 pause and machining pause.
- 6. Cumulative time : Total time of machining.
- 7. Machining length : Display single machining length.





(3) Press "Clear" to delete all the data.



ψ0.25

ψ0.30

Cutting Wire Position Adjustment

Operator can use the functions in [Manual Mode] to do Cutting Wire position Adjustment

Manual Mode provides the positioning function for operator to find the position to Top surface, center of circle hold and center of workpiece.

① Probe the surface of workpiece: Auto EDGE Find

⁽²⁾Probe the center hole: Center hole position (Find center)

③ Center of workpiece: Find the slot

Set up the wire tension and feed rate before Auto

	Positioning.	
Wire Dia.	Wire Tension (g)	Wire feed Rate
ψ0.10	5 (aprox. 500g)	5
ψ0.15	8 (aprox.1000g)	5
ψ0.20	9 (aprox.1300g)	5

13 (aprox.1700g)

14 (aprox.2100g) ^(O) Be sure there is no dust, rust and bur on the workpiece before Auto Positioning

5

5

 \rightarrow Use clothes or millstone to clean the dust, rust or bur.

Adjust the Vertical position before Auto position

 \rightarrow If the vertical position shifted, the Auto Position function might not work properly

 \bigcirc Set the Z axis to the match working height.

 \rightarrow If the height on Z axis and on EDMing are different, it might affect the accuracy of positioning

() the area for positioning should be dry surface.

 \rightarrow If there is water on the Positioning Surface, it might cause the Positioning not accurate.





© Enter [Manual] Mode

11.1 Take one corner of workpiece as Reference Point

EX : Find the position in start hole











			W USB H	HUSB MUSB HAR
	Coordinate Manual	Machining Message	System	Manual Auto1 Auto2 KeyPad To
X 0.0000	Edge Finding	Edge Finding Msg		
Y 0.0000	이 안 있는 것	-YV Avie Disection - Cutting Wire Cetting		Go Pos. Go Vert. Go Lm
		O Y+ 0.0	00 V	S.Pt Retn H.Pt Retn G92
V 0.0000		⊙ X- ⊙ X+ WT 10		2 2 7
W 0.0000	10 m -	OY-WF3	Wire	Org. S.Pt Org. H.Pt Soft Li
⊙ Rel ○ Abs ○ Mac				Set/Cancel
⊖Strt ⊖Brk ⊖G92				Manual Mode
Set Coor.	First Speed Slow	Speed Final Speed	Length of EDGE(mm)	○ Inch Jog ○ Jog ◎ Off
Disc. Status Total				O MPG O FUN
Gap Volt.(V) 0.00			_	Manual Paprameter - OFF O x1 O x10 O x100 O x10
5 -50 -25 () 25 50 ;	Cton	Ctor	urt .	0
Deion(Kohm)	Finding	Findi	ng	-Moving Direction
				• XY • UV
) -20 -10 () 10 20 S				
Lila	Return Finding Finding	g Center Center Center	Edge Vert. Corner Adjust	
Iule	PARAL. Coor. MDI COMP. Table MDI	Original Pitch Orth. Path COMP. COMP.	Polar Correct	Y- Z-
Gap Break Para Servo Limit Spec	1. Pitch Prot. Z Vert. S c. Orth. Lmt.Z E.Stop Bi	T. Pt Work Run Fail to connect HA	ARD KEY USB 26)	Reset Fee Hol
	(3) Sp	beed: Unit mm/min		
	Fi	rst Speed: The wire	's speed u	under the 《Edge》
	100	ada		

> **First Speed:** The wire's speed under the 《Edge》 mode.

Slow Speed : The speed when wire touches workpiece the first time.

Final Speed : The Speed after the wire contact to the workpiece again.



Length of EDGE : The range of machine's moving distance. When the machine is moving over the range, "Over the Movement Range " will appear. Please check the input condition at this time.

- * Please input the correct value in order to increase the accuracy when using the EDGE FIND.
- (4) Setup the condition of Wire Tension, Wire Speed and Axis Direction then press 《Edge》. Wire will start to progress and a message will appear when the work is done.

* The Setup Parameter will be saved in the memory system.



(5) Set the radius of the wire as relative coordinate. EX: Specify X0.125 and press $\langle\!\!\langle \, Enter \, \rangle\!\!\rangle$.







(6) Move the wire to the surface which is paralleled to Y-2 plane.



- (7) Return to $\langle Edge \rangle$ mode.
- (8) Press $\langle +Y \rangle$ to start EDGE FIND.

When the EDGE FIND is completed, the message "Edge completed" will be shown on the screen.

(9) Set the wire radius as REV. Coordinate. EX: Assign Y-0.125, then press \langle Enter \rangle .




(10) Burn the wire and move it to REV. Coordinate: X, Y (0,0) position.







(11) Move the cutting wire to X-40.000 and Y+20.000



Use $\langle JOG \rangle$, $\langle -X \rangle$ and $\langle +Y \rangle$ keys to move the cutting wire close to the start point.

Press (INC_JOG) then press (-X) and (+Y) to move the wire to start point.

(12) Lower the Z axis and move the upper machine head to machining position.



11.2 EDGE FIND by using remote control

(1) Let the cutting wire close to the workpiece



(2) Press 《FUN》 on the remote controller, the light will

on



(3) Press 《MODE》 on the remote controller, 【Manual】 mode will appear on the screen. Press 《MODE》 again, the function will appear in the order of 《Original Point》→《Edge》→《Slit》→《 Center》→《Cylindrical Center》 → 《Center of dimention》 → 《Vertical》 → 《Parallel Compensation》 → 【Machining】



(4) Press 《+X》 《−Y》 《−X》 《+Y》 on the remote control to assign the XY axis to the designated position.



11. Cutting Wire Position Adjustment



- (5) Check the working wire setup and speed.
- (6) Press 《START》 on the remote control to start the EDGE Find



HOLD

 \bigcirc

(7) Press 《HOLD》 to stop.

11.3 Take Machining Start hole as the reference point

(1) When the wire is located in the starting hole of workpiece, please do the following procedures for Positioning.





- (2) Under [Manual] select «Center», 3 modes are shown as follow
 - 1. Short circuit exclusion.
 - 2. Manual Center Find.
 - 3. Auto Round center Find.



- If the radius of the circle is too small, short circuit will occur after the threading process. At this point please switch on Short circuit exclusion to solve the issue.
- 1. Short circuit exclusion. : Move the wire outward with a spiral pattern, when the gap voltage reach DC8V (Wire returns to the normal status), the wire will start to search the round center again.





- A. After selecting On, the entire area will turn yellow and On will switch into Off, which means the feature has started to work.
- B. There are 2 modes of cutting direction, Customize and Fixed mode. When both are assign to be used, Customize mode will operate first.

Fixed mode: 8 types of cutting angle from 0 to 7, the value of angle can be obtained from "Deg".

Customize Mode: Click "Deg" to input the value. Range: $0^{\circ} \sim 360^{\circ}$

EX: Click "Deg" and type $90^\circ\;$, the wire will move at the direction of $90^\circ\;$.



- C. Step : Spiral route, the distance between the starting point and the outer edge.
 EX : Step :0.25mm
- D. Speed : Unit mm/min

During the Short Circuit exclusion, the speed at this time will be different from the normal status due to the gap voltage increased. Examples are shown below:



	EX: Set hole diameter as 0.5mm and Step as 0.1mm.
	First Speed: >0.5mm, when gap voltage increases, short
	circuit may occur again.
	Slow Speed : = initial speed/2
	When the speed is too fast during the
	second time cutting, it may cause the
	distance of the final cutting out become too
	long.
	Final Speed : Step/2
	Moving Speed := Step •
	The speed when the wire is moving to the
	center of the hole.
	Radius of the circle : =Diameter of the hole
lote	When Short Circuit exclusion is not solved, "Over the Diameter Range" will appear. Please check the input value at this time.
2.	 Manual Center Find : Using 3 point to find the center of the circle. A. Do the 《Edge》 process in any direction, but do not operate under the short circuit situation. B. After return to the 《Arc Center》, select SET under the first coordinate (Mechanical Coordinate). At this point X and Y coordinate will show on the block. C. Repeat the same step for second and third coordinate
	(Mechanical Coordinate).D.Click Center under central coordinate, X, Y value will be displayed. Press Go then X, Y will move to the assign position.

3. Auto Center Find : After setting up the require parameter, press Center Find so that the machine is able to find the central position.

! Note



- A. Set the speed parameter (reference to **11.1(3)**)
- B. Click Go under center coordinate, X or Y will move to the center position. X or Y will move the starting point if Go isn't been selected.

C. Select 《Center》, 《Wire》 will begin. X or Y will start Center Find process when the gap voltage reaches the Edge find voltage.



(2) Rev. Coordinate

If the reference point is far away from basement, operator can set the reference point as Rev. Coordinate. Shown as below:





11.4 Searching center by using remote controller

(1) Put the wire through starting hole. Cutting Wire should be in the center of starting point.



(2) Press $\langle\!\!\langle FUN \rangle\!\!\rangle$ on the remote controller, the light will on



(3) Press 《MODE》 on the remote, the screen will return to
 [Manual] Press 《MODE》 again until the screen shows
 《Arc Center》



- (4) Check the working wire setup and speed.
- (5) Press 《START》 on the remote control to start the EDGE Find



(6) Press $\langle\!\!\langle HOLD \rangle\!\!\rangle$ on the remote control to stop.





11.5 Positioning in the slit

(1) Make the wire through the slit



- (2) Select 《Slit Finding》 under [Manual]. There are 2 types of Slit:
 - 1. Manual Slit Find 2. Auto Slit Find



- 1. **Manual Slit Find :** This feature helps to find the distance between the two ends of an axis then the machine will start to move to the central position.
 - A. Click "Positioning Slit" on XY plane direction
 - B. Set the speed parameter (reference to 11.1(3))
 - C. Use + and key to operate Edge Find, however this method cannot work under short circuit situation.



- D. After return to the 《Slit finding》, select <u>SET</u> under the first coordinate (Mechanical Coordinate). At this point X and Y coordinate will show on the block.
- F. After return to the 《Slit》, select SET under the second coordinate (Mechanical Coordinate). At this point X and Y coordinate will show on the block.
- G. Press Go under slit center coordinate, the value will be display.
- H. Click \langle Slit Center \rangle , X or Y will move to the center position.
- Auto Slit Find : Press 《Slit》 after input the required parameter, the system will find the slit center automatically.
 - A. Click "Positioning Slit" on XY plane direction
 - B. Set the speed parameter (reference to 11.1(3))
 - C. Click «Slit Center», X or Y will move to the center position. X or Y will move the starting point if Go isn't been selected.
 - D. Select 《Start Finding》, 《Wire》 will begin. X or Y will start Center Find process when the gap voltage reach the Edge find voltage.





11.6 Remote controller Positioning in the slit

(1) Make the wire through the slit



(6) Press $\langle HOLD \rangle$ on the remote to stop.





12 Preparation Before Machining

Before machining, operator should adjust the gap between upper or lower flush head and workpiece, then execute the Dry Run function to check the status of machine movement.

12.1 Adjust the position of upper flush head

(1) Tighten the upper flush head cap.



(2) Move the XY table under Manual mode till the lower machine head is under workpiece.



《JOG》			
$\langle\!\!\langle +X \rangle\!\!\rangle$	$\langle\!\!\langle -X \rangle\!\!\rangle$		
$\langle\!\!\langle +Y\rangle\!\!\rangle$	$\langle\!\!\langle -Y\rangle\!\!\rangle$		



(3) Loosen the upper flush cap and adjust the gap between the lower head and workpiece to 0.2mm with Blad Feller Gauge.



12.2 Adjust the gap of lower flush head

(1) Make sure the lower flush cap is screwed on the lower machine head correctly.



(2) Move the XY table till the upper machine head is above the workpiece.





(3) Press $\langle\!\!\langle -Z \rangle\!\!\rangle$ key and lower the upper machine head alone Z axis.

Be careful don't let the machine head hit the workpiece or holding Jig while lower down the upper machine head.



(4) Lower the feed rate while upper machine head close to workpiece.

《LOW×1》《-Z》

Use Jog mode to move to lower machine head while lower flush cap close to workpiece .

Put the Blad Feller Gauge between lower flush cup and workpiece.





(5) Lower down Z axis and move the Blad Feller Gauge back and forth. When the Blad Feller Gauge cannot be moved, it means the adjustment is finish.





(7) Set Z axis limit in POSITION screen. (Start "Find the original point" is required, or the warning alert will appear.)



The color of Z axis will change and the Mechanical Coordinate will appear.

(8) If the upper machine head is moved lower than the Zlimit, the alarm will will be ON and Z axis will stop moving.

Press (+Z) key and move the Z axis up and higher than the lower limit, then press (RESET) to clear Alarm.

(9) Press 《Set/Cancel Z axis limit》 key to cancel Z axis lower limit.



12.3 Checking machine movement via DRY RUN function

Use dry run to run the program and make sure the upper and lower machine head won't touch the Jig holder, or exceed the working range,

Check the following situation while machine moving:

- ① Lower flush cap doesn't touch the jig holder.
- ② Upper and lower flush cap are not exceed the working area.
- ③ Cutting Path is not exceed workpiece, or cover the hole on the workpiece.
- A Rotating angle of the workpiece is match to the angle in the program.
- ^⑤ Program error or Call error Code.
- * Operation Procedure
- (1) Cut the wire and remove it from wire guide. Press
 《 Manual Wire Threading 》button to remove the rest of the wire. After the wire is removed, press 《 Manual Wire Threading 》 button again.



- (2) Under 【System】 → AUTO1 → 《Operator Parameter》 assign manual dry run speed value and then pressEnter. The value is proportional to the dry running speed.
- (3) Under [Auto1] select 《Dry Run》 and then click Start
- (4) Since the value of Manual Dry run is 0, the machine won't function when pressing the 《START》 button To stop the machine immediately, press Pause or the 《HOLD》 button on the remote control.





(5) If the dry run is complete and there is no problem occurred, operator can install the workpiece properly. otherwise, please check the setting and install the workpiece again.

M Hint





13 Machining

After the NC program input, diagram simulation, parameters, setting, Sparking Parameters setting and Cutting wire position setting are complete, please switch to [Machining] mode. Press [Machining] to enter machining mode.

					Г	WUIDD 1	LIOD		1107		707.4	
	1	a r t	14 1	b d - Linia		W USB A	USB		USE		34:1	3:0
単水ジ	花英・止於至暮	Simulation	Manual	Machining	Message	System	Manual	Autol	Aut	o2 Ke	eyPad	10
X	0.0000	Xmax = 25.7 Xmin = -0.23	'30 Ymax = 80 Ymin =	= 8.865 Zr : -17.095 Zr	nax = 60.000 nin = 0.000 X	4.0000	A	В	С	D	Е	F
Y	0.0000				Y	4.0000	G	н	I	J	К	Ĺ
z	0.0000				L	0.0000	м	N		P		
U	0.0000				V	0.0000			Ť			
V	0.0000		_			The Length of Path(mm) 241.822	S					
N	0.0000					Cutting Taper(Degree)	Y	Z	-	=	<u> </u>	ļí
🖲 Rel	🔿 Abs 🔿 Mac				L L	Wire compensation(mm)	{	}	;	,	*	<u>}</u>
O Stat	○ Brk ○ G92						1	@ 2	# 3	\$ 4	% 5	Î Ĝ
S	Set Coor.						 	*	5	7		<u>~</u>
Disc. Stat Total	tus				G	503 G505	Ba		<u></u> т,	ah		hift
P.scl Gan Volt	.(V)					Color of XY Plane						THIC
uiuu					E	Color of UV Plane G00 Color				En	iter	
5 -50 -2	5 () 25 50 ;	1				顏色設定	Caps	Lock				
50	L 65 H		Step 7:Di	raw simulated graph(Completed)		7	8	9	+	Home	Pq
	mimhim	Backgrnd Str SIMU Dra	ep CONT aw Draw	Overlook Graph Full Gra	uph SIMU Cutting M	Error PARAM Messages Setting	4	5	6	•	End	Pg
-20 -1	0 0 10 20 3	GM Code	GM Code				1	2	3	*		
	Idle	Edit Prog.	Simulation C	utting Cut P	aram. Smart Fu	unc. Cut Record			·	7	Er	nter
Gap	Break Paral	l. Pitch Prot. 2	Z Vert. ST. Pt	Work Run	Fail to connect HA	ARD KEY USB			P	ocot	F	iee
Sarua	Limit Spec	. Orth. Lmt.Z	E.Stop Brk Pt.	. Short F.Hold	(2013/4/24 08:19:2	26)				JUCI		Iol

After switch to [Machining] mode, Cutting is shown. Press Wire \Water \EDM keys, then press CYCLE START to start machining.



13.1 Before Press CYCLE START Key

One the Spark is begin, program setting cannot be changed. Please double check the setting before press <u>CYCLE START</u> (1) Check the current position. * Check Machining Start Point * Check the perpendicularity of U and V axis. * Check Z axis limit.

					X						
[6				W NSB H	USB		USI	ВήГ	15:30:	05
道求完美,止於至善	Coordinate	Manual	Machining	Message	System	Manua	Autol	Aut	to2 Ke	yPad T	'ool
X 0.0000	Editing 00001 00100					A	в	7c	D	Е	F
Y 0.0000	00002 N100 G 00003 N102 G	0 G21 G90 92 XO. YO. I100.	. JO.			G			H		
Z 0.0000	00004 N110 S 00005 N112 G	101 D1 41 G1 X6.				Ű	<u> </u>	<u> </u>	H	<u> </u>	
U 0.0000	00006 N114 G 00007 N116 X	3 X-6. I-6. 6. I6.				M		<u> </u>		<u> </u>	R
V 0.0000	00008 N118 X 00009 N120 G	5.9792 Y.4994 I- 40 G1 X2.9896 Y.	-6. .2497			S	Ţ	U	V		Х
W 0.0000	00010 N124 M 00011 %	30				Y	z	-	+	1	2
• Rel O Abs O Mac						{	$\left \right\rangle$:	п ,		>
○ Stat ○ Brk ○ G92							[º	#	\$	% (* 5 (*	 6
Set Coor.						8		<u> </u>	$\overline{\mathbf{b}}$	<u> </u>	_
Disc. Status Total						 	<u>) 8</u>	9			_
P.scl										Shin	
							Otrl		En	ter	
5 -50 -25 0 25 50 3						Сар	s Lock				
Deion(K ohm) 50 L 65 H	File name: 122	28001.NC				7	8	9	+	Home Pr	gUp
	Open Sa	ave/ Create	RS-232 Searc	h Undo	Redo Retn Main		I-I	6	H	End P	- '
) -20 -10 0 10 20 C	File De	stete INEW File	text		nouny riog.		Ĥ	<u> </u>			
TI	GM Code	GM Code						3	_	Enter	r
Idle	Edit Prog.	Simulation C	utting Cut F	aram. Smart Fu	inc. Cut Record		0	•			
Gap Break Par Servo Limit Spo	al. Pitch Prot. ec. Orth. Lmt.	Z Vert. ST. Pt Z E.Stop Brk Pt.	Work Run Short F.Hold	Fail to connect HAI (2013/4/24 08:19:2)	RD KEY USB 6)			R	eset	Fee Hol	ed Id

(2) Check the display screen

* Check program code.

* Check sub-program code if necessary.



13. Machining

					W USB H	U	SB	M	USE	3	14:0	9:37
	Coordinate	Manual	Machining	Message	System	M	lanual	Autol	1 Aut	.02 Ke	eyPad	Tool
X 0.0000	Simulation D value Offset	Simulation	options			1	A	в	С	D	E	F
Y 0.0000	000 0.225 III	Scale Factor	S Rotation Angle	Hold Time 2			G	н	I	J	ĸ	L
Z 0.0000	002 0.144 003 0.138	Thickness	Program Plane	1			м	N		P		R
U 0.0000	004 0.147	50										
V 0.0000	006 0.2	G48-Rxy	G48-Ruv			K	S	T	U		W	X
W 0.0000	007 0.0				- Inc.		Y	Z	-	=		?
⊙ Rel O Abs O Mac	009 0.0 010 0.0	0 - Inters	al	J □ X mirro	r img. r Img.		{	}	:	, ,	`	>
⊖Strt ⊖Brk ⊖G92	011 0.0 012 0.0	0 - Curso	or 1	Axis exc	change		 1	@ 2	# 3	\$	% 5	Ê
Set Coor.	013 0.0 014 0.0		Restore	Height of U	pper		& 7	* 8	(9)	\mathcal{D}	
Total Pscl	015 0.0 016 0.0		Work Setting				Ba	ack	Т	ab	s	hift
Gap Volt.(V) 0.00	017 0.0 018 0.0	D.	Restore	Height of Lo 12.12	ower		C	Xrl			·	
5 -50 -25 0 25 50 ;	019 0.0 🖌		ckground Setting		E 11		Caps	Lock	1	Er	nter	
Deion(K ohm)	<< 1/3 >>		Edit Default Comp. value	G	Enable uide Setting		R				v——	
50 <u>L</u> 65 <u>H</u>							7	8	9	+	Home	PgUp
արտիսուսուրու	Backgrnd Step SIMU Draw	CONT Draw	Overlook Graph Full Graph	SIMU Cutting	Error PARAM Messages Setting		4	5	6	Ŀ	End	PgDn
D -20 -10 0 10 20 3	GM Code GM C	ode					1	2	3	*		
Idle	Edit Prog. Simul	ation Cu	utting Cut Para	m. Smart F	unc. Cut Record		(0	ŀ	/		ner
Gap Break Para Servo Limit Spec	l. Pitch Prot. Z Ve c. Orth. Lmt.Z E.S	rt. ST. Pt Stop Brk Pt.	Work Run Fa Short F.Hold (20	il to connect HA 13/4/23 08:12:	ARD KEY USB 36)				R	eset] F H	eed lold

(3) Press 《Simulation》 to check the parameter setting.

- * Check Rotation angle and Scale
- * Check X, Yaxis mirror axis and axis switch setting.
- * Check Path compensation
- *Check Cone angle setting
- * Check the setting is same as drawing.



-Arc Radius Se	tting			Corner Working Ar	igle Setting	
Start-un s	tate Th	ie use of moun		Start-up state	The u	use of group
Dian up a	OFF III	-		OF	F	-
Input Rar	iges			Exterior angle	setting(0~180):	Default
Group	Radius >	Radius <=		Group	Angle >=	Angle <
0	0.0	30.5		0	0	81
1	30.5	30.5		1	81	90
2	30.5	35.0		2	90	100
3	35.0	36.0		3	100	110
4	36.0	37.0		4	120	180
5	37.0	38.0				
6	38.0	39.0		Cancel inte	erior angle deceleration	
7	39.0	40.0		Interior angle	setting(0~180):	Default
8	40.0	45.0		Group	Degree >	Degree <=
9	45.0	45.7		5	0	10
			UT	6	20	25
		Defails		7	30	35
		Detault		8	40	45
				9	50	60

(4) Under 《Smart Func.》 → click 「Arc/ corner」 check
 EDMing Parameter and other assist functions.

* Check FLY CUT function

* Check AWT function.

* Check Arc function Setting.

* Check Corner function Setting.

M Hint

※If all the functions are not shown on the screen completely, please type "EDM ON" in input column then press 《Enter》



1

13. Machining

ſ					W USB H	US	В	- M.	USB	ſ	39: 8	3:29
	Coordinate	Manual	Machining	Message	System	Ma	nual	Auto 1	Auto	2 Ke	yPad	Tool
X 0.0000	Simulation Xmax = 25.7	30 Ymax =	8.865 Zm	ax = 60.000			A	B	c	р	F	F
Y 0.0000	Xmin = -0.23	0 Ymin =	-17.095 Zm	in = 0.000	X 4.0000				-+		Ĩ	÷
Z 0.0000					1 4.0000 U n nnnn		G	н		1	K	L
					V 0.0000		м	N	0	P	Q	R
V 0.0000					The Length of Path(mm)		s	T	U	V	W	x
V 0.0000					241.822		γ	z	- 1	+	$\overline{1}$?
vv 0.0000					Cutting Taper(Degree)		2			-	$\overline{\langle}$	\rightarrow
Rel Abs Mac					Wire compensation(mm)	ļ		<u>i</u>			<u>. </u>	
			1	7	G501 (Inside) G501 (Outside	ŊĽ	ц	2	3	\$ 4	5	6
Set Coor.			1		0 0		3	*	()		
Disc. Status Total					G503 G505 0 0		Ba	ck	Tak		Sł	nift
P.scl Gap Volt.(V)					Color of XY Plane		-	-+				-
					Color of UV Plane G00 Color		Ut	ri		En	ter	
5 -50 -25 0 25 50 ;	7				顏色設定	C	Caps	Lock				
Deion(Kohm) 50 L 65 H		Step 7:Dr	aw simulated graph(Completed)			<u>E</u> Y		. n		_	
	Backgrad Ste	n CONT	Ouerlook	SDALL	Error DADAM	H	7	*	9	+	Home	PgUp
ահակառակակա	SIMU Dra	w Draw	Graph Full Gra	ph Cutting	Messages Setting		4	5	6	•	End	PgDn
D -20 -10 0 10 20 3	GM Code	GM Code					1	2	3	*		
Idle							^ 0	- î	_^	7	En	ter
	Edit Prog. S	imulation Cu	Itting Uut Pa	ram. Smart	Func. Cut Record							
Gap Break Para	1. Pitch Prot. Z	Vert. ST. Rt	Work Run	Fail to connect F (2013/4/24 08:19	HARD KEY USB 9:26)				Re	set	F	eed

(5) Press [Machining] key to back to MONITOR Screen.



13.2 Check Cutting Wire and Water Tank

(1) Is there enough wire for machining?





13.3 Fill water in water tank (for submerged mode)

(1) Turn Pump on to fill the water tank.

Operation button for water tank
For Submerged Type Wire EDM :
^① Press Water Dump Button (Light OFF) and shut down
Water Dump.
[©] Press Water In Button (Light ON) and water in.

(2) Set up the water level height (5~10cm above the workpiece.)

	Water level	Set up water level
		5~10cm above
		workpiece
X OL		



13.4 After pressing CYCLE START

When all the setting is checked, and work tank is full of water, Press 《CYCLE START》 to start machining.

(1) Press WIRE key.



(2) the lights of < Wire_Break > and < Short > ON.



- <Wire_Brk>Light is ON :
- * Check does wire broken?
- * Check does broken wire sensor touch cutting wire.
- * Check does cutting wire touch the metal part.
- * Check the angle between broken wire sensor and cutting wire.
- <Short>Light is ON.
- *Check does cutting wire touch workpiece.
- *Check does cutting wire touch machine.
- (3) Check Dry Run and Mac. Locked key.





13. Machining





13.5 Minutes after EDMing

Cutting Wire n=might be broken in the first 5 minutes because of the unstable EDMing.

The operator should not press 《CYCLE START》 key and leave right away. 5 minutes monitoring is needed.

(1) In most of the case, wire is cutting in 5 minutes.



(2) The flushing water in starting hole will cause the EDMing unstable.



- (3) Reduce the feed rate will make EDMing stable and
 - <Low_Volt>won't blink (reduce 20% \sim 30% is needed)
- (4) When the cutting is stable, you can increase feed rate and set as the original value.
- ! Note

When the EDMing is stable and still using the low feed rate, the EDMing efficiency and accuracy will be change. When the wire is cutting in the shape, it's better to change the feed rate back to original setting.



13.6 MONITOR

Switch to [MEM] mode and enter (MONITOR) screen.

The following functions are in MONITOR screen:

- $(\,1\,)\,$ There are 5 area in MONITOR screen.
 - Program Diagram, Machining Time, Program content Compensation, Machining Speed.
 - REV, ABS and Mechanical Coordinate.
 - Spark Parameter is shown. Setting can be changed via press ↑ ↓ key
 - * PS: Please press Enter after the adjustment.
 - Mirror · Axis Exchange · Parallel Compensation · Rotating Angle · Threading · M50/M60 status display.
 - 5 Gap Voltage Water Resistance.





13. Machining

						W USB H	USB	MU	JSB 09:57:19
	車求完美・止於至著	Coordinate	Manual	Machining	Message	System	Manual	Auto1	Auto2 KeyPad Tool
х	0.0000	Simulation Xmax = 7.07	70 Ymax =	: 14.14∩ 7m:	ax = 25.000		Cutting	PARAM	Function
Y	0.000	$-\frac{1}{2}$	0 Ymin =	0.000 Zmi	n = 0.000	X 0.0000	No	53	Block cutting
-	0.0000					Y 0.0000	DM	2	Corner decel.
2	0.0000					U 0.0000	On	16	Arc decel.
U	0.0000					V 0.0000	Off	8	Run M01
v	0.0000		(The Length of Path(mm)	405	14	Pos
w	0 0000					42.200 Cutting Taner(Degree)	AON		Fly Cut
vv	0.0000		l				AOff	10	Don't wait gap
• R	kel 🔿 Abs 🔿 Mac					Wire compensation(mm)	WT	8	Mac locked
	Strt OBrk OG92					U CEOL(Laide), CEOL(Outside	WF	11	Paral, comp.
	Set Coor.		/				WR	3	
Disc	. Status					G503 G505	SV	30	Start Break Point Point
P.scl							50	190	
Gap	Volt.(V) 0.00					Color of XY Plane	FS	2	G92 Restart
	un han ja al han han h				Ĩ	G00 Color	Feed	4.5	
5 -50	0 -25 0 25 50 ;	7				Color Setting	F.D%	140 %	« wire
50	L 65 H		Step 7:Dr	aw simulated graph(C	ompleted)		C.Len	0.5	Water
		Backgrnd St SIMU Dra	ep CONT aw Draw	Overlook Graph Full Grap	h SIMU Cutting	Error PARAM Messages Setting	Save	paramete	er EDM
5 20	Idle	GM Code Edit Prog.	GM Code		ram. Smart	Func. Cut Record	F	eed lold	Cycle Start
G	ap Break Para rvo Limit Spec	l. Pitch Prot. 2 . Orth. Lmt.2	Z Vert. ST. Pt E.Stop Brk Pt.	Work Run Short F.Hold	Fail to connect M (2013/4/26 09:51	10TION USB (:01)			Reset Feed Hold

(2) Press 《Save Parameter》 the adjust machining condition can be saved.

J Hint

* If 《 Save Parameter 》 does not be selected after the setup , the condition will reset.





(3) Select 《Z Uprise》, Z axis will rise to a certain height.

J Hint

*Z Ascend function should be used while EDMing is stop.

* When to use Z Ascend Function :

①EDMing complete and workpiece should be removed.

^②When wire is broken and need to pull Z axis up for wiring.

③Exam the Machining is correct



13. Machining

(4) Press $\langle\!\!\langle Edit\,Prog.\,\rangle\!\!\rangle$, NC program will appear on the screen.

[W USB	Η	USB	IV	USI	3	16:30	205
	Coordinate	Manual	Machining	Message	Syster	n	Manual	Auto	l Au	102 Kej	yPad	Tool
X 0.0000	Editing 00001 00100						A	в	с	D	Е	F
Y 0.0000	00002 N100 GC 00003 N102 GS) G21 G90 92 XO. YO. I100	. JO.				G			H		Ţ
Z 0.0000	00004 N110 S1 00005 N112 G4	.01 D1 £1 G1 X6.										
U 0.0000	00006 N114 G3 00007 N116 X6	X-6. I-6. 5. I6.					м			P	$ \bigcirc $	R
V 0.0000	00008 N118 X5 00009 N120 G4	.9792 Y.4994 I 10 G1 X2.9896 Y	-6. .2497				S	Т	U	V	W	X
W 0.0000	00010 N124 M3	.0					Y	Z	Ŧ	+		? /
⊙ Rel ○ Abs ○ Mac							{	}	÷	и ,		>
○ Strt ○ Brk ○ G92								0	#	\$	%	Â
Set Coor.							&	*	Ľ.			-
Disc. Status Total							-	<u> 8</u>	9			
P.scl												n
								Ctrl		En	iter	
5 -50 -25 0 25 50 ;				10			Cap	s Lock	\mathcal{D}			
Deion(K ohm)	File name: 122(8001 NC			R	NS	7					Daillia
	Open Sa	ve/ Create	DC 000 Searc	h Undo	Redo Retn	Main		Ļ	<u> </u>	H		-yop
1111 1111 1111 1111 1111 1111 1 -20 -10 0 10 20 3	File Del	iete New File	RS-232 text	modify	modify Pr	og.	4	5	6	Ŀ	End	^p gDn
	GM Code	GM Code					1	2	3	*	Ente	or
Idle (Edit Prog.	imulation C	utting Cut F	Param. Smart	Func. Cut Re	cord		0				
Gap Break Para	al. Pitch Prot.	Z Vert. ST. Pt	Work Run	Fail to connect	HARD KEY USP						Fe	ed
Servo Limit Spe	c. Orth. Lmt.2	E.Stop Brk Pt.	Short F.Hold	(2013/4/24 08:1	19:26)				R	eset	Hc	old

J Hint

On 《Program Display》, make sure the program is executed from the first line. If not, press **Ctrl**+**Home** to reset the program.



4 Machining Finish

Remove the workpiece when the machining is done.

(1) Open drain valve, drain the water in work tank. (for submergible type WEDM only)





! Note

While moving the XY table, please double check the moving direction. Moving in the wrong direction might damage the lower guide. Please adjust the feed rate to minimum speed.

 $\begin{array}{l} \left\langle JOG \right\rangle \quad \left\langle LOW \times 1 \right\rangle \\ \left\langle +X \right\rangle \quad \left\langle -X \right\rangle \\ \left\langle +Y \right\rangle \quad \left\langle -Y \right\rangle \end{array}$



15 Finish Workpiece Checking

Check the Finished Parts. Via the status of workpiece to make sure the machining procedure is correct.

(1) Check the surface to see if the cutting is correct and the surface is very smooth.



If there is some yellow dirt on the upper edge of workpiece, it should be the copper powder.

If there are curved marks on the surface, operator should check very careful and find out the reason.



If the curved marks are shown on the surface evenly \rightarrow check the rollers for wire feeding is working smoothly.

If the curved marks are shown unevenly

- → *Flush head or other parts touch the workpiece.
 - * There are some dirt or other compounds in the workpiece

J Hint

Copper Ionized

Copper Ionized situation will be appeared during EDMing when the conductivity of working fluid is too high. The more difficulty EDMing, the more cooper ionized created. If the surface is too smooth, it will be difficult to cause the EDMing . Therefore, the copper ionized situation is appeared on the upper section of workpiece while EDMing with new copper



(2) Measure the finished parts.

Check the sizes of finished parts.



If the center section is thicker or thinner than the edges, it means The wire tension is too low. Use Tension Meter to check wire tension. Check is there any differences between actual value and Data on the screen.

Because the copper debris will accumulate on the upper and lower section of finish parts, use millstone to grind the finished parts before measure it.



J Hint


16 Clean Up Machine Parts

After processing, clean all machine parts immediately. Its easiest and most effective to clean the parts when processing liquid is remains wet.





17 Shut Down

- (1) Press the red (EMEGY STOP) button which located at the left side of the monitor.
- (2) Press the red OFF button, (at the right of the EMEGY STOP) Monitor will be off.



- (3) If the machine has chiller installed, please also power off the chiller.
- (4) Shut down the main power.

Turn the Main Power Switch to OFF position.



Switch to off position



V. Application Operation



1 Perpendicularity Alignment





The method of vertical adjustment is used for workpieces with 3 smooth and perpendicular sides. It utilizes the weak sparks between the cutting wire and workpiece for vertical adjustment. This method can also be used for one side vertical adjustment.

There are 2 methods to use Perpendicularity Rectifier to align:

- 1. Perpendicular Rectifier
- Choose a precision 3- sides- perpendicular workpiece for side spark.

1.1 Perpendicularity Rectifier

adjustment.

There are 2 methods to use Perpendicularity Rectifier to align: Manual or Auto

When the cutting wire touch the detection rims, the respective signal lights would light up. When both of the signals are active, the cutting wire can be considered as perpendicular.
 * The installation procedure of perpendicular rectifier applies to both manual and auto

*Perpendicularity Rectifier install procedure.



^② Grind the machine table with millstone and wipe it clean with a damp cloth is necessary.





1. Vertical Alignment

! Note

The correct adjustment cannot be done if the moist remains and affects the signal lights from function properly.

③ Perpendicularity Rectifier



Tighten both clamping apparatus till there is no movement with hand push.

Because the Perpendicularity Rectifier is very fragile, please handle with care. Perpendicularity Rectifier can slant out of balance if it is only secured on one point. If 《D. POS》 is ON during alignment, the rectifier can be damaged easily.

⁽⁴⁾Pass cutting wire through upper and lower machine heads.



! Note



S Wire Tension and Feed rate is base on the diameter of cutting wire

Wire Diameter	Wire Tension	Feedrate
0.10 mm	5 (aprox.400g)	5
0.20 mm	9 (aprox.1300g)	5
0.25 mm	13 (aprox.2000g)	5
0.30 mm	15 (aprox.200g)	5

© Move XY table till cutting wire close to the detection-end of Vertical Alignment Jig.



 Dower the upper wire guide and close to Perpendicularity Rectifier





Sonnect one end of cable to the perpendicularity rectifier. Connect the other end to upper machine head.





1.1.1 Use Perpendicular rectifier for alignment

- (1) Complete Perpendicularity Rectifier installation.
- (2) Press [Manual] key to enter 《Vert. Adjust》





					W USB H	USB M	0:55:01 asu
· · · · · · · · · · · · · · · · · · ·	Coordinate	Manual	Machining	Message	System	Manual Auto1	Auto2 KeyPad Tool
X 0.0000 Y 0.0000 Z 0.0000 U 0.0000 V 0.0000 W 0.0000 © Rel Abs Mac Stat Bak G92 Set Coor. Disc. Status Total	Vertical Adjustment	Slow Speed 1 UV moving length(mm) 10	Ve XY Axis Direction • Y+ X- • X+ • Y- Final Speed 0.05 Wire Diameter 0.25	rt. adjustment Msg Cutting Wire Setting 0. WT 10 WF 3 Moving Speed 400 Upper guide height(run) 55.001	00 V Wire ✓ Search height Lower guide height(man) 5.002	Cutting PARAM No 53 DM 2 On 16 Off 8 AOn 14 AOff 10 VVT 8 VVF 11 VVR 3 SV 30	Function G95 Block cutting Corner decel. Arc decel. Run M01 Pos Fly Cut Don't wait gap Dry Run Mac. locked Paral. comp. Start Point Break Point
Gap Volt.(V) 0.00 5 -50 -25 0 25 50 ; Deton(K.ohm) 50 L 65 H 0 -20 -10 0 10 20 ;	Sa Vertical	ve Position	Stor Adjustn	hent A	Start djustment	FS 2 Feed 45 F.D% 140 C.Len 0.5 Save parame	G92 Restart Wire Water EDM
Idle	PARAL. Coor COMP. Table	g Finding MDI	Arc Out Circ Center Center Original Pitch Path COMP	Center Orth. COMP.	Polar Correct) Feed Hold	l Cycle I Start
Gap Break Paral Servo Limit Spec	. Pitch Prot. Z . Orth. Lmt.Z	Vert. ST. P E.Stop Brk P	t Work Run t. Short F.Hold	Fail to connect M ⁽ (2013/4/26 09:51:	DTION USB		Reset Feed Hold

(3) Click $\langle\!\langle Vert. Adjust \rangle\!\rangle$ to enter the function.

A. XY axis direction mode:

There are 4 types of mode: X+Y+ \smallsetminus X+Y- \checkmark X-Y+ \checkmark X-Y- \circ

- B. Adjust Wire Tension and Wire Speed.
- C. Height of machine head

Click" Search height When running the perpendicularity alignment process, the computer system will update and show the height of upper and lower machine head Cancel" Search height When running the perpendicularity alignment process, the computer system will only show the vertical height of XY axis.

D. Setup Speed : Unit: mm/min Reference to11.1(3)



E. U \cdot V axes movement

The max offset distance between $U \cdot V$ axes. When the value is over the limit, there will be an alert message and the operation will pause.

F. Diameter

Diameter of the wire will affect the height of upper and lower machine head. If replace different diameter during the perpendicularity alignment, parameter needs to be changed in order to get the same upper and lower machine head's height.

G. Height of upper and lower Jig

The distance between the Work table and upper and lower measurement point of the perpendicularity rectifier.

To get the correct height of upper and lower machine head during the perpendicularity alignment process, input the location parameter of upper and lower measurement point every time when using different perpendicularity rectifier.

1.1.2 Manual Alignment

Align X and U direction first

(1) Follow the procedures description above to complete

Vertical Alignment jig installation

(2)Press 《WIRE》 key, select 《INC_JOG》 mode and set jog rate to 《MED×10》.

《WIRE》

《INC_JOG》 《MED×10》

(3) Press 《 -X》 couple times till cutting wire close to detection edge, the respective signal lights on the perpendicularity rectifier will light up. When either of the signal lights up, press 《 +X》 to move cutting wire away from the detection edge. Press and hold 《 +X》 until the signal light off.





(5) Press 《-X》 so that cutting wire close to detection edge.
When both signals light up, set the jog speed to 《LOW×1》
Then go back to step (3)
If only one signal light is on, back to step (2)





$\langle\!\!\langle -X \rangle\!\!\rangle$

When both signals light up, set the jog speed to $(LOW \times 1)$. Then go back to step (3). If one of the light is on, repeat step (2).

- (6) Set jog speed to $(LOW \times 1)$ (unit: μ) and have cutting wire close to detection edge. When both vertical setup signals light up, the perpendicular adjustment is completed.
- (7) Vertical Coordinate Data Saving
 - After vertical Alignment is complete, the Vertical coordinate data has to be saved in to CNC controller. Press Vertical Coordinate Data Saving under Perpendicularity Alignment.
- (8) After the X and U axis is completed, follow the same procedures with Y and V direction.



1.2 Alignment by side burn on workpiece

The method of vertical adjustment is used for workpieces with 3 smooth and perpendicular sides. It utilizes the weak sparks between the cutting wire and workpiece for vertical adjustment. This method can also be used for one side vertical adjustment.

! Note

This method cannot be used for automatic Perpendicularity Rectifier.

(1) Prepare a workpiece with more then 3 surfaces. The plane level and verticality should have a fair precision around($3to5\mu m$).



(2) Blow dry moisture on machine head and table surface with an air gun.



! Note

If water or moisture exists, the discharge would appear on the damp parts and adjustment would not be precise.

(3) With a millstone, smooth the table surface where the perpendicular rectifier has to be installed.



The wipe it clean with a non- shedding cloth.



(4) Set up the workpiece according to the following diagram in order to perform rectification. Please check that side C is the base, A is the front and B is the right side.



DM	FINE1
ON TIME	1
OFF TIME	50
ARC ON TIME	1
ARC OFF TIME	52
Servo Voltage	28
Wire Tension (Refer t	to the table on
the right)	
Feed rate	5
Water Pressure ((): close the
adjustment valve)	

Wire 7	ension
0.10 mm	5 (400g)
0.20 mm	9 (1300g)
0.25 mm	11 (1700g)
0.30 mm	13 (2200g)



J Hint

Set the water pressure equal to 0, close water valve. Make sure there is no water comes out from upper and lower head.

(7) Set $\langle D.POS \rangle$ to ON.

《D.POS》

(8) Set $\langle\!\!\langle WIRE \rangle\!\!\rangle$, $\langle\!\!\langle WATER \rangle\!\!\rangle$ and $\langle\!\!\langle S.EDGE \rangle\!\!\rangle$ to ON

《WIRE》 《WATER》 《S.EDGE》

⊠ Danger

Cutting wire contains high voltage at this point. Do not touch copper wire or risk the danger of an electric shock.

(9) Set jog speed 《INC_JOG》 and 《MED×10》, press 《-X》 to move copper wire to workpiece and a weak discharge will pass through the wire.

Examine discharge situation.



 $(INC_JOG) (MED \times 10) (-X)$

(10) Adjust U- Shaft for an even discharge.

Adjust Y- Shaft and V- Shaft according to the same method.

(11) Set up perpendicular position

🖋 Hint

After perpendicular adjustment is finished, save into CNC. Once the data is saved, press 《VERT》 under 《JOG》 or 《INC_JOG》 mode, move alone U and V Shaft and can back to perpendicular position.



1.3 Manual Vertical Alignment

(1) Set the Wire close to the rectifier.



(2) Press 《FUN》 key on the remote control, the light on 《FUN》 key will light up.



(3) Press 《MODE》 on the remote control, 【Manual】 mode will appear on the monitor. Press 《MODE》 again, and select 《Perpendicular Alignment》



- (4) Check the setup speed, wire and other parameters.
- (5) Press 《START》 to start Edge Find.



(6) Press 《HOLD》 on the remote control to stop.





Calculation of Workpiece Tilt.











Parallel compensation can determine the tilt of the installing workpiece, indicator do not need to be used.

Base on the figure, P1 is fixed. By moving P2 up and down can determine the tilt of the workpiece.

2.1 Operation of Parallel Compensation

(1) Install the workpiece on the work table, and then adjust the parallel tilt.





(2) Press [JOG], and set the cutting wire to base plane.



(3) Press 《PARAL. COMP.》 under 【Manual】

JSEDM						W US	вН	USB	MUSE	3	:35:32
	Coordinate	Manual	Mach	ining	Message	S	/stem	Manual A	auto1 Auto	o2 KeyPa	id Tool
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Servo Limit Spe	c. Orth. Lmt.Z	E.Stop Brk I	Pt. Short	F.Hold	10, 1122 -00,27						noiu





(4) Press $\langle\!\!\langle PARAL. COMP. \rangle\!\!\rangle$ to enter the function.



! Note

(5) Press $\langle\!\!\langle XY | Axis | Airection \rangle\!\!\rangle$, to setup the direction where the cutting wire is closed to the workpiece. EX: Set Y direction as Y+.



- (9) When the two coordinates are saved, the angle of the two points will be determined.
- (10) After angle calculation is completed, press 《Set & Cancel Compensation》 to turn on/ off the parallel compensation.







2.2 Parallel Compensation on the remote control

(1) Set cutting wire close to workpiece.



(2) Press 《FUN》 on the remote control , 《FUN》 key will light up.



(3) Press 《MODE》 on the remote control, 【Manual】 mode will display on the screen. Press 《MODE》 to enter 《PARAL. COMP.》 screen.



(4) Press $\langle\!\!\langle +X \rangle\!\!\rangle \langle\!\!\langle -Y \rangle\!\!\rangle \langle\!\!\langle -X \rangle\!\!\rangle \langle\!\!\langle +Y \rangle\!\!\rangle$ keys to select the direction of XY on the screen.





(5)Check the setup working wire, speed and other parameters.

(6) Press $\langle\!\!\langle START \rangle\!\!\rangle$ on the remote control to start Edge Find.



(7) Press 《HOLD》 on the remote control to stop.



3 Return to machine Origin





3.1 Follow the shortest path return Machining start Cutting Point

- (1) 4 ways to return starting point:
 - A. [Manual] Mode : Press S.PT RETN
 - B. [Auto1] Mode: Press Start point
 - C. [Auto2] Mode : Press Start point
 - D. Press S.TP RETN on the remote control.

(2)Press (S.PT RETN). Cutting wire will return to original point following by the shortest path.

Machining Start Cutting point
«S.PT RETN»

J Hint

This method can be considered as a"Fast Return Machine Origin"

3.2 Follow the original path return Machining Start Point

This function is used on Machining Start Point when machining is interrupted.

! Note

If this function is not used on Machining Stop Point (broken wire point), the alarm would be ON and the cutting wire won't be back to Machine origin Point.

- (1) There are 3 type of original path return to Machining Start Cutting point.
 - A. [Manual] Mode : Select ORG.S.PT •
 - B. [Auto2] Mode : Select Org. Path return Start Pt.
 - C. Press ORG.S.PT on the remote control



(2) Set $\langle \langle WIRE \rangle \rangle$ (during the threading) to ON.

«WIRE»

 $\langle\!\!\langle EDM \rangle\!\!\rangle$ or $\langle\!\!\langle WATER \rangle\!\!\rangle$ cannot be ON.

(2) Press (ORG.S.PT) and press OK to start Reset Machining.
 At this point, the cut wire will return to the machining start point alone the current machining path and "Original path]
 return to the cutting point" will appear on the screen.

Org, I	Path Start Pt.(MSG)	
	Machine is cutting, please press "Reset" key to stop cutting.	
	OK	

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W 0.0000 Cutting Taper(Degree) AOff 10 Don't wait a • Rel Abs Mac Dry Run Wire compensation(mm) VVT B Dry Run • Stat Brk 692 0 VVF 11 Paral. comp • Disc. Status 0 0 VVR 3 Start Bre • Point Point 0 0 SV 30 Start Point	Pos Film Crat	AOn 14	The Length of Path(mm) 42.286					0.0000	V
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Backgrnd Step CONT Overlook Full Graph SIMU Error PARAM Setting Messages Setting EDM	EDM	Save parameter	Error PARAM Messages Setting	ph SIMU Cutting	Overlook Graph Full Gra	Step CONT Draw Draw	Backgrnd S SIMU D		
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Machine is executed Start		executed Sta	Machine is e						
Point Return function		function	Point Return						



3. Return to Machine origin

《ORG.S.PT》

	Machining stop point	
	Machining Start Cutting point	
! Note	If the cutting wire has to retra corner, the cutting wire migh	act follow by the path with sharp t be broken on that area.
	Broken Wire point	To prevent broken wire, lower Feedrate or Feed% can be used.
Prope		







CNC will save the position of broken wire or (HOLD) position. By pressing (H.PT RETN) can move the cutting wire back to position for continuing machining.

4.1 Follow the shortest path return Machining Broken Wire Point

- (1) 4 ways to return broken wire point:
 - A. [Manual] Mode : Press H.PT RETN
 - B. [Auto1] Mode : Press Break Point
 - C. [Auto2] Mode : Press Break Point
 - D. Press H.TP RETN on the remote control
- (2) Press 《H.PT RETN》 Cutting wire will return to broken wire position following by the shortest path.





4.2 Follow the original path return to broken wire

The function is used for retract to broken wire point.

! Note

If this function is not used on Machining start point, the alarm will be on and the cutting wire won't retract to broken wire

- (1) Follow the original path return to original point.
 - A. [Manual] Mode : Press ORG.H.PT
 - B. [Auto2] Mode : Press Org. Path Break Pt. .
 - C. Press ORG.H.PT on the remote control

(2) After wire feeding, press $\langle\!\langle WIRE \rangle\!\rangle$ to wind the wire.

《WIRE》

(3) Press 《ORG.S.PT》 and press OK to start Reset Machining. At this point, the cut wire will return to the machining start point alone the current machining path and "Original path return to the broken wire point" will appear on the screen.

Org. P	ath Start Pt.(MSG)	×
1	Machine is cutting, please press "Reset" key to stop cutting.	
	OK	



4. Broken wire Retract







4. Broken wire Retract



! Note

Once the cutting wire is back to broken wire follow by the current path, press 《RESTART》 after 《WIRE》 《WATER》 《EDM POWER》 to continue machining.



6

Short Circuit

If the short circuit is appeared while machining, the cutting wire will retract alone the working path till the short circuit problem is solved.

This function has to be executed under [Auto1] mode.

The procedures are shown as below

(1) Set $\langle POS \rangle$ to ON.



(2) Press 《WIRE》 《WATER》 《EDM》.



(3) Press 《START》.



(4) if the cutting wire touch the workpiece while EDMing, the light of short circuit will be on and the cutting wire will stop moving.



J Hint

This function can be worked with $\langle DRY RUN \rangle$ in order to increase moving speed and prevent wire broken due to the fast






Vertical Machining Won't move alone U and V axis.

For Taper cut, tilt the cutting wire by moving U axis and V axis and make the upper and lower guide are not on the vertical line.

There are 2 types of assigned taper cut :

One is assigned angle for taper cut.

The other is assigned upper and lower graphic fro taper cut. Please refer to **Section 4.9** for more details.



7.1 Taper Cut Setting

The distance between upper and lower guide and the thickness of workpiece has to set before taper cut.

7.1.1 Setup the height for lower flush guide

(1) Preparation:



Wire Guide specification table enclosed in machine tool box. (red box).

The specification should come with the new wire guide when you cotton cloth to wipe the surface.

(2) Clean the work table.

Grind the work table with millstone. Use clean soft cotton cloth to wipe the surface.





(3) Remove the lower flush cap.



(4) Move the machine head to the corner machine table.



(5) Use depth meter to check the distance between work table and lower wire guide.



In this example, the distance is 9.483



(6) Add the distance to the "A=" in wire guide specification table and save this value to the lower wire guide value in parameter setting screen
Depth (9.483) + "A=" (1.06) =10.543

* Usually the lower guide space in "parameter Setting" is measured and saved by perpendicularity rectifier. After the alignment by rectifier, the lower guide value needn't be changed.

* The lower guide space cannot be change under

"Parameter Setting" I only can be changed under Diagnosis Screen.

The procedures to change the setting of "Simulation". ① Click 《Simulation》 under 【Machining】

Γ					WUSS H	USB	M	USE	3	14:0	9:37
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	Servo Limit Spec	c. Orth. Lmt.Z E.St	op Brk Pt. Short F.	Hold (2013/4/23 08:12:3	6)			R	eset	H	lold

! Note



7. Taper Cutting



②Enter the 《Program simulation》 screen.

Password:"JsGuid"

M Hint

Restart the system is not necessary after changing the "Parameter Setting".



7.1.2 Setup the height for upper flush guide

(1) Preparation



(3) Remove upper flush cap

Remove the upper flush cap and other parts except wire guide.





(4) Move the upper machine head above the work table and put the gauge block on worktable.



(5) Move the upper wire guide close to gauge block. While the wire guide is as close as 1 mm to the gauge block, press $\langle\!\langle \times 1 \rangle\!\rangle$ and reduce the moving speed to minimum. Keep moving the wire guide till it touches the gauge block. The gauge block should not be moved now. Press $\langle\!\langle INC_JOG \rangle\!\rangle$ key and press $\langle\!\langle Z+\rangle\!\rangle$ key 1 or







(6) Add the height of gauge block to the "A=" in wire guide specification table. And save it to the "Parameter Setting". Gauge Block (10.00) + A (1.9) = 11.900 (Actual value of upper wire guide)

Input 11.900 to "Parameter Setting" screen in upper guide column.



J Hint

Restart the system is not necessary after changing the "Parameter Setting".

! Note

* Prevent using fast speed while moving the upper guide towards the gauge block. Otherwise it will damage the upper machine head.



7.1.3 Setup Taper Cut Mode

There are 3 taper cutting modes fro selection:

- Mode 0 : Vertical Cut. No taper cut in this mode. G51 and G52 is skipped in program.
- Mode 1 : Taper A. Cut the taper base on the taper angle input.
- Mode 2 : Taper B. Assign the upper and lower graphic in program and cut the workpiece.

7.1.4 Program plan and workpiece thickness setting

Position of program plan:

Set up the graphic position produced by taper cut.

Program plan is the same as the graphic produced by the

Vertical Cut.

Thickness of workpiece :

Set up the position on the opposite of Program Plan.

When the opposite side of surface is higher than the Program

Plan, do not add symbol in front of the thickness of workpiece.

Otherwise, add the symbol (-) in front of the thickness of workpiece thickness.

* Following is the explanation of program plan and workpiece thickness.

(1) When the program plan is on the bottom of workpiece (Same as work table),

Program Plan Position=0.000 (Work Table)





(2) When the program plan is on the top of the workpiece, Program Plan Position=20.000 (Top of workpiece) Workpiece thickness=-20.000





7.2 Taper Angle Compensation

In order to get the best setting, test cut is necessary for high precision taper cut.

The ideal method is to do the test cut on the actual cutting area. If there is no extra section in the workpiece for test cut, use the same material and thickness instead.



7.2.1 Example of test cut

Thickness of workpiece: 20 mm

Cutting taper: 10°

(1) Graphic generated by taper cut.



(2) Generate graphic program

G92 X0. Y0.	
G91 G94 F1.5	
G01 Y5.	
G52 X10. T10.	
Y10.	
G50 X-10.	
G52 X-10. T10.	
Y-10.	
G50 X10.	
Y-5.	
M02	



7. Taper Cutting



(3) Setup taper cut in "Parameter Setting" screen



7.2.2 Test the result- dimension of workpiece

(1) Test the program setup plan, A and B dimension.



Because the distance of Center- to- Center is 100mm, please use 34.20mm gauge block to make 20 degree tilting surface. $(100 \times \sin 20^{\circ} = 34.20)^{\circ}$

Use a pencil to make the mark on the measure area. The length of mark is base on the taper and the thickness of workpiee.





As shown above, move the test indicator with magnetic base back and forth. Read the number from test indicator. If the needle is not moving, it means finish taper size is accurate.

If the needle is shaking, check the needle moving direction while moving the test indicator on order to check the taper angle is larger or small than the desired angle.

If the indicator moved to the left and needle is rotated on counter clockwise direction, or while the indicator moved to the right and the needle is moved on clockwise direction, it means the taper angle is smaller than the desired setting.

On the other hand, the taper angle is larger than the desired setting.

Example

When the taper angle is less than the assigned value, indicator moves 20mm and the needle moves 0.155mm

Angle Shiftδθ	
0.155 mm	
20.0 mm	
$\delta \theta = \operatorname{Tan}^{-1} \underline{0 \cdot 155} = 0 \cdot 4 \cdot 4 \cdot 4 \cdot 4 \cdot 0 \cdot 5^{\circ}$	
2 0	

Т

Total Taper angle is 20 Each angle shift is: $0.44403 \div 2 = 0.22202$ Actual Taper angle is: $10 - 0.22202 = 9.77797^{\circ}$





Test Result: Taper Angle : 9.77797° Dimension A : 9.762 mm Dimension B : 19.801 mm

7.2.3 Calculation the compensation via test result

The error of taper angle can be corrected by the compensation of the distance on upper and lower guide.

The compensation value γ of upper and lower guide is :

$$\gamma = \frac{F}{2} \left(1 - \frac{\tan \theta}{\tan \theta} \right)$$

F: The distance between upper and lower guide.

"Parameter Setting" The sum of these 2 numbers is:

①Upper guide

②Lower guide

F = O + O = 26.089 + 2.018 = 34.107

 θ : Taper angle assigned in program

 θ ': Actual taper angle

In this example, the compensation value is :

F=34.107 ,
$$\theta = 10$$
 , $\theta' = 9.7797$
 $\gamma = \frac{34.107}{2} \left(1 - \frac{\tan 10}{\tan 9.77798} \right) = -0.3951$

Value of Upper guide (Undated value) : (value of upper guide) $-(\gamma)=26.089-(-0.3951)=26.4841$ Value of Lower guide (Undated value) : (value of lower guide) $-(\gamma)=8.018-(-0.3951)=8.4131$



Re- test cut with the new setting. For the new test result, the taper angle should be more accurate.

The compensation values on A and B dimension might be different



If the compensation values are different, the values for vertical parts and taper parts should be set separately. It will make the program more complicated.

The situation is happened if the related position of upper and lower guide is correct but is shifted up or down.

Dimension A Compensation $(10-9.742) \div 2=0.129$

Dimension B Compensation $(20-19.815) \div 2=0.0925$

The difference between compensation values is due to the vertical position error on upper and lower wire guide.

Assume the dimension A compensation value is a and dimension B compensation value is b.

When a-b>0, position is shifted down.

When a-b < 0, position is shifted up.

When a-b=0, position is correct.

If the large taper angle is used, the error is occurred (Compensation Value) /cos



* When wire guide point is located on assigned position a-b=0







If a-b>0, it means the wire guide position is lower than the assigned position.

 \rightarrow The moving distance on upper guide is larger than the assigned distance.

Have the assigned point closed to the actual point. Re- assign the position of upper and lower guide lower than the setting in "Parameter Setting" \rightarrow The movement of upper wire guide decressed.



If a-b < 0, the wire guide position is higher than the assigned position.

 \rightarrow The moving distance of upper guide is smaller than the assigned distance.

 $\mathbf{\Lambda}$

Have the assigned point closed to the actual point. Re- assign the position of upper and lower guide higher than the setting in "Parameter Setting"

 \rightarrow The movement of the upper wire guide increased.





The compensation value D calculated above is the new value for upper and lower wire guide.

* If the position of wire guide is lower than the assigned position (a-b>0), re-assign the new position lower than the assigned position.

Value of upper wire guide (new) : (Original value of upper wire guide) -D=26.4841-0.2070=26.2771

Value of lower wire guide (new) : (Original value of lower wire guide) +D=8.4131+0.2070=8.6201

* If the position of wire guide is higher than the assigned position. (a-b<0), re-assign the position higher than the assigned position.

Value of upper wire guide (new) :

(Original value of upper wire guide) +D=26.4841+0.2070=26.6911Value of lower wire guide (new) :

(Original value of lower wire guide) -D=8.4131-0.2070=8.2061



7.3 Things to be careful while taper cut

7.3.1 EDM DATA setup

Taper cut is different from Vertical cut. Even through the thickness of workpiece is the same, the EDM Data is different.



When the wire taper is increased, the cutting wire will break more easily. The larger flush cup will reduce the water pressure too.

The EDM DATA for taper cut is shown as below(compare with Vertical Cut) \therefore

ON TIME : $-2 \sim -3$ OFF TIME : $+3 \sim +4$ ARC ON TIME : $-2 \sim -3$ ARC OFF TIME : $+3 \sim +4$ Servo Voltage : $+5 \sim +7$ Wire Tension : $-1 \sim -3$ Wire Feed Rate : No change Water Pressure : No change * The EDM DATA shown above is base on the rough cut for taper machining. * The EDM DATA for taper skim cut is the same as vertical skim cut



7.3.2 Upper and lower flush head selection

For large taper angle, the wire touches the edge of flush head(15°



Even though the tapper angle (15°) is assigned in program, the angle will be more than 15° in corner cut area. Hence, check the actual taper angle in Dry Run.



Even the assigned taper angle $is15^{\circ}$, the actual angle in 90° corner will exceed 20°. Large taper flush head is recommended in this application.

When using 4 mm flushing head, there will be a limit during the cutting taper process.

Standard Model: 11°

! Note



7.3.3 Maximum Taper Angle

The thicker workpiece has, the less Taper angle workable. Following table is maximum taper angle base on the gap= 0.2mm between flush head and workpiece. If the gap is increased, the workable taper angle is decrease.

Following is the relationship between thickness of workpiece and workable taper angle:

Thickness of	Taper angle	Thickness of	Taper angle
workpiece		workpiece	
80 mm or lower	$\pm 30^{\circ}$	200 mm	$\pm 14^{\circ}$
100 mm	$\pm 25^{\circ}$	250 mm	$\pm 12^{\circ}$
120 mm	$\pm 20^{\circ}$	300 mm	$\pm 10^{\circ}$
150 mm	$\pm 18^{\circ}$		



7.3.4 Things to be careful to restore broken wire while taper cut

It's difficult to thread the wire during taper cut. It's necessary to thread the wire in start point.

DO NOT press $\langle\!\!\langle VERT \rangle\!\!\rangle$ while machine is back to start point.



Use "Retract back to start point alone the working path" method to move the upper and lower machine head back to starting point. Feed the wire then press 《WIRE》 to wind the cutting wire. 《WIRE》, 《WATER》, 《EDM》 and then press 《RESTART》. When NC program is executed to broken wire point, the light on 《RESTART》 key will be off. Press 《START》 to start machining.

When wire is broken during taper cut, press 《ORG.S.PT》 under 【Auto】 mode and move the upper and lower machine head back to start point.



Feed the cutting wire then press $\langle\!\!\langle WIRE \rangle\!\!\rangle$ key to wind the wire. Then press $\langle\!\!\langle ORG.H.PT \rangle\!\!\rangle$.



Press 《WIRE》 《WATER》 《EDM》 when cutting wire retract back to broken wire



Press 《RESTART》 to restart





8

Skim Cut

8.1 Principle of Skim Cut

When the cutting speed is increased, the cutting accuracy and surface finish is reduced. For a better cutting accuracy and surface finish, cutting speed should be lowered. For the first cut, workpiece cannot reach the accuracy of 10µm

or 1µm Ra surface finish.

After the rough cut, couple times of skim cut is necessary in order to get a better finish result.



* The value of ON TIME will affect the cutting accuracy and surface finish. The material and thickness of workpiece and wire diameter will also effect the result.



8.2 Procedures of Skim Cut

Besides reducing ON TIME, Wire tension, Water pressure and Servo Voltage are also the factors which affect the accuracy and roughness during the skim cut.

There is small compensation value on the cutting path for 1st slim cut. It's a little bit increment on the cutting depth. The cutting paths of skim cuts (from 1st to 4th cut) is shown as Follow.



! Note

EDMing with the EDM DATA is provided by the CNC controller. For high accuracy workpiece, test burn is recommended.

8.3 Specifications of EDM DATA

* Servo Voltage (SV)

Servo Voltage will effect the feed rate.

The accuracy of Verticality can be changed by FEED Rate (Adjusted by Servo Voltage). Shown as below:





* ON TIME

ON TIME will change the surface roughness a lot. Decrease the ON TIME for more Skim Cuts.



- Example :
- 1^{st} cut : ON TIME = 15~17 2^{nd} cut : ON TIME = 6~8 3^{rd} cut : ON TIME = 3~5 4^{th} cut : ON TIME = 2
- * Wire Tension (WT)

Wire tension will effects the accuracy of Corner Cut. Set the wire tension higher than the setting in 1st cut.







8.4 Program for Skim Cut

During the skim cut, the machine will cut the workpiece with the same cutting graphic.

(Example 1) Main program (Skim Cut: 4 times, final cut off; 1 time) [Main Program] O9930 (Main Program) : →Feed Rate Setting G94F1.5; S1D0; \rightarrow Call EDM S- Code #1 and compensation D#0 M98P9931; \rightarrow Call Program number 9931. \rightarrow Call EDM S- Code #2 and compensation D#1 S2D1F1.2; →Call Program number 9931 M98P9931; \rightarrow Call EDM S- Code #3 and compensation D#2 S3D2F1.2; M98P9931; →Call Program number 9931 \rightarrow Call EDM S- Code #4 and compensation D#3 S4D3F1.2; M98P9931; →Call Program number 9931 ∘ S1D4F1.5; \rightarrow Call EDM S- Code #1 and compensation D#4 M98P9932; →Call Program number 9932 • \rightarrow END Program M02; Graph Program O9931 (Sub program 1) G92X0.Y0. G42 G91 G01 Y5.: X5.; Y10.; X-10.; Y-10.; X2.5; Y-1.; \rightarrow Retract (Cutting wire retract to start) F0.2M70; →End Sub Program M99; 10 \bigcirc Start Point



 $\begin{bmatrix} Cut off Program \end{bmatrix}$ O9932 (Sub program 2) : G92X0.Y0.; -G41 G91 G01 Y5.; X-2.5; Y-0.5 M99 → Sub Program END

► Input G41 for a compensation D during cut off process.



(Example 2) Start hole is inside the Final parts

If the start hole is inside the final parts, the waste parts will fall down during the first cut. Use M00 command to stop the machine in order to remove the waste parts. Same procedure has to be done for the 2^{nd} and others cuts.

[Main Program]

O9940 (Main Program) :

G94F1.5; S0D0;	 →Feed Rate Setting → Call EDM S- Code #1 and compensation D#0
M98P9941;	→Call program number 9941
<u>M00;</u>	→Hold
S2D1F1.2;	\rightarrow Call EDM S- Code #2 and compensation D#1
M98P9941; S3D2F1.2;	 →Call program number 9941 → Call EDM S- Code #3 and compensation D#2
M98P9941; S4D3F1.2;	 →Call program number 9941 → Call EDM S- Code #4 and compensation D#3
M98P9941;	→Call program number9941
M02;	→Program End

— Hold the machine and remove the waste material.



(Example 3) For Taper Cut Program

For taper and Vertical cutting, the cutting program should be changed to Taper and Vertical mode.

[Main Program]

O9950 (Main Program) :

G94F1.5;	→Feed Rate Setting
S0D0;	\rightarrow Call EDM S- Code #0 and compensation D#0
M98P9951;	\rightarrow Call program number 9951 (1 st taper cut)
M00;	\rightarrow Hold (Remove the water material)
S0D0;	\rightarrow Call EDM S- Code #0 and compensation D#0
M98P9952;	→Call program number 9952 \circ (1 st vertical cut)
M00;	\rightarrow Hole (remove the water material)
S2D2F1.2;	\rightarrow Call EDM S- Code #2 and compensation D#2
M98P9951;	\rightarrow Call program number 9951 (2 nd taper cut)
S2D2F1.2;	\rightarrow Call EDM S- Code #2 and compensation D#2
M98P9952;	→Call program number 9952 \circ (2 nd vertical cut)
M02;	→Program End







8.5 Things to be careful during Skim Cut

8.5.1 Taper Cut

Do the following procedures for inner hole taper cut.



8.5.2 Punch program

In order to finish the punch cut, the un- cut section has to be done in one cut.

In general cases, there is 2- 5 mm uncut section in the workpiece. This length is varying on the application.

For long and wide products, 2 start holes on each end as shown is recommended.





9 Other Manual Functions

Except Edge Find, Center Find and Slit functions, KENT USA WEDM provides more function for position :

- 1 Out Circle Center
- ② Side Center
- 3 Coor. Table

9.1 Out Circle Center

Calculate the center position via selecting points from the arc. Use the Edge Find function to select points and save the coordinate. After the calculation, machine can find the center automatically.







(2) Press [Manual] to enter [Out Circle Center]

(2) Press 《Out Circle Center》 to enter Arc Center screen.





- (3) In Arc Center screen, setup wire tension and wire feed rate. (WT=10, Wire Speed=3)
- (4) $\langle\!\langle XY \rangle\!\rangle$ axis direction $\rangle\!\rangle$ Selection
- (5) Set up 《Setup Speed》

* Pease refer to 4.11.1(3) to learn more.

- (6) Edge Find points (Mechanical Coordinate)
 - Select 3~6 center points : The more testing points, the more accurate it will be. However, it will spend more time to do the edge find points.
 - 2. SET: Input the coordinate of Arc into P* X .
 - 3. Reset : Clear the current coordinate.
 - 4. All Reset : Clear all of the coordinates.
- (7)Select 《Center》, the machine head will adjust its wire speed and wire tension and then start the Edge Find process. When Edge Find is completed, * on P1 will disappear. Edge Find Coordinate (Mechanical Coordinate) is represented by P1 at this time. After that, the machine head will return to the starting point.
- (8) Move the machine head to the next Edge Find position.
- (9) Repeat step (7) and (8), and save 3~6 points coordinates.
 * 3 points at least.
- (10) When (9) is done, the Center Coordinate will be shown as $X \land Y \land \circ$
- (11) Press $\langle\!\!\langle \, Center \; Return \, \rangle\!\rangle$ and move the machine head to center Position
 - * Cut down the cutting wire is required.



9.2 Side Center

Record the points ①② and machine can calculate the side center position.

Use Side Center function to find the side center of workpiece.

Procedure :

- (1) In [JOG] Mode, move the cutting wire to \mathbb{O} position.
- (2) Press [Manual] to enter manual screen.
- (3) Press 《Side Center》 and enter Side Center screen.

	(X) + 10 平高	Coordinate	Manual	Machining	Message	System	Manual Aut	ol Auto2 Ke	vPad Tool
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Y	0.0000			Side	e Center Finding M	sg	Go Pos.	Go Vert.	z - ÉMT Go Lmt.
z	0.0000			XY Axis Direction	Cutting Wire Setting				1.20
υ	0.0000			O Y+	0.	00 V	S.Pt Retn	H.Pt Retn	G92
v	0.0000		5 P	○ X-	WT 10		<u>}</u>	f_	
w	0.0000		- 11 C	O Y-	WF 3	Wire	Org. S.Pt	Org. H.Pt	Soft Lmt
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Stat (OBrk O G92	X	Y	⊡ Do	200	5	Manual Mode	WIAIIUAI	
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				FIIIQI	ug	rmung		Y+	Z+
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Gap	Break Para	1. Pitch Prot. 2	Vert. ST.	Pt Work Run	Warning:Wire bre	ak		Denet	Feed
Servo	Limit Spec	c. Orth. Lmt.Z	E.Stop Brk H	t. Short F.Hold	(2013/4/29 08:04:	51)		reset	Hold



(4) Setup Wire tension and Wire Feed rate.

(Wire Tension = 10, Wire Feed Rate = 3)

- (5) At 《XY axis direction》 select edge finding direction.(Ex: X direction)
- (6) Select "Side Center", the machine head will move to the side center position.
 - 1. Press Go : After finding the second point, machine head will move to the center of the workpiece automatically.
 - 2. Cancel Go : After finding the second point, machine head

will return to the Start point.

(7) Press Do "First Point Coordinate" \circ

* When Edge Find is complete, "First Point Coordinate" will appear automatically.

- (8) Press 《Start Side》, 《WIRE》 and 《Edge Find》 will start automatically.
- (9) When the message "Searching first point" appears, that means Edge find is complete.
- (10) Press Do "Second point Coordinate".
 - * When Edge Find is complete, "Second Point Coordinate" will appear automatically.
- (11) Repeat step $(6) \cdot (7)$.
- (12) Press 《Start Side》, 《WIRE》 and 《Edge Find》 will start automatically.
- (13) Press 《Return to Side Center》, machine head will move to the side center

*Cut down the cutting wire is required.

* Use Air gun to blow the workpiece before doing the Arc Center and Side Center.

* The functions of Arc Center and slide Center is to find the center position, it won't move the cutting wire to the center automatically.

This center position is used as a reference Coordinate.

! Note


9.3 Coor. Table

If there are some dies need to be cut in a workpiece, there will be some starting holes in NC program.

Therefore, if the wire has to return to the start point due to the wire broken or power is off during the 2^{nd} or later die, it only can return to the starting hole of current cut.

Original Point Return can set the first starting hole as reference original point. If the machine cannot return to the starting hole, it can be return to this reference point for machining.



9.3.1Original point Setup

Procedure :

- (1)Finish the workpiece installation and adjust the wire position.
- (2) Press [Manual] key and enter "Coor. Table" screen.
- (3) 2 kinds of coordinate record(mechanical coordinate) :
 - 1. Position and coordinate record.
 - 2. Set G54~G59 to the program.



9. Other Manual Function

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- 1. Position and Coordinate Record (mechanical coordinate) :
 - A. When the machine is at the saving point, use the mouse or ↑ ↓ key on the key board to select the saving group.
 Press Record to save.
 - B. 3 approaches to position :
 - I. Assign the position group and then press $\underline{Position Z}$ $\underline{Position UV} \cdot \underline{Position XY}$, the machine will move to the record position.
 - II. After assign the position group, choose single axis or multi axis under the "Positioning axis selection". Next press Position, the machine will move to the record point based on the assign instruction.
 - III. Move the mouse to the position group and then right click, a message will appear (Do you want to position to No. 00??). When pressed the OK Button, Z axis will move right after XYUV axis moved to the record point.

! Note

* When the machine is operating the fixed displacement, be sure upper and lower machine head are at the safe zone.



2. Set G54~G59 to the program :

Operation of G54~G59 and its using limit.

I. Command format : G54 <X1.0> <Y1.0> <P10>

"G54" represent mechanical coordinate

positioning(G54~G59 Default record number

of the mechanical coordinates 001~006)

"<?>" Default parameter can be omitted.

X, Y parameter of the increment relative to G54, if omit X,

Y, then replace it by 0,0.

"P" parameter forces the specific coordinate to record the number. If there is P parameter, then default G54~G59 coordinates to record number.

- Ex : G54 P7 No.007 positioning coordinate. The original G54 positioning coordinate will become invalid.
- II. Input G54 ~ G59 to the workpiece program for mechanical positioning, but need to be write before G92.
- III. DO NOT start the parallel compensation function, but it is fine operate the simulate parameter such as zoom, rotate, mirror etc.

Appendix : G54~G59 function

Description :

1. G54~G59 in program can be used to select the working coordinate system and set up the starting hole position in program. Controller can switch the coordinate system or reset starting hole by the command in program.

Procedure :

- 1. Complete the original point setting before machining.
- 2. Command Format :

```
(1)

N0010 G54;

N0011 G90G00X2.Y2.;

N0012 G92X2.Y2.;

N0013 .....

(2)

N0010 G54X2.Y2.;

N0011 .....
```



M02

Program the EDMing by the format (1) or (2) will get the same machining result. 3. The G90, G00 in format (1) are modal command, it's still enable. In format (2) command, it will still keep the ABS/REV position command, movement command and modal command. 4. The default coordinate in system is G54. Example : G54(200,200) G55(190,200) G56(210,200) G57(195,205) G57 is used as Start Point for the following example: 1. O0012 G57(195,205) G91 G92 X1. Y1. G01 X2. G01 Y3. G54(200,200) G55(190,200) G56(210,200) G55 X2. Y2. G01 X2. G01 Y3. M02 O0012 Machine Relative Absolute G91 (195., 205.) (-5.,-5.) (-5.,-5.) G92 X1. Y1. (195., 205.) (1., 1.) (1., 1.)G01 X2. (197., 205.) (3., 1.)(3., 1.)G01 Y3. (197., 208.)(3., 4.)(3., 4.)G55 X2. Y2. (192., 202.) (2., 2.) (-2., -2.) G01 X2. (194., 202.) (0., -2.)(4., 2.) G01 Y3. (194., 205.) (4., 5.) (0., 1.)M02 _ -_ 2. O0013 G91

 G91
 G57(195,205)

 G55 X1. Y1.
 f

 G01 X2.
 f

 G01 Y3.
 f

 G92 X2. Y2.
 G55(190,200)

 G01 X2.
 G55(190,200)

 G01 X2.
 G55(190,200)

 G01 X2.
 G55(190,200)

 G01 X3.
 G55(190,200)



9. Other Manual Function

O0013	Machine	Relative	Absolute
G91	(195., 205.)	(-5.,-5.)	(-5.,-5.)
G55 X1. Y1.	(191., 201.)	(1., 1.)	(1., 1.)
G01 X2.	(193., 201.)	(3., 1.)	(3., 1.)
G01 Y3.	(193., 204.)	(3., 4.)	(3., 4.)
G92 X2. Y2.	(193., 204.)	(3., 4.)	(2., 2.)
G01 X2.	(195., 204.)	(5., 4.)	(4., 2.)
G01 Y3.	(195., 207.)	(5., 7.)	(4., 5.)
M02	-	_	

! Note

The G92 added below G01 \sim G02 \sim G03... will reset the ABS coordinate value only. It won't change the REV. Coordinate value.

3. O0014 G91 G55 X1. Y1. G01 X2. G01 Y3.	G57(195,205) G55(190,200) G5	54(200,200) G56(210,2	
G56 X2. Y2.			
G01 X2.			
G01 Y3.			
M02		1	1
O0014	Machine	Relative	Absolute
G91	(195., 205.)	(-5.,-5.)	(-5.,-5.)
G55 X1. Y1.	(191., 201.)	(1., 1.)	(1., 1.)
G01 X2.	(193., 201.)	(3., 1.)	(3., 1.)
G01 Y3.	(193., 204.)	(3., 4.)	(3., 4.)
G56 X2. Y2.	(212., 202.)	(22., 2.)	(2., 2.)
G01 X2.	(214., 202.)	(24., 2.)	(4., 2.)
G01 Y3.	(214., 205.)	(24., 5.)	(4., 5.)
M02	-	-	-



10 MDI Mode

Press MDI under (Manual) mode. Single block NC program can be executed under (MDI) mode. By using single block NC command to move machine table in certain distance or execute the cutting.

10.1 Manual Data Input

 $Procedure \ :$

(1) Press 《MDI》 and switch to MDI mode.

							2.
	~				W USB		82:550
遊求完美・止於至著	Coordinate	Manual	Machining	Message	System	Manual Autol Au	ato2 KeyPad Tool
X 0.0000	MDI			E L I I		Cutting PARAM	Function
Y 0.0000	00001			0.00	in)	No 53	Block cutting
7 0.0000				Select MDI Cu	tting Mode	DM 2	Corner decel.
2 0.0000				O Machinin	ng to Start PT.	On 16	🗌 Arc decel.
U 0.0000				🔿 Machinin	ng to Break PT.	Off 8	Run M01
V 0.0000				O Machinin	ng to G92	AOn 14	Pos
W 0.0000		INPUT	Г	O Cutting t	o Position point	AOff 10	Don't wait gap
Rel O Ahs O Mac				Machining	ng MDI		Dry Run
○ Strt ○ Brk ○ G92				O Machinii	ng to record		🗌 Mac. locked
Set Coor.						WF 11	🗖 Paral. comp.
Dias China				Record Numb	er Produce	WR 3	Start Break
Total					Program	SV 30	Point Point
P.scl				0 - Vertica	I 💌	FS 2	G92 Restart
				Program Plane	e Thickness	Feed 4.5	
5 -50 -25 0 25 50 ;					-20	F.D% 140 %	Wire
Deion(K ohm)	DPOS	MDI		0.		Clep 05	Watar
50 L 65 H	Dirob	Start Pt.	Reset	Stop	Start		water
	S. EDGE	MDI Break Pt.	MDI	MDI	MDI	Save parameter	EDM
) -20 -10 0 10 20 3	Origin Edge	Slit	Arc Out Circl	e Side	Edge Vert		
	Return Finding	Finding	Center Center	Center	Corner Adjust	Feed	Cycle
Idle	PARAL. Coor. COMP. Table	(MDI)	Original Pitch Path COMP.	Orth. COMP.	Polar Correct	Hold	Start
Gap Break Para	al. Pitch Prot. Z	Vert. ST. Pt	Work Run	Fail to compact M	IO		Field
Servo Limit Spe	c. Orth. Lmt.Z	E.Stop Brk Pt.	Short F.Hold	2013/4/29 08:04:	45)	F	Reset Hold
		-11					



- (2) Press Produce Program to produce NC program or input the NC program in the edit area.
 - * G92 need to be added when input the NC program, otherwise "unset G92" alert will appear.
- (3) Under "Select MDI Cutting Mode" press 《Machining MDI》 to verify Cut Mode, Program Plane, Workpiece Thickness then type the NC program in the input area.

EX : G01X45. Cut Mode : 0-vertical • Program Plane : 0 • Workpiece Thickness : 60 mm

Input $\langle G \rangle \langle 0 \rangle \langle 1 \rangle \langle X \rangle \langle 4 \rangle \langle 5 \rangle \langle . \rangle$

					W USE	ЗН	USB MUS	B 10:30:23
追求完美,止於至善	Coordinate	Manual	Machining	Message	Sys	tem	Manual Autol At	ato2 KeyPad Tool
X 0.0000	MDI						Cutting PARAM	Function
× 0.0000 (00001 G95G91G	92X0.YO.		Peedrate(mm/	min)		No 53	Block cutting
7 0.0000	00002 G01X45.		\searrow	Select MDI C	Cutting Mode		DM 2	Corner decel.
2 0.0000				🔘 Machin	ing to Start P	Т.	On 16	🗌 Arc decel.
U 0.0000				O Machin	ing to Break H	PT.	Off 8	🗆 Run M01
V 0.0000				O Machin	ing to G92		40n 14	Pos
W 0.0000	Inn	nt		O Cutting	to Position p	oint	10	Don't wait can
	Inp			Machin	ing MDI			Dry Run
Strt Brk G92	EX	GOIX	45.	Machin	ing to record			🗌 Mac. locked
Cet Crun					ing to record		VVF 11	🗌 Paral. comp.
Set Coor.				Record Num	ber Pro	duce	VVR 3	Start Break
Disc. Status Total				<u> </u>	Pro;	gram	SV 30	Point Point
P.sd				0 - Vertic	al	•	FS 2	G92 Restart
		Cut M	lode	Program Pla	ne Thicknes	35	Feed 4.5	
5 -50 -25 0 25 50 ;				20	-20		E D% 140 %	Wire
Deion(K ohm)	DPOS	MDI						TTL 4
50 L 65 H	DIOD	Start Pt.	Reset	Stop	Sta	art		water
untrutum untrutud	S. EDGE	MDI Break Pt.	MDI	MDI	M.	DI	Save parameter	EDM
D -20 -10 (0 10 20 3	Origin Edge Return Findin	g Slit Finding	Arc Out Ci Center Cent	rcle Side er Center	Edge Corner	Vert. Adjust	Feed	Cycle
Idle	PARAL. Coor COMP. Table	MDI	Original Pitch Path COM	n Orth. P. COMP.	Polar Correct		Hold	Start
Gap Break Para	l. Pitch Prot. Z	Vert. ST. I	t Work Run	Fail to connect N	10TION USB			Feed
Servo Limit Spec	c. Orth. Lmt.Z	E.Stop Brk P	t. Short F.Hold	(2013/4/29 08:04	:44)		ŀ	Keset Hold



(4) To move the Table, press $(Auto1) \rightarrow (Dry Run)$, and then select (Start MDI).



(5) Use Single command to cut wire cut: Press 《WIRE》 《WATER》 《EDM》, and then 《Start MDI》 to start.

(6) To return to machining start point press MDI Start Point, machine will return to start point at a dry run speed.

(7) To return to machining broken wire point press MDI Break Point, machine will return to broken wire point at a dry run speed.

(8)Either press Stop MDI or other Feed Hold button can stop Dry Run or other processing.

(9) To reset the current machining, press Reset MDI or other Reset to clear the recent working status.

! Note

Do not press 《Dry Run》 key while single command wire cut. Otherwise the wire will be broken because of the fast feed rate.

J Hint

While single command wire cut, working parameter can be adjust.



10.2 D.POS (Discharge Position) Mode :

Main function :"Manual Discharge". Coordinate 《WIRE》 《WATER》 key to operate "Manual Feed" machining.

Procedure :

- Set the working parameter On
 Aon, but the value cannot be too big. Otherwise the wire will touch the workpiece and broken easily.
- (2) Start 《WIRE》 《WATER》 《EDM》 《D.POS》 on the remote control or on screen to operate lower speed cutting when the workpiece and wire are not under short circuit situation.

✗ Danger

For personal safety, do not touch the wire at this point. D. POS Mode has to be closed when operating normal machining.

10.3 S.EDGE (Spark Edge) Spark Manual

Main function: By using weak energy to do vertical alignment or to confirm whether the wire is perpendicular to the workpiece or not.

- (1) Clean upper and lower machine head with air gun.
- (2) Since the energy of 《S.EDGE》 is stabled, the value of wire feed rate and wire tension need to be adjusted.
- (3) After selecting S.EDGE, WIRE & EDM will operate automatically. Then press D.POS , the gap voltage will increase from 0V to 45V.
- (4) Use remote control or screen to operate XU or YV vertical alignment at low speed when workpiece and wire are not under short circuit situation.



10.4 MDI Mode selection

Main function: Base on the G95 straight cutting type returns to the Cutting point, Broken point, G92 point or assign cutting destination point or record point.

(1) To the cutting point : The cutting point is under the short circuit situation when operating the machining. Due to this reason, move the wire to the not short circuit situation and then reset machining. After turn on 《WIRE》《WATER》
《EDM》《Start MDI》, the machine will cut to the cutting point based on the temporary machining parameter.

(2) To broken wire point : Reset machining under no short

circuit situation. After turn on 《WIRE》《WATER》 《EDM》《Start MDI》, the machine will cut to the broken point based the temporary machining parameter.

(3) To G92 point : Reset machining in any position and

without having short circuit. After turn on 《WIRE》 《WATER》
《EDM》 《Start MDI》, the machine will cut to the last G92 point based on the temporary machining parameter.
To the fixed point: 《MDI Start》, "Please turn on Water, Wire and EDM" message will appear when these conditions are

appear when these conditions are not ON. After turning on 《WIRE》 《WATER》 《EDM》, the coordinate setup window below will appear.

(4)



10. MDI Mode

Machining to Po	sition		×
■ REL	X 🛛		
□ABS	Z 0		
	ClearAll	ок	Cancel

The fixed point above is setup by coordinate (ABS/REL) position to cut.

- (4) MDI Program : Refer to 10.1 •
- (5) Machining to record point : When operating this function, please select the recording number. Start 《WIRE》 《WATER》

《EDM》《Start MDI》, machine will cut by the working parameter to the recording point.

* Recording point [Manual] → 《Coor. Table》 coordinate position (mechanical coordinate)



1 Alarm

While the machine is malfunction, machine will stop automatically.

While the alarm appears during the graphic simulation, the simulation procedure is interrupted.

The type and content of alarm will be shown on the Alarm Screen.

11.1 Check for the Alarm Message

(1) Alarm Message is shown on the screen while the Alarm is on.

	Sedm .					W USB H	USB MUSB 1::15-2:1
8*	R完美·止於至著	Coordinate	Manual	Machining	Message	System	Manual Auto1 Auto2 KeyPad Tool
Х	0.0000	-Composite Messag	29 29				
Y	0.0000	Code	Time		Messages	~	Go Pos Go Vert Go Lint
_	0.0000	S00001	2013/4/29 10:50:37	Fail to connect MOTIO	ONUSB		
2	0.0000	S00142	2013/4/29 10:50:37	Fail to connect HARD	KEYUSB		
U	0.0000	S00242	2013/4/29 10:50:38	Fail to connect WIO			S.Pt Retn H.Pt Retn G92
v	0.0000	M01006	2013/4/29 10:50:42	Emergent stopping			$\left[\begin{array}{c} \Omega \\ \Omega \\ \end{array}\right]$
V	0.0000	M01000	2013/4/29 10:50:42	Servo is not ready			
w	0.0000		2010/ 1/20 10:00:12	Certo Io Iloridady			Org. S.Pt Org. H.Pt Soft Lmt.
@ Dal	O Alto O Man						Set/Cancel
C Ctrt	O Ads O Mat						Zlimit Manual hold
	O DIK O G92						-Manual Mode
	Set Coor.						◯ Inch Jog ◯ Jog ◯ Off
Disc. St	tatus						O MPG O FUN
Total Red							
-Gan Vo	olt.(V)					~	Manual Paprameter - OFF
	0.00	<				>	$\bigcirc x1 \qquad x10 \qquad x100 \qquad x1000$
5 -50 -:	25 0 25 50 ;			Compared a			0
Deion(F	K ohm)	LI INEW TECC	ord is above			Clear	Moving Direction
50	L 65 H	🔳 New reco	ord is under	🔲 History			
			17				
impun	un in the second se	Error Message	Trace				Y+ Z+
) -20 -1	10 0 10 20 3						
		11/10	info		Jac J.	4 - 4	
	Idle		ung o				X- 💭 😲 🕞 X+ 😲
		USB States	Messages	Intenance Motion Sta	les I/O State	es j	Y- Z-
Gap	Break Para	l. Pitch Pro	t. Z Vert. ST. P	t Work Run F	ail to connect. WIG)	Feed
Serve	o Limit Spe	c. Orth. Lm	t.Z E.Stop Brk Pt	t. Short F.Hold	013/4/29 10:50:38)	Reset Hold
						\sim	
						Alarr	n
						1 11411.	<u> </u>



- (2) $\[Current \] and \[History \] Alarm :$
 - Under [Message] press (info Message) and select

 $\ ^{\sqcap}$ Current $_{\bot}$ and $\ ^{\sqcap}$ History $_{\bot}$ to read all the alarm message.

(3) Alarm Clear :

To clear the Alarm, press 《Clear》.





J Hint

* If the Alarm cannot be cleared after 《Clear》 is entered, please shut down the main power and restart the machine. If the alarm still cannot be cleared, please call the technician for trouble shooting.



12 Maintain/Working History

Maintain information provides the wire consumption status. Base on the information operator can replace the material and parts such as PC Board, Filters Wire, and Ionized resin. Working History provides the data of Staring time, working, and total working time.

12.1 Display Maintain information

Please enter the maintain information if the message appears. In this message if the value is over the limit, please follow the step below.



(1) Press [Message] to enter «Maintenance» screen



(2) After cleaning and replacement are completed, change condition of the assign item under \ulcorner Setting \lrcorner

L	Sen					W USB	HUSE	B M US	B [];	32:40
	末完美・止於至著	Coordinate	Manual	Machining	Message	System	Man	ual Autol Au	to2 KeyPa	d Tool
x	0.0000	-Maintenance Information	1				-Cu	ting PARAM	Function	
v	0.000	Used Wire Length			Set	ling		No 1	Block	cutting
	0.0000	Length Limit(Rm):	92	0%	۲	Used wire length		DM 2	Corner	r decel.
z	0.0000					Hooner used time		On 10	🗌 Arc de	cel.
U	0.0000	Whe Hooper				nooper abea time		Off 10	🗆 Run M	101
v	0.0000	Time Limit(hr):	100	0%	0	Filter used time			🗆 Pos	
	0.0000	This Link (in).	100			EL Bruch time		.On 8	🗌 Fly Cu	ıt
vv	0.0000	Filter Box Used Time				LL. Didsir time		.Off 9	🗌 Don't v	wait gap
Rel	l 🔿 Abs 🔿 Mac	Used time(hr):	0	0%	0	Resin used time		/VT 9	Dry Rt	un
O Std	t 🔿 Brk 🔿 G92	Time Limit(hr):	100			Table used dates		NF 6	Paral	ocked
	Set Coor.	EL. Brush Used Tim	9			rable used time			T alal.	comp.
Disc. S	Status	Used time(hr):	0	0%					Start	Break
Total P.scl		Time Limit(hr):	100			Docot		SV [15		
-Gap V	olt.(V)	– I. EX. Resin Used Ti	me			Resei		FS 10	G92	Restart
mpn		Used time(hr):		100%			F	eed 20		
5 -50	-25 0 25 50	Time Limit(hr):	92	100.10		Madifu	E.	D% 100 %	W	ire
Deion	(K ohm)	-Working Table Used	Time			Limitation		on 0.5	W.	
50	L 65 H	Used time(hr):	4	Fat					vv a	ller
		Time Limit(hr):	100	5%			S	ave parameter	FD	м
) -20	-10 () 10 20 3									141
		ILAO -	info					Feed	Cv	cle
	Idle	\$		=0				Hold	St	art
		USB States M	essages Mai	ntenance Motion S	ates 1/0 Sta	ates		noiu	່ວເຜ	ait
Gaj	p Break Para	al. Pitch Prot. Z	Vert. ST. Pt	Work Run	The maximum	time which ion-e>	change		onat	Feed
Serv	o Limit Spe	c. Orth. Lmt.Z	E.Stop Brk Pt	. Short F.Hold	resin has been	used.		K	eset	Hold

(3) To change the limit value press 《Modify Limitation》, a input value window will appear. Input the assign value and then press OK.

Modify the length limit of used wire)	×
Please input the new limit (1~100	
82	
OK Cancel	

(4) To clear the time recorded press 《Reset》, pressOK when the message appears.

Confirm(MSG)	×
Reset Ion EX. resin used time?	
OK Cancel	



12.2 Daily Maintain.

	Daily Maintian	
	Maintain items	Check
1	Wire path comfirm.	
2	Working fluid comfirm.	
3	Upper/Lower electrode tips confirm.	
4	Wire collect confirm	
5	Confirmation of working fluid resistance	
6	Clean up every part of the machine after machining	
7	Working Table and Working Tank confirm	

	Weekly Confirmation
	Confirm items Check
1	Upper/Lower wire guide and flush head
2	Vertical correction for wire
3	Clean up under arm and oil seal plate

Monthly Maintain							
	Maintain items	Check					
1	Tension wheel suface comfirm						
2	Path of wire winding to every wheel confirm						
3	Process of cleaning fluid cooler filter						

	Three Month Maintain										
	Maintain items	Check									
1	Clean upper/lower machine head parts										
2	Replace working fluid and clean water tank and internal float.										
3	Check upper/ lower ground wire.										
4	Check upper/lower machine head surface.										



12.3 Maintain Procedure

(1) Wire path confirmation (Auto and Manual Threading)

Auto Threading :





Manual Threading :





(2) Working fluid verification

Open the water tank cap to check the condition of working fluid and filter. The following figure is the front view of W-430 flush type water tank. Other types of water tank will be shown in appendix (I.)



W-B430 • Wi-430 submerge type water tank side view



Please check the following when the machine power is on :

- (1) Please check the water height of the sewage tank and clean sink before turn on the machine power.
- (2) If the sink is too dirty, please turn off the machine and replace the filter.

[Procedure of filter replacement]

- 1. Power off the machine, and open the acrylic cover which is on the top of the filter.
- 2. Pull out the connector on the top of the filter.



3. Replace a new filter.



4. Connect the connector to the filter.













(3) Check upper/lower Power Feed Contactor

[Check upper power feed contactor]

1. Remove the fastening screw on upper machine head.



2. Insert a small hexagon wrench and push out the Power Feed Contactor. The L-



3. Check Power Feed Contactor:

Is there any wear mark or dirt on the surface of power contactor?



4. Clean the contactor with detergent :

Make sure there is no dirt on the surface of contactor.





5. Use the L- shape Ruler to install power contactor. The power contactor must be inserted completely and should not be exposed.





6. Tighen the fastening screw.





[Check Lower Power Feed Contactor]





2. Insert a small hexagon wrench and push out the Power Feed Contactor. The L-Shaped small ruler can be used to remove the contactor too.



3. Check power Feed Contactor :

Is there any wear mark or dirt on the surface of power contactor?



4. Clean the contactor with detergent :

Make sure there is no dirt on the surface of contactor.





5. Use the L- shape Ruler to install power contactor. The power contactor must be inserted completely and should not be exposed.





6. Tighen the fastening screw.





(4) Verification of waste wire and barrel

Abandon the waste wire when it is half full in the barrel.

- 1. Power off the machine.
- 2. Remove the cap and then take out the barrel.



3. Close the cap and re-install the barrel.





(5) Verification of processing liquid's water resistance

If the value of water resistance is between WAL and WAH or higher than WAH, that means the water quality is under control.



If the water resistance value is lower than WAL and the problem has not been solved after 60 minutes of deionized motor operating. ION- Exchange resin needs to be replaced at this point. The initial color of the ION-Exchanger resin is deep blue or golden yellow. The color will change into brown after processing liquid goes through ION- Exchange resin. ION- Exchange resin also has to be changed if the color doesn't change but the water resistance value cannot increase.

- 1. Turn off the machine.
- 2. Unplug the connecter that is connected to the rapid resin tank.
- 3.Loosen the twill.
- 4.Remove the resin tank.
- 5. Unscrew the resin tank lid with counter clockwise direction.
- 6. Pour in the new ION- Exchange resin.
- 7. Fasten the lid, reinstall the resin tank and then buckled the twill.
- 8. Connect the connector to the resin tank.



* Reference : The table below represents the ION- Exchange Resin volume of different WEDM model.



Model	Volume
Submerge type	10 (L)
Flush type	5 (L)

(6) Clean Up Machine Parts

After processing, clean all machine parts immediately.

It is easy and most effective to clean the parts when processing liquid is still wet. Please remove the parts to clean it.





- 2. Under [Process Monitoring] set WA=1, and then open the process liquid.
- 3. Use a toothbrush to scrub the lower machine head and get rid of dirt.
- 4. Remove the upper and lower flush nozzle and take out the diamond guides. Use toothbrush to clean the diamond guides.
- 5. Remove the Power cable terminals and use toothbrush to clean the contact surface.



6. Re- install flush nozzle and power cable terminals.



(7) Verification of Work Tank and Table

Make sure there aren't dents, cracks and sediment on the cross bridge fixture and table.

If there are cracks and dents on the work table and cross bridge fixture, a huge error will appear during the machining.

Use wet damp cloth to wipe out the sediment, otherwise use the rust remover (K-200) to get rid of it.



Check the waterproof oil seal plate in the working tank, and take out the waste and waste wire carefully in order to prevent oil seal plate and lower arm get scratched. When cleaning the inter side of the oil seal plate, be caution to avoid the oil seal plate getting scratched or leakage because issue will occur.





13 AWT Description

The AWT system created by KENT USA EDM MFG has state of the art design, with Intelligent Auto Threading Software. Following is the description of KENT USA WEDM AWT system.

13.1 AWT/ Wire Cutting Function description:

Hot Key \rightarrow Under Tool, there are $\lceil AWT \rfloor$ \land $\lceil Cut Wire \rfloor$

 \lceil Water or Air \rfloor etc. In addition, some function can also be found on the controller box.





13.2 AWT/ Wire Cutting Function description:

Under [Machining] \rightarrow (Smart Func.) \rightarrow \square AWT \square , the figure below shows the setting of AWT.



13.2.1 AWT State :

- (1) AWT Step : The numbers in this block represent the step which the threading process is going through
- (2) AWT Time(Sec) : The duration between starts and ends AWT.
- (3) Finish counts : The sum of threading successfully.
- (4) Current fail counts : The sum of fail threading.
- (5) Fail counts : The sum of fail threading on G92.





13.2.2 AWT Setting1

- (1)Limit times of AWT fail in break point: When AWT fail is over the limit, the machine will move to the starting point and thread automatically. After done with threading, the machine will go back to break point by itself.
- (2) Limit times of AWT fail : When the sum of AWT fail in both starting and breaking point are over the limit, the machine will stop cutting or move to the next G92.
- (3) Delay time of returning to AWT point(Sec) : Two situation might happened while this function is set.
 - When the delay time of threading on the breaking point is over the limit, the machine will thread at the starting point.
- ii. When the delay time of threading on the breaking point is over the limit, The machine will thread at the next G92.
 - (4) Height of Z axis arise while AWT(mm) : Every time before operating threading(M60), Z axis has to raise to the height limit.
 - (5) Select wire diameter : The threading speed and wire length depend on the feeding path
 - (6) M50/60 Switch : This function is used to remove the metal piece from the workpiece after done with machining. When the path between M50 and M60 is done with machining, set M50/M60 to ON to switch the function between M50 and M60.



- (7)Move to next G92 while an error message appears in BYPASS: When the re-threading process reaches the set limit, an error message will appear. If this function is ON, the machine will move and thread at the next G92. And if this function is OFF, the machine will stop when fail threading.
- (8) Limit times of deflection : When the machine reaches its deflection limit, the machine will record it as one threading fail.
- (9) Open up No.9 air valve : During preheat, the wire will be tighten. Therefore, when cutting the wire, there will rounding force in the wire. The thinner the wire, the stronger rounding force it will have. This means when the thickness of the wire is below 0.15m No.9 valve needs to be opened. However, please close No.9 valve when preheating thicker wire in order to prevent affecting the wire straightness.



(10) Times of cutting waste wire : If the wire is break inside the workpiece,this function can be set to make the threading process more successful.

									W USB			IVI		3	14:4	0:0*	
8.4	》 完美·北黔王莽	Coordin	ate	Manual		Machining	(N	Aessage	System		Manual	Autol	Au	102 Ke	eyPad	Tool	
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	0.0000	5000	6.05mm	0.111111	11	16	27	22	Wamup powo			H		-		<u>}</u> −−	
	0.0000	5000	40	35	30	10	8	7	Warm-up powe		М	N	0	P	Q	R	
	0.0000	5001	2	3	7	35	70	75	Wire-cut nower			T				Î v	
	0.0000	5002	25	20	15	5	5	5	Wire-cut power		<u> </u>					<u> </u>	
1	0.0000	5004	190	200	210	220	300	350	Total warm-up a		Y	z	-	+		2	
	0.0000	5005	350	370	380	390	400	440	Total wire-cut p			Ŀ	-	<u> </u>	<u> </u>	₩	
Rel	🔿 Abs 🔿 Mac	5006	450	460	470	480	500	520	Receive waste		{	}			<	2	
Stat	OBrk OG92	5007	200	210	220	230	240	250	The speed of re		÷	H	#	è	÷	<u>}</u>	
		5008	60	62	64	66	70	75	The rolling velo		11	2	3	4	5	6	
	Set Coor.	5009	80	85	90	95	100	105	The speed of re		&	*	(
c. St	atus	5010	40	42	44	46	50	52	The rolling velo		7	8	9		<u> </u>		
al		5011	6	6	6	6	6	6	過上機頭水段數(F		в	ack	т	ab	l s	hift	
d		5012	5	5	5	5	5	5	Wire cut MODE 🗸		├ ──				l	_	
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μıπ	hin minimum	Code	Fly Cut	Arc	Cor	ner ŝ	SET	AWT	ByPass		4	5	б		End	PgDn	
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Gan	Brook Poro	Ritah	Prot 7	Wort S	T P+ W	ark Du						_	1		1		
Gap	DIBAK LAIS	. I Itcli	1101. 2	Vert. D	1.15 W	JIK KU	Emerg 20126	ent stoppin					R	eset	H P	eed	



Hint

Parameter :

Please set the suitable parameter for machining If the wring value has been input, it may cause the machine disable to work operate irregularly. Parameter is really important for machining.

Password is needed for edit parameter. The password is included in the disk.

13.2.3 AWT Setting2 : Passcode is needed

- (1) Warm-up power ON Time : The straightness of the wire will be affected if the wire isn't be used for a long time. Heating the wire can resume it to the original straightness. However the wire will deform or break if it heats too long. The heating time cannot be too short either because the time won't be enough for the wire to get straight.
- (2)Warm-up power OFF Time: This is a function where the warm up time can be adjust. When decreases the warm up power OFF time the heating temperature will raise, whereas the temperature will decrease when increasing the warm up power OFF time.
- (3) Wire-cut power ON Time : If the parameter is set too big, the wire cut power will cause the wire tip becomes not sharp. Whereas the wire tip will be break because of pulling or cannot be cut if the power is set too low.
- (4) Wire-cut power OFF Time : This is a function where the wire cut time can be adjust. • . When decreases the wire cut power OFF time the heating temperature will raise, whereas the temperature will decrease when increasing the wire cut power OFF time.


Best ConditionExcess of PowerLack of powerImage: Descent set of the s

- (5) Total warm-up power time : Total time to preheat. Warm up time cannot be too long or too short, it might cause the deformation and affect the straightness of the wire.
- (6) Total wire-cut power time: Total time to cut wire. The values that used as the parameter depends on wire cut ON, OFF time, wire cut tension etc. Do not change this setting if you are not technician.
- (7)Receive waste wire time: While done with wire cut or wire break, turn off the motor to stop the receive waster wire time.
- (8) The speed of receive waste wire(Servo Motor) : Turn on and adjust the speed of the motor after finish cutting or breaking the wire.
- (9) The rolling velocity of determine the wire is break or not(Servo Motor) : To confirm the threading process is successful or not, the rolling wheel(It is used to receive the waste wire.) will start rolling. If the tension wheel and the motor operate at the same time, that mean the threading process is done.
- (10) The speed of receive waste wire(DC Motor): same with (8), but the parameter can only suitable for AC motor.
- (11) The rolling velocity of determine the wire is break or not(DC Motor) :same with (9), but the parameter is only suitable for AC motor.
- (12) Water flow rate of the upper machine head : After wire cut, semiautomatic water flow rate is used to help the wire pass through the upper diamond guide. When the wire is sent to the diamond guide, the water flow rate will change to automatic which is based on the set parameter.
- (13) Wire cut MODE: (Not available)



- (14) Warm-up pulling force : In order to reach the best condition of straightness, wire tension plays an important role at this point. The best condition cannot be achieved if the wire tension is too big or too small.
- (15)Wire-cut pulling force: A temperate pulling force is needed during wire cut, the force cannot be too big or too small.
- (16) Distance 1 speed (mm/min) : The feeding speed from enable AWT to wire cut point.
- (17) Distance 2 speed (mm/min): The feeding speed from wire cut point to the flush water cap of upper machine head.
- (18) Distance 3 speed (mm/min) : The feeding speed from the flush water cap of upper machine head to the work piece.
- (19) Distance 4 speed (mm/min) : The feeding speed from workpiece to flush water wheel.
- (20) Distance 5 speed (mm/min): The feeding speed from flush water wheel to wire receiving wire.
- (21) Distance 6 speed (mm/min) : The feeding speed from the wire receiving wheel to wire recycle bin.





- (22) The speed of wire backward (mm/min) : This function is under Tool
- (23) The speed of wire forward (mm/min) : This function is under Tool
- (24) Deflection retrogression speed : There are 6 detection points(16)~(21) in



the threading system. Since the threading speed in each part of section is different, the detected speed will also be different. If the wire is not able to thread due to the wire curvature, the tension wheel will roll reversely. Besides, if the wire is too thin and the wire is moving backward too fast, the wire that locates between wire feed wheel and tension wheel will come off. This will cause the threading process to fail.

- (25) The waste wire eliminate On Time set : While machining, if the power of On Time is relatively big, the surface of the wire will be rough which will increase the possible of threading to fail. If the On Time parameter is larger than the set limit, the waste wire eliminate On Time set will start to operate.
- (26) Water pressure default value in Manual threading : The parameter in this section stands for the intensity of water pressure in semiautomatic threading. Please input the suitable parameter when using the wire with different thickness, otherwise the wire might stock at the receiving wire section.



(27) Wire tension default value in Manual threading : When the EDM system is ON, the tension wheel will provide a tension to stop wire feeding (None AWT system only). However, it might cause the wire comes off from the path.

13.3 ByPass :

Under [Machining] \rightarrow (Smart Function) \rightarrow ByPass), the figures provides a screen shot and shows the machining process.











Purpose:

When doing machining with multiple G92, if one of the G92 points reaches thread failure limit, the machine will move to the next G92 and start machining. This function is created to save more time and be more convenient for the users when operating machining.

Machining:



- 1. Based on the figure above, Bypass records the G92 points that are failed to thread. When the machining is done with its mission, the user can find the G92 points that are failed to thread based on Bypass and do the machining. The record will be deleted automatically whenever the G92 point is done with machining.
- 2. Before using Bypass, please check and remove the wastes in the break point.
- 3. Please Reset the machining program and select machining to break point then click Remachining . The maching will operate dry_run and move to the specified break point. After the machine reaches the break point, it will stay hold. Please thread manually and re-machining at this point.



13.4 Machining Program

Purpose : To make the AWT program more automation, M40/M50M60 need to include in NC program.



Format : Based on the figure above, M60 will be added behind every G92. When the metal part is done with machining, a small distance is left to avoid the metal part being re-discharge and get damage. M50 is an instruction to cut through this distance and remove the metal part from the work piece. Last, M40 will be used to cut the wire then the machine will move to the next G92 based on G00.

Procedure :

- 1.When M50/M60=0, if the program reads M60, the machine will start threading. During machining, if the program reaches M50, the machine will operate dry run and move to the next G92.
- 2. After done with machining, but use Bypass to check and finish the unfinished work.
- 3. When the machine is done with machining, please move the machine to the start point and set M50/M60=1 to remove the wastes from the workpiece.
- 4. At this point when program reaches M60, wire cut will be operated. Next, the machine will Dry Run and move to M50 which is stands for threading. Press CYCLE START to finish up cutting, the wire will be cut when it meets M40. When the cutting process is done, G00 will be operated. The machine will move to the next G92 and repeat the same machining process.



AWT description

- (1). Problem with the threading process after threading the wire into the guide with a depth of $1 \sim 2$ mm.
- A : 1. Please check the wire if its rust or not.(The oxide particle that is on the wire will result the wire having a rough surface.)
 - 2. Check the copper wire quality. (Highly recommand not to use the wire that has been produced over 6 months.)
 - 3. Please check the inner suface of upper guide and make sure its clean.
 - 4. Please clean the upper guide and make sure there is no scratch or wire inside the guide.
 - 5. While cutting the wire, if the power connect part (JU120AN) moves speed too fast, it will cause the cooper wire being compressed. The compressed wire will not able to go through the lower guide. Please adjust the airflow from the cylinder.
 - 6. Discharging won't happen when cutting the wire. If there is, please check the power connect part (JU120AN) and the (JU53CN).
- (2). After pressing the AUTO key (Auto threading wire key) the braking wheel (WD48AN) will rotate in clockwise. Please check the part list (JY025-A)

Checking process:

- A : 1. Please check JU110BN and make sure there are no chips.
 - 2. Please check the lower guide (WA52AN) and make sure there are no chips.
 - 3. When the cooper wire threads into the low arm , please check machine coordinate from the Z-axis.
- (3). When operation the wire treading function, the wire is able to thread through wire sensor (JU110BN), but not able to reach the cut wire point (JU126AN). Please check the JY025-A and JY026-A

Checking process:

- A : 1. Please check the conduit (JU99) and make sure there is no wire inside. (The different series has different part numbers: WA430A \ WA530A type is JU99AN \ WA640A type is AU07AN)
 - 2. Make sure JU74B and JU118B are clean.
- (4). The copper wire is not fully attached on the braking wheel (WD48AN). Please check the part list (JY025-A)



Checking process:

- A : 1. Please check the braking wheel (WD48AN).
 - 2. Please check the creasing wheel (JU16BN) and stable the wheel by adjusting the screw
- (5). Could not thread through the upper guide. Please check the part list (JY028-A)

Check process:

- A : 1. Please check the power connects and upper guide (WA76AN), make sure there is no scratch or wire inside the guide.
 - 2. Please check the upper guide make sure there is no chip inside.
 - 3. When ATW cut the cooper wire, if the following phenmenon happened such as discharge, wire overheat, or wire apex becomes obtuse, please check the attachment
- (6). Wire will slip off after being cut. Please check the JY026-A

Check process:

- A : 1. Please check the cylinder (JU01).
 - 2. Make sure (JU91) and (JU41) are fixed .
 - 3. Make sure (JU91B) and (JU131A) are not damaged.
 - 4. Please remove the waste wire.
- (7). Unable to break the wire. Please check JY025-A

Check process:

- A : 1. Please check the cylinder (JU01) is working fine.
 - 2. Make sure JU53C and JU120A are not damaged.
 - 3. The temperature of the ATW equipment too low and the wire tension too small.
 - 4. Please check JU121 and make sure the cables are connected properly.
- (8). The braking wheel won't stop when the wire reaches the wire holder (JU91B). Please check the JY025-A

Check process:

- A : 1.Make sure the cylinder (JU01) tis working fine.
 - 2. Make sure there is no wear mark on JU107.
 - 3. Make sure the spring is not elastic fatigue.
 - 4. Make sure the cable on JU107 is connected properly.
 - 5. Make sure JU16B is clean and not being insulated.



(9). The flushing water from the upper guide is scattering. Please check the JY028-A

Check process:

- A: 1. Control the amount of water being released by adjusting valve (AJ29D).
 - 2. The upper diamond guide (WA103) is damaged.
 - 3. The upper diamond guide (WA103) and upper guide are too close to each other.
- (10). Copper wire isn't able to thread through the lower guide.

Check process:

- A : 1. Make sure there is no chip in the lower guide.
 - 2. If there is scratch or wire stock inside the lower guide, this means the lower guide is damaged.
- (11). The copper wire are not able to reach the wire recycle system while threading. Please check the JY007-A and AY050-A

Check process:

- A : 1. Please check the Z-Axis machine coordinates because it will impact the feeding length on W-Axis.
 - 2. Make sure the power connect feed (WA76DN) is not damaged.
 - 3. Please check if there is water come out from the part (WA51EN).
 - 4. Make sure no chips are in WA51EN.
 - 5. Make sure the flushing wheel (WA04CN) is working fine, otherwise please change the bearings (WA02).
 - 6. Make sure no chips are in the space from water flushing wheel (WA04CN), WAT43B to WD70BN and WD71AN.
- (12). The copper wire has difficulty passing through the wire break point.

Checking process:

- A : 1. The curvation of the wire can be an issue.
 - 2. After cutting the wire, the cut point not well.
 - 3. Verticality issue of the upper machine head
 - 4. The speed of the wire passing through the workpiece is too fast.



(13). The cooper wire have deflection condition to big.

Check process:

A: 1. Please check the Attachment 1.

Environment:

The copper wire needs to be produced within 6 months, the radian can not over 20 mm and with a length of 300 mm. Besides, the room temperature has to control with in 25° C $\pm 3^{\circ}$ C.

Do not randomly change the specification and brand of the wire. Because the quality and material of the wire produced by different companies are different, during auto threading the wire might fail to thread.

Maintain and clean regularly.



(14) Copper Wire curves irregularly

A: While heating, the color of the wire will turn red and the diameter srink due to the high temperature. Please go to 【Auto PARM】→ 《Auto Feed》 → (Auto Feed Setting 2) to increase the parameter of the heating time based on the wire condition.

- (15) Copper Wire isn't straight
 A: While heating, the curvature of the wire is too big is due to the low heating temperature. Please go to 【Auto PARM】 → 《Auto Feed》
 → (Auto Feed Setting 2) to decrease the parameter of the heating time
 - based on the wire condition.



(16) The tip of the wire becomes round after being cut.

- A: Cutting wire function is turining on too long. Please go to [Auto PARM]
 - \rightarrow 《Auto Feed》 \rightarrow (Auto Feed Setting 2) to decrease the parameter of the cuttiing time based on the wire condition.
- (17) A cross section is formed on the tip of the wire after being cut.
- A: Please go to 【Auto PARM】 → 《Auto Feed》 → (Auto Feed Setting 2) to decrease the parameter of the cuttiing time based on the wire condition.
- 1. The diameter of the hole of diamond guide is 0.255mm. Copper Wire cannot thread through if its curve irregularly.
- The distance between the diamond guide and the workpiece is 10~11mm. Please make sure the copper wire is straight enough to thread throught the workpiec





















The Agent's engineer training finished and signature:



Appendix

Appendix



Appendix 1

1.1 0	/ 01 / 10 //					
Group	G	Function	Format			
	Instruction					
00	G04	Hold (for a specified time)	G04 P_或 G04X_			
	G92	Program origin setup	G92 X_Y_Z_			
01	G00	Fast positioning	G00 X_Y_U_V_			
	G01	Linear cutting	G01 X_Y_U_V_			
	G02	Clockwise arc cutting	G02 X_Y_I_J_U_V_K_L_			
	G03	Counter clockwise arc cutting	G03 X_Y_I_J_U_V_K_L_			
03	G90	Absolute coordinate instruction	G90 (specifying absolute value coordinates)			
	G91	Increment coordinate instruction	G91 (specifying relative value coordinates)			
04	G22	Software travel limit ON	G22 X_Y_I_J_			
	G23	Software travel limit OFF	G23			
05	G94	Manual speed feed	G94 F_			
	G95	Servo speed feed	G95			
06	G20	Imperial system input	G20			
	G21	Metric system input	G21			
07	G40	Wire diameter correction cancelled	G40 X_Y_			
	G41	Wire diameter correction to left	G41 X_Y_D_,D_			
	G42	Wire diameter correction to right	G42 X_Y_D_ ,D_			
08	G50	Wire inclination cleared	G50 X_Y_			
	G51	Wire inclination to left	G51 X_Y_T_			
\mathbf{D}	G52	Wire inclination to right	G52 X_Y_T_			
09	G60	Work piece top and bottom circular	G60 X_Y_R_			
		angle are equal				
	G61	Work piece top and bottom circular	G61 X_Y_R_			
		angle are unequal				
10	G48	Automatic circular angle ON	G48			
	G49	Automatic circular angle OFF	G49			

1.1 Overview of G instructions



1.2 Over view of M instructions

M instruction	Function	Descriptions
M00	Program stops	When the program is executed to the single block of M00, the machine operation will automatically stop, the electrical discharge power, wire feed, machining liquid supply and wire tension push button switch will automatically shut off. If restart of working is required, the above 4 machining conditions should be given, then press {CYCLE START}.
M01	Selective program stops	When the program is executed to the single block of M01, if the {OPT STOP} push button on the machine operation control panel is pushed, the effect will be the same as M00, and if {OPT STOP} is not pressed, the M01 instruction will be ignored and will not be executed.
M02	Program ends	When the program is executed to the single block of M02, this means the execution of that program has ended, and the machine operation will also automatically stop, the electrical discharge power, wire feed, machining liquid supply and wire tension push button switch will automatically shut off.
M21	Single Block Hold ON	The HOLD function between single blocks is valid, the hold time is set by the Block Stop Time (unit: sec.) in the SETTING screen.
M22	Single Block Hold OFF	The HOLD function between single blocks is invalid.
M30	Program ends and reverses	When the program is executed to the single block of M30, this means the execution of that program has ended, and the machine operation will also automatically stop, the electrical discharge power, wire feed, machining liquid supply and wire tension push button switch will automatically shut off. While the program will automatically reverse.
M41	Machining power off	Electrical discharge power is off
M42	Wire feed off	Copper wire feed stops
M43	Machining liquid supply off	Machining liquid supply stops
M70	Reverse travel starts	When the program is executed to the single block of M70, the copper wire will return to the machining starting point along the cutting path.
M81	Machining power on	Electrical discharge power is on
M81	Wire feed on	Copper wire feed starts
M82	Reverse travel starts	When the program is executed to the single block of M70, the copper wire will return to the machining starting point along the cutting path.
M98	Call sub-program	Used to call sub-program from the master program
M99	Sub-program ends	Used to indicate the termination of the sub-program, and return to the master program.

WEDM Operation Manual

Cutting parameter

Wire	Material Type			Material Thickness				
0.2	Ste	eel (SKD11	1)	10 mm				
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2 .	4		17
OFF TIME	T.OFF	8	13	12	11	11		8
ARC ON	A.ON	14	4	2	1	1	0.	15
ARC OFF	A.OFF	10	15	14	13	11		10
Servo Voltage	S.V	32	50	50	45	50		32
Wire Tension	W.T	6	10	10	10	10		6
Wire Feed	W.F	10	10	10	10	10		10
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	11.0	16.0	20.0	25.0	25.0		11.0
FEED%	F.R	120	120	120	120	120		130
Upper Nozzle Gap		0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	lap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55	50~55		50~55
			X					
OFFSET No	(D)	00	01	02	03	04		00
Rough cut	A	0.150						0.152
Rough cut&1 Sl	kim	0.183	0.113					
Rough cut&2 Sl	kim	0.192	0.124	0.116				
Rough cut&3 Sl	kim	0.198	0.129	0.119	0.117			
Rough cut&4 Sl	kim	0.199	0.130	0.120	0.118	0.117		
OFFSET Difference			0.069	0.010	0.002	0.001		
	RESULTS							
Cutting Feed Ra	te (mm/min)	13.2~13.6	19.2~19.8	24.0~24.6	30.0~31.0	30.0~31.0		14.3~14.6
Gap Voltage ((GV)	43~50	60~70	60~70	55~65	55~65		42~52
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.55		3.0

Wire	Material Type			Material Thickness				
0.2	Steel (SKD11)			20 mm				
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim 4		Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2 .			17
OFF TIME	T.OFF	8	13	12	11	11		8
ARC ON	A.ON	14	4	2	1	1	0.	15
ARC OFF	A.OFF	10	15	14	13	11		10
Servo Voltage	S.V	32	50	50	45	50		32
Wire Tension	W.T	6	10	10	10	10		6
Wire Feed	W.F	10	10	10	10	10		10
Water Flow Rat	e W.F.R	7	0	0	0	0		7
G94F	FEED	5.0	8.0	11.0	12.0	12.0		5.0
FEED%	F.R	140	140	140	140	140		150
Upper Nozzle Gap		0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle (lap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55	50~55		50~55
OFFSET No	(D)	00	01	02	03	04		00
Rough cut	A	0.151						0.152
Rough cut&1 Sl	kim	0.185	0.114					
Rough cut&2 Sl	kim	0.193	0.125	0.118				
Rough cut&3 Sl	kim	0.200	0.130	0.120	0.118			
Rough cut&4 Sl	kim	0.201	0.131	0.121	0.119	0.118		
OFFSET Difference			0.070	0.010	0.002	0.001		
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	7.0~7.4	11.2~11.5	15.4~15.8	16.8~17.2	16.8~17.2		7.5~7.7
Gap Voltage ((GV)	42~50	57~68	60~70	56~68	60~70		41~52
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.55		3.0

WCUT Machning	Data Sheet
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Wire	Material Type			Material Thickness				
0.2	Steel (SKD11)			30 mm				
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO					1		
ON TIME	T.ON	16	6	4	2	1		17
OFF TIME	T.OFF	8	13	11	10	11		8
ARC ON	A.ON	14	4	2	1	1		15
ARC OFF	A.OFF	10	15	13	12	11	0.	10
Servo Voltage	S.V	30	50	50	45	50		30
Wire Tension	W.T	6	10	10	10	10		5
Wire Feed	W.F	11	10	10	10	10		11
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	3.5	4.8	6.0	7.0	7.0		3.5
FEED%	F.R	120	120	120	120	120		130
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	lap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55	50~55		50~55
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.153						0.155
Rough cut&1 Sł	kim	0.186	0.116					
Rough cut&2 Sl	kim	0.195	0.127	0.120				
Rough cut&3 Sk	kim	0.203	0.132	0.124	0.121			
Rough cut&4 Sk	kim	0.204	0.133	0.125	0.122	0.121		
OFFSET Difference -			0.071	0.008	0.003	0.001		
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	4.2~4.5	5.7~5.9	7.2~7.6	8.4~8.8	8.4~8.8		4.5~4.8
Gap Voltage ((GV)	50~60	60~70	65~75	60~70	60~70		46~55
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.6		3.0

WCUT Machning	Data Sheet
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Wire	Material Type			Material Thickness				
0.20 mm Brass			Steel (SKD11)			40 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2	1		17
OFF TIME	T.OFF	8	13	11	10	11		8
ARC ON	A.ON	14	4	2	1	1		15
ARC OFF	A.OFF	10	15	13	12	11	0.	10
Servo Voltage	S.V	28	50	50	45	50		28
Wire Tension	W.T	6	11	11	11	11		6
Wire Feed	W.F	10	10	10	10	10		11
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	3.0	4.0	5.0	5.5	5.5		3.0
FEED%	F.R	120	120	120	120	120		130
Upper Nozzle G	lap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	Bap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55	50~55		50~55
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.157						0.158
Rough cut&1 Sl	kim	0.189	0.118					
Rough cut&2 Sl	kim	0.198	0.129	0.122				
Rough cut&3 Sl	kim	0.205	0.133	0.126	0.123			
Rough cut&4 Sl	kim	0.206	0.134	0.127	0.124	0.123		
OFFSET Difference			0.072	0.007	0.003	0.001		
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	3.5~3.7	4.6~4.8	6.0~6.2	6.6~6.8	6.6~6.8		3.7~3.9
Gap Voltage ((GV)	44~55	50~59	60~70	62~74	60~70		43~52
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.57		3.0

WCUT Machning	Data Sheet
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Wire	Material Type			Material Thickness				
ø0.20 mm Brass			Steel (SKD11)			50 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2	1		17
OFF TIME	T.OFF	8	12	12	10	11		8
ARC ON	A.ON	14	4	2	1	1		15
ARC OFF	A.OFF	10	14	14	12	11	0.	10
Servo Voltage	S.V	28	50	50	40	50		25
Wire Tension	W.T	6	11	11	11	11		6
Wire Feed	W.F	10	10	10	10	10		11
Water Flow Rate	e W.F.R	3	0	0	0	0		3
G94F	FEED	2.0	2.8	3.5	4.0	4.0		2.0
FEED%	F.R	140	140	140	140	140		150
Upper Nozzle Gap		0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	lap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55	50~55		50~55
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.159						0.160
Rough cut&1 Sl	kim	0.190	0.120					
Rough cut&2 Sl	kim	0.200	0.131	0.127				
Rough cut&3 Sl	kim	0.210	0.134	0.128	0.126			
Rough cut&4 Sl	xim	0.211	0.135	0.129	0.127	0.126		
OFFSET Difference			0.076	0.006	0.002	0.001		
			RI	ESULTS				
Cutting Feed Ra	te (mm/min)	2.76~2.82	3.64~3.96	4.46~4.64	5.56~5.64	5.56~5.64		2.98~3.04
Gap Voltage ((GV)	35~45	57~67	68~75	60~70	60~70		39~50
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.5		3.0

Wire	Material Type			Material Thickness				
0.20 mm Brass			Steel (SKD11)			60 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO					1		
ON TIME	T.ON	16	6	4	2			17
OFF TIME	T.OFF	8	12	12	10	S		8
ARC ON	A.ON	14	4	2	1			15
ARC OFF	A.OFF	10	14	14	12		Ċ	10
Servo Voltage	S.V	28	50	50	40			25
Wire Tension	W.T	6	11	11	11		\mathbf{D}	6
Wire Feed	W.F	11	11	11	11			11
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	1.8	3.5	4.0	4.0			1.8
FEED%	F.R	130	130	130	130			140
Upper Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle C	Bap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega - cm)$	50~55	50~55	50~55	50~55			50~55
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.160						0.162
Rough cut&1 Sl	kim	0.192	0.121					
Rough cut&2 Sl	kim	0.201	0.132	0.128				
Rough cut&3 Sl	kim	0.212	0.136	0.129	0.127			
OFFSET Difference			0.076	0.007	0.002			
			RI	ESULTS				
Cutting Feed Ra	te (mm/min)	2.34~2.38	4.35~4.55	4.90~5.20	5.20~5.35			2.52~2.58
Gap Voltage (C	GV)	47~58	58~70	60~70	55~64			46~57
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

WCUT Machning	Data Sheet
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Wire	Dia. and Typ	e	Ν	/laterial Typ	e	Material Thickness		ness
0.2	20 mm Brass		Steel (SKD11)				70 mm	
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2			17
OFF TIME	T.OFF	9	11	11	10	S		9
ARC ON	A.ON	14	4	2	1			15
ARC OFF	A.OFF	11	13	13	12			11
Servo Voltage	S.V	28	45	45	40			28
Wire Tension	W.T	6	11	11	11			6
Wire Feed	W.F	11	11	11	11			11
Water Flow Rat	e W.F.R	7	0	0	0			7
G94F	FEED	1.2	2.1	2.6	2.6			1.3
FEED%	F.R	160	160	160	160			160
Upper Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle (Bap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega - cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.162						0.163
Rough cut&1 Sl	kim	0.193	0.123					
Rough cut&2 Sl	kim	0.203	0.133	0.129				
Rough cut&3 Sl	kim	0.215	0.136	0.130	0.128			
OFFSET Differe	ence		0.079	0.006	0.002			
			RE	ESULTS				
Cutting Feed Ra	ate (mm/min)	1.92~1.95	3.30~3.40	4.00~4.20	4.16~4.32			2.08~2.16
Gap Voltage(C	GV)	44~56	56~67	60~70	56~68			45~53
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

WCUT Machning	Data Sheet
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Wire	Dia. and Typ	e	Ν	Material Type		Material Thickness		ness
0.2	20 mm Brass		Steel (SKD11)				80 mm	
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2			17
OFF TIME	T.OFF	9	11	11	10			9
ARC ON	A.ON	14	4	3	2			15
ARC OFF	A.OFF	11	13	13	12			11
Servo Voltage	S.V	28	45	45	40			28
Wire Tension	W.T	6	11	11	12			6
Wire Feed	W.F	11	11	11	11			11
Water Flow Rat	e W.F.R	7	0	0	0			7
G94F	FEED	1.2	2.2	2.9	2.9			1.2
FEED%	F.R	130	130	130	130			140
Upper Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle (Gap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega - cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.163						0.165
Rough cut&1 Sl	kim	0.195	0.125					
Rough cut&2 Sl	kim	0.205	0.134	0.130				
Rough cut&3 Sl	kim	0.217	0.137	0.132	0.129			
OFFSET Differe	ence		0.080	0.005	0.003			
			RI	ESULTS				
Cutting Feed Ra	ate (mm/min)	1.56~1.59	2.84~2.90	3.45~3.75	3.77~3.95			1.64~1.72
Gap Voltage ((GV)	41~50	55~68	57~68	52~61			40~50
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

Wire	Dia. and Typ	e	Material Type			Material Thickness		ness
0.2	20 mm Brass		Steel (SKD11)			90 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2			17
OFF TIME	T.OFF	10	10	11	10			10
ARC ON	A.ON	14	4	3	2			15
ARC OFF	A.OFF	12	12	13	12		0.	12
Servo Voltage	S.V	28	45	45	40			28
Wire Tension	W.T	5	11	11	12			5
Wire Feed	W.F	12	12	12	12			12
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	0.9	1.7	2.2	2.2			0.9
FEED%	F.R	140	140	140	140			150
Upper Nozzle G	ap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle C	fap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega-cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.165						0.167
Rough cut&1 Sł	kim	0.197	0.127					
Rough cut&2 SI	kim	0.207	0.136	0.132				
Rough cut&3 Sk	kim	0.219	0.140	0.134	0.130			
OFFSET Differe	ence		0.079	0.006	0.004			
			RI	ESULTS				
Cutting Feed Ra	te (mm/min)	1.24~1.26	2.24~2.38	3.00~3.08	3.00~3.08			1.32~1.36
Gap Voltage ((GV)	38~50	54~64	55~68	49~60			37~50
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

WCUT Machning	Data Sheet
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Wire	Dia. and Typ	e	Ν	/laterial Typ	e	Material Thickness		ness
0.2	20 mm Brass		Steel (SKD11)				100 mm	
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2			17
OFF TIME	T.OFF	11	10	11	9	S		10
ARC ON	A.ON	14	5	3	2			15
ARC OFF	A.OFF	12	12	13	11			12
Servo Voltage	S.V	28	45	45	40			28
Wire Tension	W.T	5	11	11	12			5
Wire Feed	W.F	13	12	12	12			13
Water Flow Rat	e W.F.R	7	0	0	0			7
G94F	FEED	0.9	1.8	2.1	2.1			0.9
FEED%	F.R	120	120	120	120			130
Upper Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle C	Bap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega - cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.166						0.168
Rough cut&1 Sl	kim	0.197	0.126					
Rough cut&2 Sl	kim	0.206	0.135	0.131				
Rough cut&3 Sl	kim	0.219	0.139	0.133	0.130			
OFFSET Differe	ence		0.080	0.006	0.003			
			RI	ESULTS				
Cutting Feed Ra	te (mm/min)	1.07~1.09	2.13~2.16	2.48~2.52	2.52~2.56			1.15~1.18
Gap Voltage ((GV)	36~50	53~63	57~70	46~58			34~55
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

WCUT Machning	Data Sheet
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Wire	Dia. and Typ	e	N	Aaterial Typ	e	Material Thickness		ness
0.2	0 mm Brass		Copper				10 mm	
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO					1		
ON TIME	T.ON	16	6	4	2	1		18
OFF TIME	T.OFF	10	13	13	12	11		11
ARC ON	A.ON	12	4	2	1	1		14
ARC OFF	A.OFF	12	15	15	14	11		13
Servo Voltage	S.V	38	45	50	50	50		38
Wire Tension	W.T	6	9	9	10	10	\mathbf{D}	6
Wire Feed	W.F	9	10	10	10	10		9
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	13.0	20.0	24.0	24.0	24.0		13.0
FEED%	F.R	120	120	120	120	120		140
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle G	lap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55	50~55		50~55
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.166						0.168
Rough cut&1 Sk	xim	0.195	0.126					
Rough cut&2 Sk	<i>c</i> im	0.201	0.133	0.125				
Rough cut&3 Sk	xim	0.203	0.135	0.128	0.125			
Rough cut&4 Sk	tim	0.204	0.136	0.129	0.126	0.125		
OFFSET Differe	ence		0.068	0.007	0.003	0.001		
			RF	ESULTS				
Cutting Feed Ra	te (mm/min)	15.4~15.7	23.5~24.5	28.6~29.2	28.8~29.4	28.8~29.4		18.0~18.4
Gap Voltage (C	(VC	41~50	50~61	55~68	58~70	60~70		42~53
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.55		3.0

WCUT Machning	Data Sheet
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Wire	Dia. and Typ	e	Ν	Material Type			Material Thickness	
0.2	0 mm Brass		Copper				20 mm	
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO					1		
ON TIME	T.ON	16	6	4	2	1		18
OFF TIME	T.OFF	9	13	13	12	11		11
ARC ON	A.ON	12	4	2	1	1		14
ARC OFF	A.OFF	11	15	15	14	11	0.	13
Servo Voltage	S.V	38	45	50	50	50		38
Wire Tension	W.T	6	9	9	10	10		6
Wire Feed	W.F	9	10	10	10	10		9
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	7.5	10.0	13.0	13.0	13.0		7.5
FEED%	F.R	100	100	100	100	100		120
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	lap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55	50~55		50~55
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.167						0.169
Rough cut&1 Sł	kim	0.196	0.127					
Rough cut&2 Sl	kim	0.202	0.134	0.127				
Rough cut&3 Sl	kim	0.205	0.135	0.129	0.126			
Rough cut&4 Sł	kim	0.206	0.136	0.130	0.127	0.126		
OFFSET Differe	ence		0.070	0.006	0.003	0.001		
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	7.4~7.9	9.5~10.5	12.8~13.6	13.0~14.0	13.0~14.0		8.9~9.6
Gap Voltage ((GV)	40~49	50~58	55~68	60~70	60~70		42~49
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.57		3.0

WCUT Machning	Data Sheet
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Wire	Dia. and Typ	e	Ν	Aaterial Typ	e	Mat	ness		
0.2	20 mm Brass			Copper			30 mm		
Cutting Process		Stable						Max	
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut	
EDM Number	NO					1			
ON TIME	T.ON	16	6	4	2	1		18	
OFF TIME	T.OFF	9	13	13	11	11		10	
ARC ON	A.ON	13	4	2	1	1		15	
ARC OFF	A.OFF	11	15	15	13	11	0.	12	
Servo Voltage	S.V	35	45	50	45	50		35	
Wire Tension	W.T	6	10	10	11	11		6	
Wire Feed	W.F	9	10	10	10	10		9	
Water Flow Rate	e W.F.R	7	0	0	0	0		7	
G94F	FEED	5.0	8.5	12.0	12.0	12.0		5.0	
FEED%	F.R	110	110	110	110	110		120	
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2	
Lower Nozzle C	lap	0.2	0.2	0.2	0.2	0.2		0.2	
Liquid Quantity	$(K\Omega - cm)$	50~55	50~55	50~55	50~55	50~55		50~55	
OFFSET No	(D)	00	01	02	03	04		00	
Rough cut		0.169						0.171	
Rough cut&1 Sł	kim	0.197	0.129						
Rough cut&2 Sl	kim	0.202	0.134	0.128					
Rough cut&3 Sł	kim	0.206	0.135	0.130	0.127				
Rough cut&4 Sk	kim	0.207	0.136	0.131	0.128	0.127			
OFFSET Differe	ence		0.071	0.005	0.003	0.001			
			RI	ESULTS					
Cutting Feed Ra	te (mm/min)	5.4~5.6	9.3~9.8	13.0~13.4	13.1~13.6	13.1~13.6		5.8~6.5	
Gap Voltage (C	GV)	39~46	50~60	60~70	60~70	60~70		40~50	
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20	
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.6		3.0	

WCUT Machning	Data Sheet
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Wire Dia. and Type			Material Type			Material Thickness		
0.20 mm Brass		Copper			40 mm			
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2	1		18
OFF TIME	T.OFF	9	12	12	11	11		10
ARC ON	A.ON	13	4	2	1	1		15
ARC OFF	A.OFF	11	14	14	13	11	0.	12
Servo Voltage	S.V	35	45	50	50	50		35
Wire Tension	W.T	6	10	10	11	11		6
Wire Feed	W.F	10	10	10	10	10		10
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	3.0	4.0	5.1	5.1	5.1		3.0
FEED%	F.R	140	140	140	140	140		160
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	lap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55	50~55		50~55
)					
OFFSET No	(D)	-00	01	02	03	04		00
Rough cut		0.170						0.172
Rough cut&1 Sk	kim	0.198	0.130					
Rough cut&2 Sk	kim	0.203	0.135	0.128				
Rough cut&3 Sk	kim	0.208	0.136	0.131	0.128			
Rough cut&4 Sk	xim	0.209	0.137	0.132	0.129	0.128		
OFFSET Differe	ence		0.072	0.005	0.003	0.001		
RESULTS								
Cutting Feed Rate (mm/min) 4.15~4.26		5.50~5.70	7.10~7.24	7.14~7.26	7.14~7.26		4.70~4.90	
Gap Voltage ((GV)	42~50	50~60	58~69	60~70	60~70		42~53
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.58		3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type		Material Type			Material Thickness			
0.20 mm Brass		Copper			50 mm			
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Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2	1		18
OFF TIME	T.OFF	8	12	12	10	11		9
ARC ON	A.ON	14	4	2	1	1		16
ARC OFF	A.OFF	10	14	14	12	11	0.	10
Servo Voltage	S.V	30	50	55	45	50		30
Wire Tension	W.T	6	10	11	13	11		6
Wire Feed	W.F	10	10	10	11	11		10
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	2.5	3.5	4.3	4.3	4.3		2.5
FEED%	F.R	140	140	140	140	140		160
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle Gap		0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	50~60	50~60	50~60	50~60	50~60		50~60
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.172						
Rough cut&1 Sl	kim	0.200	0.132					
Rough cut&2 Sl	kim	0.205	0.137	0.130				
Rough cut&3 Sl	kim	0.210	0.138	0.132	0.129			
Rough cut&4 Sl	kim	0.211	0.138	0.133	0.130	0.129		
OFFSET Differe	ence		0.072	0.006	0.003	0.001		
RESULTS								
Cutting Feed Rate (mm/min) 3.43~3.65		4.85~5.14	5.97~6.08	5.98~6.12	5.98~6.12		3.96~4.05	
Gap Voltage ((GV)	40~50	60~70	60~70	60~70	60~70		40~50
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.6		3.0
WCUT Machning	Data Sheet							
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Wire Dia. and Type		Material Type			Material Thickness			
0.2	20 mm Brass		Copper			60 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO					5		
ON TIME	T.ON	16	6	4	2			18
OFF TIME	T.OFF	8	12	12	10	S		9
ARC ON	A.ON	14	4	2	1			16
ARC OFF	A.OFF	10	14	14	12			10
Servo Voltage	S.V	33	50	55	45			33
Wire Tension	W.T	6	10	11	13		\mathbf{D}	6
Wire Feed	W.F	10	10	10	11			10
Water Flow Rat	e W.F.R	7	0	0	0			7
G94F	FEED	2.5	3.5	4.3	4.3			2.5
FEED%	F.R	110	130	130	130			130
Upper Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle (Bap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega - cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.173						0.175
Rough cut&1 Sl	kim	0.201	0.132					
Rough cut&2 Sl	kim	0.206	0.137	0.130				
Rough cut&3 Sl	kim	0.210	0.138	0.133	0.130			
OFFSET Differ	ence		0.072	0.005	0.003			
RESULTS								
Cutting Feed Ra	ate (mm/min)	2.71~2.82	4.48~5.63	5.55~5.72	5.59~5.86			3.18~3.43
Gap Voltage (0	GV)	38~47	49~56	60~70	58~72			39~49
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type		Material Type			Material Thickness			
0.20 mm Brass		Copper			70 mm			
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO					1		
ON TIME	T.ON	16	6	4	2			18
OFF TIME	T.OFF	9	11	12	10	S		10
ARC ON	A.ON	14	4	2	1			16
ARC OFF	A.OFF	11	13	13	12			12
Servo Voltage	S.V	32	45	50	45			32
Wire Tension	W.T	6	11	11	12			6
Wire Feed	W.F	11	11	11	11			11
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	2.2	3.2	4.0	4.0			2.5
FEED%	F.R	100	100	100	100			100
Upper Nozzle G	ap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle C	fap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55			50~55
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.175						0.177
Rough cut&1 Sł	kim	0.205	0.134					
Rough cut&2 Sl	kim	0.210	0.139	0.133				
Rough cut&3 Sk	kim	0.215	0.142	0.135	0.132			
OFFSET Differe	ence		0.073	0.007	0.003			
·								
RESULTS								
Cutting Feed Ra	te (mm/min)	2.16~2.26	3.15~3.26	3.95~4.16	4.00~4.16			2.48~2.58
Gap Voltage (C	GV)	38~49	50~60	59~70	60~70			42~50
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type		Material Type			Material Thickness			
0.20 mm Brass		Copper			80 mm			
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2			18
OFF TIME	T.OFF	9	11	12	10	S		10
ARC ON	A.ON	14	4	2	1			16
ARC OFF	A.OFF	11	13	13	12		0.	12
Servo Voltage	S.V	32	45	50	45			32
Wire Tension	W.T	6	11	11	12			6
Wire Feed	W.F	11	11	11	11			11
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	1.9	2.8	3.6	3.6			2.1
FEED%	F.R	100	100	100	100			100
Upper Nozzle G	ap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega-cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.176						0.178
Rough cut&1 Sk	xim	0.206	0.135					
Rough cut&2 Sk	xim	0.210	0.140	0.133				
Rough cut&3 Sk	kim	0.215	0.143	0.136	0.132			
OFFSET Differe	ence		0.072	0.007	0.004			
·								
RESULTS								
Cutting Feed Ra	te (mm/min)	1.85~1.92	2.76~2.88	3.58~3.76	3.60~3.78			2.06~2.16
Gap Voltage (C	(VC	37~50	49~59	60~70	60~70			40~50
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type		Material Type			Material Thickness			
0.20 mm Brass		Copper			90 mm			
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2			18
OFF TIME	T.OFF	10	11	11	11			11
ARC ON	A.ON	14	5	3	2			16
ARC OFF	A.OFF	12	13	13	12			13
Servo Voltage	S.V	32	45	45	40			32
Wire Tension	W.T	7	11	11	12			7
Wire Feed	W.F	12	12	12	12			12
Water Flow Rat	e W.F.R	7	0	0	0			7
G94F	FEED	1.4	2.5	3.2	3.3			1.4
FEED%	F.R	110	110	110	110			120
Upper Nozzle G	lap	0.2	0.2	0.1	0.1			0.2
Lower Nozzle C	Bap	0.2	0.2	0.1	0.2			0.2
Liquid Quantity	$(K\Omega - cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.178						0.180
Rough cut&1 Sl	kim	0.209	0.137					
Rough cut&2 Sl	kim	0.213	0.142	0.134				
Rough cut&3 Sl	kim	0.218	0.146	0.138	0.134			
OFFSET Differe	ence		0.072	0.008	0.004			
	RESULTS							
Cutting Feed Ra	te (mm/min)	1.52~1.58	2.73~2.85	3.52~3.63	3.63~3.70			1.65~1.72
Gap Voltage((GV)	38~50	48~59	50~60	55~65			39~52
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

Wire Dia. and Type		Material Type			Material Thickness			
0.20 mm Brass		Copper			100 mm			
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO					1		
ON TIME	T.ON	16	6	4	2			18
OFF TIME	T.OFF	10	11	11	11			11
ARC ON	A.ON	14	5	3	2			16
ARC OFF	A.OFF	12	13	13	12		0.	13
Servo Voltage	S.V	32	45	45	40			32
Wire Tension	W.T	7	11	11	12			7
Wire Feed	W.F	12	12	12	12			12
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	1.4	2.5	3.2	3.3			1.4
FEED%	F.R	100	100	100	100			110
Upper Nozzle G	ap	0.2	0.2	0.1	0.1			0.2
Lower Nozzle G	lap	0.2	0.2	0.1	0.2			0.2
Liquid Quantity	$(K\Omega-cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.179						0.181
Rough cut&1 Sk	cim	0.211	0.138					
Rough cut&2 Sk	<i>i</i> m	0.215	0.143	0.135				
Rough cut&3 Sk	tim	0.220	0.147	0.139	0.135			
OFFSET Differe	ence		0.073	0.008	0.004			
RESULTS								
Cutting Feed Rat	te (mm/min)	1.38~1.44	2.50~2.60	3.20~3.30	3.30~3.40			1.50~1.56
Gap Voltage (C	(VC	37~56	45~56	50~62	58~68			36~46
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type		Material Type			Material Thickness			
0.20 mm Brass		Aluminium			10 mm			
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO					1		
ON TIME	T.ON	13	6	4	2	1		14
OFF TIME	T.OFF	12	13	13	13	11		13
ARC ON	A.ON	10	4	2	1	1		12
ARC OFF	A.OFF	14	15	15	15	11		15
Servo Voltage	S.V	50	55	55	55	50		50
Wire Tension	W.T	6	8	8	8	10	\mathbf{D}	6
Wire Feed	W.F	9	10	10	10	10		9
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	10	15	20	25	25.0		10
FEED%	F.R	120	120	120	120	120		130
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle G	lap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55	50~55		50~55
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.168						0.170
Rough cut&1 Sk	kim	0.195	0.125					
Rough cut&2 Sk	kim	0.205	0.137	0.121				
Rough cut&3 Sk	kim	0.215	0.148	0.127	0.120			
Rough cut&4 Sk	xim	0.216	0.149	0.128	0.121	0.120		
OFFSET Differe	ence		0.067	0.021	0.003	0.001		
	RESULTS							
Cutting Feed Ra	te (mm/min)	12.0~13.5	18.0~19.6	24.0~25.0	30.0~32.0	30.0~32.0		13.0~14.0
Gap Voltage (C	GV)	58~65	70~80	75~80	70~75	70~75		60~70
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.55		3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type			Material Type			Material Thickness		
0.2	20 mm Brass		Aluminium			20 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO					1		
ON TIME	T.ON	13	6	4	2	1		14
OFF TIME	T.OFF	12	13	13	13	11		13
ARC ON	A.ON	10	4	2	1	1		12
ARC OFF	A.OFF	14	15	15	15	11	0.	15
Servo Voltage	S.V	50	55	55	50	50		50
Wire Tension	W.T	6	8	8	8	10		6
Wire Feed	W.F	9	10	10	10	10		9
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	6.0	8.0	10.0	12.5	12.5		6.0
FEED%	F.R	120	120	120	120	120		140
Upper Nozzle G	lap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	Bap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55	50~55		50~55
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.173						0.175
Rough cut&1 SI	kim	0.202	0.129					
Rough cut&2 SI	kim	0.210	0.144	0.124				
Rough cut&3 Sl	kim	0.220	0.150	0.130	0.122			
Rough cut&4 SI	kim	0.221	0.151	0.131	0.123	0.122		
OFFSET Differe	ence		0.070	0.020	0.008	0.001		
			RI	ESULTS				
Cutting Feed Ra	te (mm/min)	7.2~8.4	9.6~10.8	12.0~13.6	15.0~16.8	15.0~16.8		8.4~9.6
Gap Voltage ((GV)	57~63	70~75	70~80	65~75	65~75		58~65
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.58		3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type			Material Type			Material Thickness		
0.2	0 mm Brass		Aluminium			30 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO					1		
ON TIME	T.ON	14	6	4	2	1		16
OFF TIME	T.OFF	12	13	13	11	11		12
ARC ON	A.ON	12	4	2	1	1		14
ARC OFF	A.OFF	14	15	15	13	11		14
Servo Voltage	S.V	45	55	55	50	50		45
Wire Tension	W.T	6	8	8	9	10		6
Wire Feed	W.F	9	10	10	10	10		9
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	4.0	6.0	8.0	10.0	10.0		4.0
FEED%	F.R	150	150	150	150	120		170
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	lap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55	50~55		50~55
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.178						0.180
Rough cut&1 Sł	kim	0.205	0.132					
Rough cut&2 Sł	kim	0.215	0.145	0.127				
Rough cut&3 Sł	kim	0.225	0.152	0.132	0.124			
Rough cut&4 Sk	xim	0.226	0.153	0.133	0.125	0.124		
OFFSET Differe	ence		0.073	0.020	0.008	0.001		
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	6.0~6.8	9.0~10.3	12.0~13.6	15.0~16.0	15.0~16.0		6.8~7.6
Gap Voltage ((GV)	52~60	65~75	70~75	60~70	60~70		58~65
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.59		3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type			Material Type			Material Thickness		
0.2	0 mm Brass		Aluminium			40 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO							
ON TIME	T.ON	14	6	4	2	1		16
OFF TIME	T.OFF	12	12	11	10	11		12
ARC ON	A.ON	12	4	2	1	1		14
ARC OFF	A.OFF	14	14	13	12	11		14
Servo Voltage	S.V	45	55	55	50	50		45
Wire Tension	W.T	6	9	10	10	11		5
Wire Feed	W.F	9	11	11	11	11		9
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	3.0	4.5	6.0	7.5	7.5		3.0
FEED%	F.R	150	150	150	150	150		170
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	lap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55	50~55		50~55
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.182						0.184
Rough cut&1 Sł	kim	0.220	0.134					
Rough cut&2 Sł	kim	0.235	0.150	0.128				
Rough cut&3 Sł	kim	0.245	0.155	0.132	0.125			
Rough cut&4 Sk	xim	0.255	0.156	0.133	0.126	0.125		
OFFSET Differe	ence		0.090	0.023	0.007	0.001		
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	4.5~4.9	6.7~7.3	9.0~10.0	11.0~12.5	11.0~12.5		4.7~5.2
Gap Voltage((GV)	51~59	60~70	60~70	57~68	57~68		55~65
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.6		3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type			Material Type			Material Thickness		
0.2	20 mm Brass		Aluminium			50 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO							
ON TIME	T.ON	14	6	4	2	1		16
OFF TIME	T.OFF	12	12	11	10	11		12
ARC ON	A.ON	12	4	2	1	1		14
ARC OFF	A.OFF	14	14	13	12	11	0.	14
Servo Voltage	S.V	40	55	55	50	50		45
Wire Tension	W.T	6	9	10	10	11		6
Wire Feed	W.F	9	11	11	11	11		9
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	2.5	3.6	4.8	6.0	6.0		2.5
FEED%	F.R	150	150	150	150	150		170
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	Jap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	55~60	55~60	55~60	55~60	55~60		55~60
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.186						0.189
Rough cut&1 Sl	kim	0.230	0.136					
Rough cut&2 Sl	kim	0.235	0.155	0.130				
Rough cut&3 Sl	kim	0.240	0.157	0.132	0.127			
Rough cut&4 SI	kim	0.241	0.158	0.133	0.128	0.127		
OFFSET Differe	ence		0.083	0.025	0.005	0.001		
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	3.75~4.25	5.4~6.2	7.2~8.0	8.4~9.4	8.4~9.4		4.25~4.80
Gap Voltage ((GV)	48~58	65~75	65~75	55~65	55~65		48~59
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.57		3.0

Wire Dia. and Type			Material Type			Material Thickness		
0.2	20 mm Brass		Aluminium			60 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO							
ON TIME	T.ON	14	6	4	2	1		16
OFF TIME	T.OFF	11	12	11	10	11		11
ARC ON	A.ON	12	4	2	1	1		14
ARC OFF	A.OFF	13	14	13	12	11	0.	13
Servo Voltage	S.V	40	55	55	50	50		45
Wire Tension	W.T	6	9	10	10	11		6
Wire Feed	W.F	9	11	11	11	11		9
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	2.5	3.6	4.8	6.0	6.0		2.5
FEED%	F.R	120	120	120	120	120		140
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	fap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55	50~55		50~55
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.188						0.190
Rough cut&1 Sl	kim	0.232	0.138					
Rough cut&2 Sl	kim	0.236	0.155	0.131				
Rough cut&3 Sl	kim	0.242	0.158	0.134	0.129			
Rough cut&4 Sl	kim	0.243	0.159	0.135	0.130	0.129		
OFFSET Differe	ence		0.084	0.024	0.005	0.001		
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	3.0~3.2	4.2~4.5	5.7~5.9	7.2~7.5	7.2~7.5		3.5~3.6
Gap Voltage ((GV)	45~55	63~75	65~75	59~70	59~70		48~60
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.58		3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type			Material Type			Material Thickness		
0.2	20 mm Brass		Aluminium			70 mm		
-								
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	14	6	4	2			16
OFF TIME	T.OFF	11	12	11	10			12
ARC ON	A.ON	12	14	2	1			14
ARC OFF	A.OFF	13	14	13	12			14
Servo Voltage	S.V	40	50	50	45			45
Wire Tension	W.T	6	10	10	10			6
Wire Feed	W.F	10	11	11	11			10
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	2.0	3.0	4.0	5.0			2.0
FEED%	F.R	120	120	120	120			130
Upper Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle C	Bap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega - cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.190						0.192
Rough cut&1 Sl	kim	0.233	0.139					
Rough cut&2 Sl	kim	0.238	0.156	0.132				
Rough cut&3 Sl	kim	0.243	0.160	0.135	0.130			
OFFSET Differe	ence		0.083	0.025	0.005			
			RE	ESULTS	1		1	
Cutting Feed Ra	te (mm/min)	2.4~2.6	3.6~3.9	4.8~5.0	6.0~6.4			2.6~2.8
Gap Voltage ((GV)	47~56	58~69	60~70	55~67			49~60
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

Wire Dia. and Type			Material Type			Material Thickness		
0.20 mm Brass			Aluminium			80 mm		
-								
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	14	6	4	2			16
OFF TIME	T.OFF	11	12	11	10	S		11
ARC ON	A.ON	12	4	3	2			14
ARC OFF	A.OFF	13	14	13	12			13
Servo Voltage	S.V	40	50	50	45			40
Wire Tension	W.T	7	11	11	12			7
Wire Feed	W.F	10	11	11	11			11
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	2.0	3.0	4.0	5.0			2.2
FEED%	F.R	100	100	100	100			100
Upper Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle C	Bap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega - cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.191						0.193
Rough cut&1 Sł	kim	0.235	0.139					
Rough cut&2 Sl	kim	0.239	0.156	0.133				
Rough cut&3 Sk	kim	0.245	0.162	0.136	0.131			
OFFSET Differe	ence		0.083	0.026	0.005			
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	2.0~2.1	3.0~3.4	4.0~4.5	5.0~5.6			2.2~2.3
Gap Voltage (C	GV)	46~55	55~68	60~70	58~69			46~59
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type			Material Type			Material Thickness		
0.2	0 mm Brass		Aluminium			90 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	14	6	4	2			16
OFF TIME	T.OFF	11	11	11	10	S		11
ARC ON	A.ON	12	4	3	2			14
ARC OFF	A.OFF	13	13	13	12			13
Servo Voltage	S.V	40	45	45	40			40
Wire Tension	W.T	7	11	11	12			7
Wire Feed	W.F	10	11	11	11			11
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	1.2	2.0	2.4	3.0			1.4
FEED%	F.R	140	140	140	140			140
Upper Nozzle G	ap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega-cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.193						0.194
Rough cut&1 Sk	xim	0.236	0.141					
Rough cut&2 Sk	xim	0.240	0.156	0.134				
Rough cut&3 Sk	xim	0.247	0.163	0.137	0.132			
OFFSET Differe	ence		0.084	0.026	0.005			
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	1.68~1.74	2.78~2.86	3.36~3.48	4.20~4.40			1.94~2.04
Gap Voltage (C	(VC	46~55	58~69	60~70	48~56			44~57
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

Wire Dia. and Type			Material Type			Material Thickness		
0.2	0 mm Brass		Aluminium			100 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	14	6	4	2			16
OFF TIME	T.OFF	11	11	11	9	S		11
ARC ON	A.ON	12	4	3	2			14
ARC OFF	A.OFF	13	13	13	11			13
Servo Voltage	S.V	40	45	45	40			40
Wire Tension	W.T	7	11	11	12			7
Wire Feed	W.F	11	12	12	12			12
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	1.0	1.6	1.8	2.0			1.1
FEED%	F.R	150	150	150	150			150
Upper Nozzle G	ap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega - cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.193						
Rough cut&1 Sk	cim	0.237	0.141					
Rough cut&2 Sk	<i>cim</i>	0.240	0.158	0.136				
Rough cut&3 Sk	cim	0.247	0.164	0.139	0.134			
OFFSET Differe	ence		0.083	0.025	0.005			
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	1.50~1.53	2.40~2.46	2.70~2.78	3.00~3.04			1.63~1.67
Gap Voltage (C	(VC	43~56	55~68	58~70	46~59			44~55
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type			Material Type			Material Thickness		
0.25 mm Brass			Steel (SKD11)			10 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO					1		
ON TIME	T.ON	16	6	4	2	1		16
OFF TIME	T.OFF	12	13	15	13	11		10
ARC ON	A.ON	14	4	2	1	1		16
ARC OFF	A.OFF	14	15	17	15	11	0.	12
Servo Voltage	S.V	30	40	45	50	50		30
Wire Tension	W.T	8	11	11	11	11		8
Wire Feed	W.F	11	10	10	10	10		11
Water Flow Rat	e W.F.R	7	0	0	0	0		7
G94F	FEED	7.5	10.0	10	12	12.0		7.5
FEED%	F.R	130	120	140	140	140		145
Upper Nozzle G	lap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle (Bap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	55~60	55~60	55~60	55~60	55~60		55~60
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.161						0.160
Rough cut&1 Sl	kim	0.205	0.142					
Rough cut&2 Sl	kim	0.210	0.145	0.141				
Rough cut&3 Sl	kim	0.213	0.149	0.144	0.140			
Rough cut&4 Sl	kim	0.214	0.150	0.145	0.141	0.140		
OFFSET Different	ence		0.061	0.005	0.004	0.001		
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	9.5~11.5	11.0~13.0	12.0~14.0	12.0~14.0	12.0~14.0		10.5~12.5
Gap Voltage ((GV)	40~48	50~60	55~65	70~80	70~80		48~58
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.55		3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type			Material Type			Material Thickness		
0.25 mm Brass			Steel (SKD11)			20 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2	1		18
OFF TIME	T.OFF	8	12	12	12	11		8
ARC ON	A.ON	14	4	2	1	1		16
ARC OFF	A.OFF	10	14	14	14	11	0.	10
Servo Voltage	S.V	30	45	50	50	50		28
Wire Tension	W.T	8	11	12	12	12		8
Wire Feed	W.F	11	10	11	10	10		11
Water Flow Rat	e W.F.R	7	0	0	0	0		7
G94F	FEED	4.5	6	7	12	12.0		4.5
FEED%	F.R	140	150	150	120	120		170
Upper Nozzle G	lap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle (Bap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega - cm)$	55~65	55~65	55~65	55~65	55~65		55~65
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.163						0.160
Rough cut&1 Sl	kim	0.205	0.139					
Rough cut&2 Sl	kim	0.215	0.143	0.140				
Rough cut&3 Sl	kim	0.219	0.148	0.143	0.141			
Rough cut&4 Sl	kim	0.220	0.149	0.144	0.142	0.141		
OFFSET Differ	ence		0.071	0.005	0.002	0.001		
			RI	ESULTS				
Cutting Feed Ra	ate (mm/min)	6.0~7.5	9.0~11.0	11.0~13.0	10.0~12.0	10.0~12.0		7.5~8.0
Gap Voltage (0	GV)	38~45	45~55	50~65	50~65	50~65		38~45
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.57		3.0

Wire Dia. and Type			Material Type			Material Thickness		
0.25 mm Brass			Steel (SKD11)			30 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2	1		18
OFF TIME	T.OFF	9	13	15	11	11		9
ARC ON	A.ON	14	4	2	1	1		16
ARC OFF	A.OFF	11	15	17	13	11	0.	11
Servo Voltage	S.V	30	40	45	45	50		26
Wire Tension	W.T	8	11	11	11	11		8
Wire Feed	W.F	10	10	10	10	10		10
Water Flow Rat	e W.F.R	7	0	0	0	0		7
G94F	FEED	3.0	7.5	9.0	9.0	9.0		3.0
FEED%	F.R	160	100	100	100	100		180
Upper Nozzle C	lap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle (Gap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega - cm)$	50~60	50~60	50~60	50~60	50~60		50~60
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.166						0.167
Rough cut&1 Sl	kim	0.205	0.140					
Rough cut&2 Sl	kim	0.216	0.150	0.144				
Rough cut&3 Sl	kim	0.220	0.156	0.149	0.147			
Rough cut&4 Sl	kim	0.221	0.157	0.150	0.148	0.147		
OFFSET Difference			0.064	0.007	0.002	0.001		
			RE	ESULTS			1	
Cutting Feed Ra	ate (mm/min)	4.3~5.0	7.2~8.2	8.5~9.6	8.5~9.6	8.5~9.6		4.5~5.8
Gap Voltage((GV)	40~50	50~60	52~63	53~64	53~64		35~45
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.57		3.0

Wire Dia. and Type			Material Type			Material Thickness		
0.25 mm Brass			Steel (SKD11)			40 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO					1		
ON TIME	T.ON	16	6	4	2	1		18
OFF TIME	T.OFF	9	13	15	11	11		9
ARC ON	A.ON	14	4	2	1	1		16
ARC OFF	A.OFF	11	15	17	13	11	0.	11
Servo Voltage	S.V	26	40	45	45	50		26
Wire Tension	W.T	8	11	11	11	11		8
Wire Feed	W.F	10	10	10	10	10		10
Water Flow Rat	e W.F.R	7	0	0	0	0		7
G94F	FEED	2.5	6.0	8.5	8.5	8.5		2.5
FEED%	F.R	130	110	110	110	110		160
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	fap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	50~62	50~62	50~62	50~62	50~62		50~62
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.167						0.168
Rough cut&1 Sl	kim	0.206	0.142					
Rough cut&2 Sl	kim	0.217	0.151	0.145				
Rough cut&3 Sl	kim	0.222	0.157	0.150	0.148			
Rough cut&4 Sl	kim	0.223	0.128	0.151	0.149	0.148		
OFFSET Different	ence		0.0065	0.007	0.002	0.001		
			RI	ESULTS				
Cutting Feed Ra	te (mm/min)	3.0~3.5	6.8~7.5	8.9~9.5	8.9~9.5	8.9~9.5		3.9~4.3
Gap Voltage ((GV)	38~46	45~54	60~70	60~70	60~70		38~46
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.59		3.0

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Wire Dia. and Type		Material Type			Material Thickness			
0.2	5 mm Brass		Steel (SKD11)			50 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2	1		18
OFF TIME	T.OFF	8	13	13	10	11		10
ARC ON	A.ON	14	4	2	1	1		16
ARC OFF	A.OFF	10	15	15	11	11		11
Servo Voltage	S.V	28	40	45	45	50		28
Wire Tension	W.T	8	12	12	12	12		8
Wire Feed	W.F	10	10	11	11	11		10
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	1.8	3	4	5	5.0		1.7
FEED%	F.R	160	150	150	150	150		180
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	lap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	55~60	55~60	55~60	55~60	55~60		55~60
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.170						0.171
Rough cut&1 Sł	xim	0.210	0.143					
Rough cut&2 Sl	xim	0.218	0.150	0.144				
Rough cut&3 Sł	kim	0.224	0.158	0.151	0.149			
Rough cut&4 Sk	tim	0.225	0.159	0.152	0.150	0.149		
OFFSET Differe	ence		0.066	0.007	0.002	0.001		
	RE	ESULTS						
Cutting Feed Ra	te (mm/min)	2.66~2.80	4.3~5.2	5.5~6.3	7.2~7.9	7.2~7.9		2.9~3.3
Gap Voltage (C	(VC	44~51	54~62	65~73	65~73	65~73		35~45
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.58		3.0

WCUT Machning	Data Sheet
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Wire	Dia. and Typ	e	Material Type			Material Thickness		
0.2	25 mm Brass		Steel (SKD11)			60 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO					1		
ON TIME	T.ON	16	6	4	2			18
OFF TIME	T.OFF	8	13	14	9	S		9
ARC ON	A.ON	14	4	2	1			16
ARC OFF	A.OFF	10	15	16	11			11
Servo Voltage	S.V	28	40	45	45			30
Wire Tension	W.T	8	11	12	12			8
Wire Feed	W.F	10	10	10	11			11
Water Flow Rat	e W.F.R	7	0	0	0			7
G94F	FEED	1.5	2.0	3.0	3.2			1.6
FEED%	F.R	160	160	130	130			160
Upper Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle (Bap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega - cm)$	40~55	40~55	40~55	40~55			40~55
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.172						0.173
Rough cut&1 Sl	kim	0.214	0.145					
Rough cut&2 Sl	kim	0.221	0.152	0.146				
Rough cut&3 Sl	kim	0.226	0.159	0.153	0.150			
OFFSET Differe	ence		0.067	0.006	0.003			
			RI	ESULTS				
Cutting Feed Ra	ate (mm/min)	2.15~2.35	3.0~3.6	3.75~3.96	4.10~4.42			2.45~2.60
Gap Voltage((GV)	36~46	46~54	50~59	60~68			40~47
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

Wire Dia. and Type		Material Type			Material Thickness			
0.2	5 mm Brass		Ste	el (SKD11)	70 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2			18
OFF TIME	T.OFF	8	12	12	10			8
ARC ON	A.ON	14	4	2	1			16
ARC OFF	A.OFF	9	14	14	11			10
Servo Voltage	S.V	30	40	43	43			28
Wire Tension	W.T	9	11	11	12			9
Wire Feed	W.F	11	11	11	11			11
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	1.3	2.0	2.8	3.0			1.4
FEED%	F.R	160	140	150	150			170
Upper Nozzle G	ap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55			50~55
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.173						0.174
Rough cut&1 Sk	cim	0.216	0.147					
Rough cut&2 Sk	<i>i</i> m	0.223	0.158	0.148				
Rough cut&3 Sk	tim	0.227	0.160	0.155	0.151			
OFFSET Differe	ence		0.067	0.005	0.004			
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	2.0~2.33	2.75~2.88	4.1~4.5	4.4~4.7			2.33~2.56
Gap Voltage (G	(VC	38~45	50~55	50~55	54~60			41~48
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

Wire Dia. and Type		e	Ν	Aaterial Typ	e	Material Thickness		
0.2	5 mm Brass		Steel (SKD11)			80 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2			18
OFF TIME	T.OFF	8	12	12	10	S		8
ARC ON	A.ON	14	4	2	1			16
ARC OFF	A.OFF	9	14	14	11			10
Servo Voltage	S.V	30	40	43	43			28
Wire Tension	W.T	9	11	11	12		\mathbf{D}	9
Wire Feed	W.F	11	11	11	11			11
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	1.1	1.6	2.2	2.2			1.2
FEED%	F.R	160	160	160	160			190
Upper Nozzle G	ap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55			50~55
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.175						0.176
Rough cut&1 Sk	cim	0.217	0.148					
Rough cut&2 Sk	<i>xim</i>	0.224	0.160	0.150				
Rough cut&3 Sk	cim	0.228	0.167	0.156	0.152			
OFFSET Differe	ence		0.061	0.011	0.004			
· · · · · ·								
			RI	ESULTS				
Cutting Feed Ra	te (mm/min)	1.73~1.78	2.53~2.58	3.49~3.55	3.51~3.66			2.03~2.38
Gap Voltage (C	(VC	34~44	45~53	47~55	50~59			37~46
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

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Wire Dia. and Type		e	Ν	/laterial Typ	e	Material Thickness		
0.2	25 mm Brass		Steel (SKD11)			90 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO					1		
ON TIME	T.ON	16	6	4	2			18
OFF TIME	T.OFF	8	12	10	9	S		8
ARC ON	A.ON	14	4	3	2			16
ARC OFF	A.OFF	10	14	12	10			10
Servo Voltage	S.V	26	40	40	40			26
Wire Tension	W.T	8	11	12	12			7
Wire Feed	W.F	11	12	12	12			11
Water Flow Rat	e W.F.R	7	0	0	0			7
G94F	FEED	0.9	1.6	2.1	2.1			1.2
FEED%	F.R	150	140	140	140			130
Upper Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle (Bap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega - cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.180						
Rough cut&1 Sl	kim	0.222	0.149					
Rough cut&2 Sl	kim	0.231	0.164	0.151				
Rough cut&3 Sl	kim	0.236	0.168	0.155	0.152			
OFFSET Differe	ence		0.066	0.013	0.003			
			RI	ESULTS				
Cutting Feed Ra	te (mm/min)	1.33~1.36	2.14~2.36	2.83~3.09	2.85~3.12			1.34~1.38
Gap Voltage (0	GV)	33~42	45~53	45~52	50~56			34~40
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

Wire Dia. and Type		Material Type			Material Thickness			
0.2	5 mm Brass		Ste	eel (SKD11)	100 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2			18
OFF TIME	T.OFF	8	12	10	9	S		8
ARC ON	A.ON	14	4	3	2			16
ARC OFF	A.OFF	10	14	12	10			10
Servo Voltage	S.V	26	40	40	40			26
Wire Tension	W.T	8	12	12	12		\mathbf{D}	7
Wire Feed	W.F	11	12	12	12			12
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	0.8	1.4	1.8	1.8			1.0
FEED%	F.R	140	140	140	140			120
Upper Nozzle G	ap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega-cm)$	55~60	55~60	55~60	55~60			55~60
)					
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.183						0.185
Rough cut&1 Sk	xim	0.225	0.150					
Rough cut&2 Sk	kim	0.234	0.165	0.152				
Rough cut&3 Sk	xim	0.237	0.169	0.156	0.152			
OFFSET Differe	ence		0.068	0.013	0.004			
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	1.10~1.25	1.93~2.03	2.49~2.53	2.50~2.56			1.19~1.34
Gap Voltage (C	(VC	32~45	43~52	45~53	46~55			33~43
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

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Wire Dia. and Type		e	Material Type			Material Thickness		
0.2	25 mm Brass		Steel (SKD11)			125 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	3			18
OFF TIME	T.OFF	8	11	9	8	S		8
ARC ON	A.ON	14	4	3	2			16
ARC OFF	A.OFF	8	12	10	8			9
Servo Voltage	S.V	26	40	40	40			26
Wire Tension	W.T	7	11	12	12			7
Wire Feed	W.F	12	12	12	12			12
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	0.8	1.4	1.8	1.8			0.9
FEED%	F.R	100	100	100	100			100
Upper Nozzle G	ap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega-cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.186						0.188
Rough cut&1 Sk	kim	0.230	0.153					
Rough cut&2 Sk	kim	0.239	0.168	0.153				
Rough cut&3 Sk	kim	0.242	0.170	0.157	0.154			
OFFSET Differe	ence		0.072	0.013	0.003			
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	0.77~0.81	1.38~1.43	1.79~1.82	1.81~1.86			0.88~0.94
Gap Voltage (C	GV)	31~44	43~51	44~53	46~55			32~43
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

Wire Dia. and Type		Material Type			Material Thickness			
0.2	25 mm Brass		Ste	el (SKD11)	150 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	3			18
OFF TIME	T.OFF	8	11	9	8	S		8
ARC ON	A.ON	14	4	3	2			16
ARC OFF	A.OFF	8	12	10	8			9
Servo Voltage	S.V	26	40	40	40			26
Wire Tension	W.T	7	11	12	12		\mathbf{D}	7
Wire Feed	W.F	12	12	12	12			12
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	0.6	1.2	1.6	1.6			0.6
FEED%	F.R	80	80	80	80			100
Upper Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle C	Bap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega - cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.188						
Rough cut&1 Sl	kim	0.238	0.156					
Rough cut&2 Sl	kim	0.244	0.170	0.155				
Rough cut&3 Sl	kim	0.246	0.172	0.158	0.154			
OFFSET Differe	ence		0.082	0.014	0.004			
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	0.47~0.51	0.95~0.98	1.25~1.30	1.27~1.38			0.58~0.63
Gap Voltage(C	GV)	29~40	42~53	43~55	45~50			31~42
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

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Wire Dia. and Type			Material Type			Material Thickness		
0.25 mm Brass			Copper			10 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO					7		
ON TIME	T.ON	16	6	4	2	1		16
OFF TIME	T.OFF	11	13	15	12	11		10
ARC ON	A.ON	14	4	2	1	1		14
ARC OFF	A.OFF	13	15	17	14	11		12
Servo Voltage	S.V	45	50	50	55	50		45
Wire Tension	W.T	7	11	11	11	11		7
Wire Feed	W.F	10	9	10	10	10		11
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	7.5	9.5	10.0	12.0	12.0		7.5
FEED%	F.R	170	170	170	170	170		180
Upper Nozzle G	lap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	lap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	55~70	55~70	55~70	55~70	55~70		55~70
		······						
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.180						0.181
Rough cut&1 Sł	kim	0.210	0.146					
Rough cut&2 Sl	kim	0.227	0.155	0.144				
Rough cut&3 Sł	kim	0.232	0.162	0.145	0.141			
Rough cut&4 Sk	kim	0.233	0.163	0.146	0.142	0.141		
OFFSET Differe	ence		0.070	0.017	0.004	0.001		
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	12.0~14.0	15.0~16.5	16.5~18.0	17.0~19.0	17.0~19.0		13.0~14.5
Gap Voltage (C	GV)	55~68	60~75	70~78	70~78	70~78		53~68
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.58		3.0

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Wire Dia. and Type			Material Type			Material Thickness		
0.25 mm Brass			Copper			20 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO					1		
ON TIME	T.ON	16	6	4	2	1		18
OFF TIME	T.OFF	10	13	15	11	11		11
ARC ON	A.ON	14	4	3	1	1		16
ARC OFF	A.OFF	12	15	17	13	11	0.	13
Servo Voltage	S.V	40	50	50	50	50		40
Wire Tension	W.T	8	11	11	11	11		8
Wire Feed	W.F	10	10	10	10	10		10
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	6.0	9.0	11.0	12.0	12.0		6.0
FEED%	F.R	110	110	110	110	110		130
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	Jap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	55~65	55~65	55~65	55~65	55~65		55~65
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.182						0.183
Rough cut&1 Sł	kim	0.223	0.147					
Rough cut&2 Sl	kim	0.234	0.156	0.144				
Rough cut&3 Sl	kim	0.239	0.162	0.146	0.141			
Rough cut&4 Sł	kim	0.240	0.163	0.147	0.142	0.141		
OFFSET Differe	ence		0.077	0.016	0.005	0.001		
	RESULTS							
Cutting Feed Ra	te (mm/min)	6.5~7.5	8.3~9.5	10.~11.2	10.5~11.6	10.5~11.6		7.5~8.5
Gap Voltage ((GV)	45~53	50~60	60~70	61~71	61~71		45~53
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.56	<u> </u>	3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type			Material Type			Material Thickness		
0.25 mm Brass			Copper			30 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO					1		
ON TIME	T.ON	16	6	4	2	1		18
OFF TIME	T.OFF	10	13	14	11	11		11
ARC ON	A.ON	14	4	2	1	1		16
ARC OFF	A.OFF	12	15	16	13	11	0.	13
Servo Voltage	S.V	38	45	45	45	50		38
Wire Tension	W.T	8	11	11	11	11		8
Wire Feed	W.F	10	10	10	10	10		10
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	6.0	8.0	8.5	9.0	9.0		6.0
FEED%	F.R	90	90	90	90	90		90
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	lap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	45~60	50~60	50~60	50~60	50~55		45~60
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.183						0.184
Rough cut&1 Sł	kim	0.223	0.148					
Rough cut&2 Sł	kim	0.235	0.156	0.145				
Rough cut&3 Sł	kim	0.239	0.163	0.147	0.142			
Rough cut&4 Sł	<u>kim</u>	0.240	0.164	0.148	0.143	0.142		
OFFSET Differe	ence		0.076	0.016	0.005	0.001		
		1	RE	ESULTS	1		1	
Cutting Feed Ra	te (mm/min)	5.0~5.8	7.0~7.8	7.5~8.2	8.0~9.0	8.0~9.0		5.0~6.0
Gap Voltage (C	GV)	40~50	50~60	50~60	50~60	50~60		40~50
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	8.0~9.0		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	50~60		3.0

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Wire Dia. and Type			Material Type			Material Thickness		
0.25 mm Brass			Copper			40 mm		
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Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO					1		
ON TIME	T.ON	16	6	4	2	1		18
OFF TIME	T.OFF	10	13	14	11	11		11
ARC ON	A.ON	14	4	2	1	1		16
ARC OFF	A.OFF	12	15	16	13	11	0.	13
Servo Voltage	S.V	38	45	45	45	50		38
Wire Tension	W.T	8	11	11	11	11		8
Wire Feed	W.F	10	10	10	10	10		10
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	4.5	6.0	6.5	7.0	7.0		5.0
FEED%	F.R	90	90	90	90	90		90
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	Jap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	42~55	48~59	52~60	51~61	51~61		44~59
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.184						0.184
Rough cut&1 Sl	kim	0.224	0.149					
Rough cut&2 Sl	kim	0.235	0.157	0.147				
Rough cut&3 Sl	kim	0.239	0.165	0.147	0.144			
Rough cut&4 Sl	kim	0.240	0.166	0.148	0.145	0.144		
OFFSET Differe	ence		0.074	0.018	0.003	0.001		
			RI	ESULTS				
Cutting Feed Ra	te (mm/min)	3.6~4.4	5.2~6.0	5.8~6.6	7.2~8.0	7.2~8.0		4.1~4.7
Gap Voltage ((GV)	40~50	50~60	50~60	50~60	50~60		35~48
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.59	<u> </u>	3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type			Material Type			Material Thickness		
0.25 mm Brass			Copper			50 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2	1		18
OFF TIME	T.OFF	9	13	13	9	11		10
ARC ON	A.ON	14	4	2	1	1		16
ARC OFF	A.OFF	11	14	15	10	11	0.	12
Servo Voltage	S.V	35	45	45	45	50		35
Wire Tension	W.T	9	12	12	12	12		8
Wire Feed	W.F	10	10	10	10	10		10
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	2.0	4.0	5.0	5.0	5.0		2.0
FEED%	F.R	140	140	120	120	120		160
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	lap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	53~60	53~60	53~60	53~60	53~60		53~60
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.188						0.190
Rough cut&1 Sł	kim	0.232	0.154					
Rough cut&2 Sl	kim	0.242	0.164	0.152				
Rough cut&3 Sł	kim	0.242	0.164	0.155	0.152			
Rough cut&4 Sł	kim	0.243	0.165	0.156	0.153	0.152		
OFFSET Differe	ence		0.078	0.009	0.003	0.001		
	RESULTS							
Cutting Feed Ra	te (mm/min)	2.75~3.13	5.45~5.66	5.96~6.13	5.96~6.14	5.96~6.14		3.16~3.34
Gap Voltage ((GV)	38~52	45~55	50~60	52~63	52~63		40~55
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.56	<u> </u>	3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type			Material Type			Material Thickness		
0.25 mm Brass			Copper			60 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2			18
OFF TIME	T.OFF	9	13	13	9	S		10
ARC ON	A.ON	14	4	2	1			16
ARC OFF	A.OFF	11	14	15	10			12
Servo Voltage	S.V	35	45	45	45			35
Wire Tension	W.T	9	12	12	12			8
Wire Feed	W.F	10	10	10	10			10
Water Flow Rat	e W.F.R	7	0	0	0			7
G94F	FEED	1.8	3.0	4.0	4.0			1.8
FEED%	F.R	140	140	140	140			160
Upper Nozzle G	ap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle C	Jap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega - cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.192						0.194
Rough cut&1 Sl	kim	0.234	0.156					
Rough cut&2 Sl	kim	0.244	0.166	0.154				
Rough cut&3 Sl	kim	0.244	0.166	0.157	0.154			
OFFSET Differe	ence		0.078	0.009	0.002			
RESULTS								
Cutting Feed Ra	te (mm/min)	2.44~2.56	4.10~4.45	5.40~5.65	5.55~5.75			2.86~2.99
Gap Voltage (C	GV)	39~46	45~56	50~60	53~64			39~46
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type			Material Type			Material Thickness		
0.25 mm Brass			Copper			70 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2			18
OFF TIME	T.OFF	9	12	12	9	S		10
ARC ON	A.ON	14	4	2	1			16
ARC OFF	A.OFF	11	14	14	10			12
Servo Voltage	S.V	33	45	45	45			33
Wire Tension	W.T	9	12	12	12			8
Wire Feed	W.F	10	10	10	11			10
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	1.6	2.8	3.6	3.6			1.6
FEED%	F.R	130	120	120	120			150
Upper Nozzle G	ap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle Gap		0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega - cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.194						0.195
Rough cut&1 Sl	kim	0.237	0.158					
Rough cut&2 Skim		0.246	0.168	0.156				
Rough cut&3 Skim		0.247	0.169	0.159	0.156			
OFFSET Difference			0.078	0.010	0.003			
RESULTS								
Cutting Feed Rate (mm/min)		2.04~2.22	3.33~3.53	4.21~4.66	4.32~4.72			2.25~2.45
Gap Voltage (GV)		35~45	48~56	50~58	55~60			38~46
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type			Material Type			Material Thickness		
0.25 mm Brass			Copper			80 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO					1		
ON TIME	T.ON	16	6	4	2			18
OFF TIME	T.OFF	8	11	11	9	S		10
ARC ON	A.ON	14	4	2	1			16
ARC OFF	A.OFF	10	13	13	10			12
Servo Voltage	S.V	30	43	43	43			32
Wire Tension	W.T	9	12	12	12			8
Wire Feed	W.F	11	11	11	11			11
Water Flow Rate	e W.F.R		0	0	0			7
G94F	FEED	1.4	2.4	3.3	3.3			1.4
FEED%	F.R	130	120	120	120			150
Upper Nozzle Gap		0.2	0.2	0.2	0.2			0.2
Lower Nozzle Gap		0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega - cm)$	50~55	50~55	50~55	50~55			50~55
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.195						0.196
Rough cut&1 Sl	kim	0.238	0.159					
Rough cut&2 Sl	kim	0.247	0.169	0.157				
Rough cut&3 Skim		0.249	0.170	0.160	0.157			
OFFSET Difference			0.079	0.010	0.003			
RESULTS								
Cutting Feed Rate (mm/min) 1.78		1.78~1.88	2.96~3.24	3.92~4.24	3.96~4.44			2.04~2.24
Gap Voltage (GV)		35~46	45~56	46~52	50~58			35~43
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type			Material Type			Material Thickness		
0.25 mm Brass			Copper			90 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2			18
OFF TIME	T.OFF	8	11	11	9	S		10
ARC ON	A.ON	14	4	2	1			16
ARC OFF	A.OFF	10	13	13	10			12
Servo Voltage	S.V	30	43	43	43			32
Wire Tension	W.T	9	12	12	12			8
Wire Feed	W.F	11	11	11	11			11
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	1.2	2.0	3.0	3.0			1.2
FEED%	F.R	120	120	120	120			140
Upper Nozzle Gap		0.2	0.2	0.2	0.2			0.2
Lower Nozzle Gap		0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55			50~55
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.197						0.198
Rough cut&1 Sl	kim	0.240	0.161					
Rough cut&2 Skim		0.249	0.171	0.159				
Rough cut&3 Skim		0.251	0.172	0.162	0.159			
OFFSET Difference			0.079	0.010	0.003			
RESULTS								
Cutting Feed Rate (mm/min)		1.80~1.92	2.36~2.44	3.46~3.64	3.58~3.72			1.64~1.78
Gap Voltage (GV)		34~43	45~55	46~55	50~60			35~42
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0
WCUT Machning	Data Sheet							
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Wire Dia. and Type		Material Type			Material Thickness			
0.2	25 mm Brass		Copper			100 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2			18
OFF TIME	T.OFF	8	11	10	8	S		9
ARC ON	A.ON	14	4	2	2			16
ARC OFF	A.OFF	10	13	12	10			11
Servo Voltage	S.V	30	40	40	40			28
Wire Tension	W.T	8	12	12	12			8
Wire Feed	W.F	11	11	11	11			12
Water Flow Rat	e W.F.R	7	0	0	0			7
G94F	FEED	1.0	1.5	2.5	2.5			1.0
FEED%	F.R	120	120	120	120			140
Upper Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle (Bap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55			50~55
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.198						0.199
Rough cut&1 Sl	kim	0.242	0.162					
Rough cut&2 Sl	kim	0.250	0.172	0.160				
Rough cut&3 Sl	kim	0.252	0.173	0.163	0.160			
OFFSET Different	ence		0.079	0.010	0.003			
			RE	ESULTS				
Cutting Feed Ra	ate (mm/min)	1.18~1.24	1.76~1.88	2.85~3.15	2.90~3.30			1.35~1.45
Gap Voltage ((GV)	31~39	45~54	45~53	48~55			32~40
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type		Material Type			Material Thickness			
0.2	25 mm Brass		Copper			125 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	3			18
OFF TIME	T.OFF	8	10	10	8	S		8
ARC ON	A.ON	14	4	3	2			16
ARC OFF	A.OFF	10	12	12	10			10
Servo Voltage	S.V	28	40	40	40			40
Wire Tension	W.T	8	12	12	12			8
Wire Feed	W.F	12	12	12	12			12
Water Flow Rat	e W.F.R	7	0	0	0			7
G94F	FEED	0.8	1.4	2.5	2.5			1.0
FEED%	F.R	100	100	100	100			100
Upper Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle (Bap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega - cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.200						0.201
Rough cut&1 Sl	kim	0.250	0.164					
Rough cut&2 Sl	kim	0.256	0.174	0.162				
Rough cut&3 Sl	kim	0.264	0.174	0.165	0.162			
OFFSET Different	ence		0.090	0.009	0.002			
			RE	ESULTS			1	
Cutting Feed Ra	ate (mm/min)	0.78~0.84	1.38~1.54	2.45~2.75	2.50~2.80			0.95~1.15
Gap Voltage ((GV)	30~40	42~52	45~53	48~65			31~42
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type		Material Type			Material Thickness			
0.2	25 mm Brass		Copper			150 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO					4		
ON TIME	T.ON	16	6	4	3			18
OFF TIME	T.OFF	8	11	10	8	S		8
ARC ON	A.ON	14	5	3	2			16
ARC OFF	A.OFF	9	13	11	9			9
Servo Voltage	S.V	28	40	40	40			30
Wire Tension	W.T	7	12	12	12			7
Wire Feed	W.F	12	12	12	13			12
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	0.6	1.2	2.2	2.2			0.8
FEED%	F.R	100	100	100	100			100
Upper Nozzle G	ap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle C	lap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55			50~55
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.202						0.203
Rough cut&1 Sl	kim	0.258	0.166					
Rough cut&2 Sl	kim	0.266	0.178	0.163				
Rough cut&3 Sl	kim	0.268	0.180	0.168	0.163			
OFFSET Differe	ence		0.088	0.012	0.005			
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	0.58~0.64	1.18~1.26	2.10~2.34	2.15~2.35			0.78~0.82
Gap Voltage(C	GV)	30~40	42~50	43~52	45~56			30~41
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type			Material Type			Material Thickness		
0.2	25 mm Brass		Aluminium			10 mm		
-								
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2	1		17
OFF TIME	T.OFF	12	13	13	10	11		13
ARC ON	A.ON	12	4	2	1	1		13
ARC OFF	A.OFF	14	15	15	11	11	0.	15
Servo Voltage	S.V	50	50	55	55	50		45
Wire Tension	W.T	7	10	10	10	10		7
Wire Feed	W.F	9	9	9	9	10		9
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	12.0	20.0	30.0	30.0	30.0		12.0
FEED%	F.R	160	160	160	160	160		170
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	lap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55	50~55		50~55
)					
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.192						0.193
Rough cut&1 Sł	kim	0.243	0.148					
Rough cut&2 Sl	kim	0.258	0.161	0.139				
Rough cut&3 Sl	kim	0.258	0.165	0.148	0.138			
Rough cut&4 Sł	kim	0.259	0.166	0.149	0.139	0.138		
OFFSET Differe	ence		0.093	0.017	0.010	0.001		
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	18.2~20.2	31.0~33.0	46.0~48.0	46.0~48.0	46.0~48.0		19.4~21.4
Gap Voltage ((GV)	55~60	60~65	60~65	65~70	65~70		50~60
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.61		3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type			Material Type			Material Thickness		
0.2	25 mm Brass		Aluminium			20 mm		
-								
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2	1		18
OFF TIME	T.OFF	12	13	13	10	11		13
ARC ON	A.ON	12	4	2	1	1		14
ARC OFF	A.OFF	14	15	15	11	11	0.	15
Servo Voltage	S.V	50	50	55	55	50		45
Wire Tension	W.T	7	11	10	10	10		7
Wire Feed	W.F	9	9	9	9	10		9
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	8.0	13.0	20.0	20.0	20.0		8.0
FEED%	F.R	120	130	130	130	130		160
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	lap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55	50~55		50~55
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.197						0.198
Rough cut&1 Sł	kim	0.245	0.150					
Rough cut&2 Sl	kim	0.260	0.165	0.141				
Rough cut&3 Sl	kim	0.270	0.175	0.147	0.141			
Rough cut&4 Sł	kim	0.271	0.176	0.148	0.142	0.141		
OFFSET Differe	ence		0.095	0.028	0.006	0.001		
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	9.0~10.0	15.5~17.5	25.0~27.0	25.0~27.0	25.0~27.0		12.0~13.5
Gap Voltage (C	GV)	56~61	60~69	63~69	59~67	59~67		51~59
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.60		3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type			Material Type			Material Thickness		
0.2	25 mm Brass		Aluminium			30 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2	1		18
OFF TIME	T.OFF	12	13	13	10	11		13
ARC ON	A.ON	12	4	2	1	1		14
ARC OFF	A.OFF	14	15	15	11	11	0.	15
Servo Voltage	S.V	50	50	55	55	50		45
Wire Tension	W.T	7	11	10	10	10	2	7
Wire Feed	W.F	9	9	9	9	10		9
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	5.0	7.0	10.0	10.0	10.0		5.0
FEED%	F.R	130	160	160	160	160		150
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	lap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55	50~55		50~55
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.201						0.202
Rough cut&1 Sł	kim	0.250	0.152					
Rough cut&2 Sł	kim	0.262	0.165	0.146				
Rough cut&3 Sł	kim	0.272	0.176	0.154	0.145			
Rough cut&4 Sk	xim	0.273	0.177	0.155	0.146	0.145		
OFFSET Differe	ence		0.096	0.022	0.009	0.001		
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	6.0~7.5	11.0~12.5	15.0~16.5	15.0~16.5	15.0~16.5		7.0~8.5
Gap Voltage (C	GV)	55~62	63~68	65~70	65~70	65~70		50~60
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.61		3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type		Material Type			Material Thickness			
0.2	25 mm Brass		Aluminium			40 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2	1		18
OFF TIME	T.OFF	12	13	13	10	11		13
ARC ON	A.ON	12	4	2	1	1		14
ARC OFF	A.OFF	14	15	15	11	11	0.	15
Servo Voltage	S.V	50	50	55	50	50		45
Wire Tension	W.T	7	11	10	10	10		7
Wire Feed	W.F	9	9	9	9	10		9
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	4.0	6.0	9.0	9.0	9.0		4.0
FEED%	F.R	120	140	140	140	140		140
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	lap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55	50~55		50~55
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.205						0.208
Rough cut&1 Sł	kim	0.253	0.154					
Rough cut&2 Sl	kim	0.265	0.165	0.149				
Rough cut&3 Sl	kim	0.273	0.176	0.154	0.147			
Rough cut&4 Sł	kim	0.274	0.177	0.155	0.148	0.147		
OFFSET Differe	ence		0.0970	0.022	0.007	0.001		
			RI	ESULTS				
Cutting Feed Ra	te (mm/min)	4.6~5.6	8.2~9.2	12.0~13.6	12.2~13.6	12.2~13.6		5.4~6.6
Gap Voltage ((GV)	55~61	62~69	60~70	58~65	58~65		50~60
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.60	<u> </u>	3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type			Material Type			Material Thickness		
0.2	25 mm Brass		Aluminium			50 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2	1		18
OFF TIME	T.OFF	12	13	13	10	11		13
ARC ON	A.ON	12	4	2	1	1		14
ARC OFF	A.OFF	14	15	15	11	11	0.	15
Servo Voltage	S.V	50	50	55	55	50		45
Wire Tension	W.T	7	11	11	12	12		7
Wire Feed	W.F	9	9	9	10	10		9
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	3.0	5.0	8.0	8.5	8.5		3.0
FEED%	F.R	120	120	120	120	120		150
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	lap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55	50~55		50~55
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.208						0.212
Rough cut&1 Sl	kim	0.256	0.156					
Rough cut&2 Sl	kim	0.268	0.166	0.151				
Rough cut&3 Sl	kim	0.275	0.176	0.155	0.148			
Rough cut&4 SI	kim	0.276	0.177	0.156	0.149	0.148		
OFFSET Differe	ence		0.099	0.021	0.007	0.001		
			RI	ESULTS				
Cutting Feed Ra	te (mm/min)	3.4~4.0	5.8~6.2	9.4~10.2	9.8~10.6	9.8~10.6		4.3~4.6
Gap Voltage ((GV)	53~61	60~70	65~75	65~70	60~70		53~62
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.6	<u> </u>	3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type			Material Type			Material Thickness		
0.2	25 mm Brass		Aluminium			60 mm		
-								
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3	Skim4		Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2	1		18
OFF TIME	T.OFF	12	13	13	10	11		13
ARC ON	A.ON	12	4	2	1	1		14
ARC OFF	A.OFF	14	15	15	11	11	0.	15
Servo Voltage	S.V	50	50	50	50	50		45
Wire Tension	W.T	7	11	11	12	12		7
Wire Feed	W.F	9	9	9	10	10		10
Water Flow Rate	e W.F.R	7	0	0	0	0		7
G94F	FEED	3.6	5.0	8.0	8.0	8.0		3.6
FEED%	F.R	100	100	100	100	100		120
Upper Nozzle G	ap	0.2	0.2	0.2	0.2	0.2		0.2
Lower Nozzle C	lap	0.2	0.2	0.2	0.2	0.2		0.2
Liquid Quantity	$(K\Omega-cm)$	55~60	55~60	55~60	55~60	55~60		55~60
OFFSET No	(D)	00	01	02	03	04		00
Rough cut		0.210						0.212
Rough cut&1 Sl	kim	0.257	0.157					
Rough cut&2 Sl	kim	0.270	0.168	0.152				
Rough cut&3 Sl	kim	0.275	0.176	0.156	0.149			
Rough cut&4 Sl	xim	0.276	0.177	0.157	0.150	0.149		
OFFSET Differe	ence		0.099	0.020	0.007	0.001		
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	3.8~4.0	4.8~5.4	7.8~8.6	8.1~8.8	8.1~8.8		4.2~4.6
Gap Voltage ((GV)	52~60	55~64	60~70	60~70	60~70		48~58
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6	3~5		17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9	0.6		3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type		Material Type			Material Thickness			
0.2	5 mm Brass		Aluminium			70 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO					1		
ON TIME	T.ON	16	6	4	2			18
OFF TIME	T.OFF	12	13	13	10	5		13
ARC ON	A.ON	12	4	2	1			14
ARC OFF	A.OFF	14	15	15	11			15
Servo Voltage	S.V	45	45	50	50			45
Wire Tension	W.T	8	11	11	12			8
Wire Feed	W.F	11	11	11	11			11
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	2.6	4.8	7.5	7.5			2.8
FEED%	F.R	100	100	100	100			100
Upper Nozzle G	ap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega - cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.212						0.214
Rough cut&1 Sk	kim	0.256	0.158					
Rough cut&2 Sk	<u>kim</u>	0.271	0.168	0.153				
Rough cut&3 Sk	kim	0.276	0.177	0.158	0.150			
OFFSET Differe	ence		0.099	0.019	0.0080.008			
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	2.6~2.9	4.4~5.8	7.4~8.4	7.6~8.6			2.7~3.0
Gap Voltage (C	(VC	48~58	52~60	53~62	60~70			48~56
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type		Material Type			Material Thickness			
0.2	25 mm Brass		Aluminium			80 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2			18
OFF TIME	T.OFF	12	13	13	10	S		13
ARC ON	A.ON	12	4	2	1			14
ARC OFF	A.OFF	14	15	15	11			15
Servo Voltage	S.V	45	45	50	50			45
Wire Tension	W.T	8	11	11	12			8
Wire Feed	W.F	11	11	11	11			11
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	1.8	4.4	7.2	7.2			2.0
FEED%	F.R	120	120	120	120			120
Upper Nozzle G	ap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle C	Jap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega - cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.213						0.215
Rough cut&1 Sł	kim	0.256	0.157					
Rough cut&2 SI	kim	0.272	0.169	0.153				
Rough cut&3 Sł	kim	0.276	0.177	0.159	0.151			
OFFSET Differe	ence		0.099	0.018	0.008			
			RI	ESULTS				
Cutting Feed Ra	te (mm/min)	2.10~2.24	5.20~5.60	8.60~8.76	8.64~8.78			2.34~2.48
Gap Voltage ((GV)	48~58	52~60	53~62	60~70			48~56
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type		Material Type			Material Thickness			
0.2	25 mm Brass		Aluminium			90 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO					7		
ON TIME	T.ON	16	6	4	2			18
OFF TIME	T.OFF	11	13	12	10			13
ARC ON	A.ON	12	4	2	1			14
ARC OFF	A.OFF	14	15	15	11			15
Servo Voltage	S.V	40	45	45	45			40
Wire Tension	W.T	8	11	11	12			8
Wire Feed	W.F	11	12	12	12			11
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	1.6	4.2	7.0	7.0			1.8
FEED%	F.R	110	110	110	110			110
Upper Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle C	Bap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega - cm)$	55~60	55~60	55~60	55~60			55~60
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.215						0.217
Rough cut&1 Sl	kim	0.258	0.159					
Rough cut&2 Sl	kim	0.274	0.171	0.155				
Rough cut&3 Sl	kim	0.278	0.179	0.161	0.153			
OFFSET Differe	ence		0.099	0.018	0.008			
			RE	ESULTS				
Cutting Feed Ra	te (mm/min)	1.74~1.78	4.58~4.66	7.5~7.8	7.5~7.8			1.96~2.04
Gap Voltage ((GV)	43~49	46~55	51~60	53~63			42~53
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9		<u> </u>	3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type		Material Type			Material Thickness			
0.25 mm Brass			Aluminium			100 mm		
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2			18
OFF TIME	T.OFF	11	13	12	10	S		12
ARC ON	A.ON	14	4	2	2			14
ARC OFF	A.OFF	13	15	14	12			14
Servo Voltage	S.V	40	45	45	45			40
Wire Tension	W.T	8	11	11	12			8
Wire Feed	W.F	11	12	12	12			11
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	1.5	4.0	6.5	6.5			1.6
FEED%	F.R	100	100	100	100			100
Upper Nozzle G	ap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle Gap		0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~5			50~55
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.216						0.218
Rough cut&1 Sk	kim	0.258	0.160					
Rough cut&2 Skim		0.275	0.172	0.155				
Rough cut&3 Skim		0.279	0.180	0.163	0.154			
OFFSET Differe	ence		0.099	0.017	0.009			
RESULTS								
Cutting Feed Rate (mm/min) 1.4		1.48~1.53	3.96~4.22	6.3~6.8	6.4~6.9			1.56~1.63
Gap Voltage (C	(VC	43~49	50~56	54~60	54~60			43~50
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type		Material Type			Material Thickness			
0.25 mm Brass		Aluminium		125 mm				
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO							
ON TIME	T.ON	16	6	4	2			18
OFF TIME	T.OFF	11	12	12	9	S		12
ARC ON	A.ON	14	5	3	2			14
ARC OFF	A.OFF	13	14	14	9			14
Servo Voltage	S.V	40	45	45	45			45
Wire Tension	W.T	9	12	12	12		\mathbf{D}	9
Wire Feed	W.F	12	12	12	12			12
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	1.0	2.5	4.2	4.2			1.2
FEED%	F.R	100	100	100	100			100
Upper Nozzle G	lap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle C	Bap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55			50~55
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.218						0.220
Rough cut&1 Sl	kim	0.260	0.162					
Rough cut&2 Sl	kim	0.279	0.174	0.157				
Rough cut&3 Sl	kim	0.284	0.182	0.165	0.156			
OFFSET Differe	ence		0.102	0.017	0.009			
RESULTS								
Cutting Feed Rate (mm/min) 0.95		0.95~1.11	2.43~2.52	4.10~4.44	4.10~4.44			1.14~1.25
Gap Voltage((GV)	41~51	45~56	50~58	53~60			41~50
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	µ mRa	2.8	1.4	1.1	0.9			3.0

WCUT Machning	Data Sheet
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Wire Dia. and Type		Material Type			Material Thickness			
0.25 mm Brass		Aluminium			150 mm			
Cutting Process		Stable						Max
		Rough cut	Skim1	Skim2	Skim3			Rough cut
EDM Number	NO					1		
ON TIME	T.ON	16	6	4	3			18
OFF TIME	T.OFF	11	12	11	9	S		12
ARC ON	A.ON	14	5	3	2			14
ARC OFF	A.OFF	13	14	13	9			14
Servo Voltage	S.V	40	45	45	45			40
Wire Tension	W.T	8	12	12	12			8
Wire Feed	W.F	13	13	13	13			13
Water Flow Rate	e W.F.R	7	0	0	0			7
G94F	FEED	0.7	2.0	3.4	3.4			0.8
FEED%	F.R	100	100	100	100			100
Upper Nozzle G	ap	0.2	0.2	0.2	0.2			0.2
Lower Nozzle C	lap	0.2	0.2	0.2	0.2			0.2
Liquid Quantity	$(K\Omega-cm)$	50~55	50~55	50~55	50~55			50~55
OFFSET No	(D)	00	01	02	03			00
Rough cut		0.220						0.222
Rough cut&1 Sł	kim	0.264	0.164					
Rough cut&2 SI	kim	0.283	0.177	0.159				
Rough cut&3 Sł	kim	0.288	0.185	0.168	0.158			
OFFSET Differe	ence		0.103	0.017	0.010			
RESULTS								
Cutting Feed Rate (mm/min) 0.6		0.66~0.72	1.95~2.15	3.35~3.55	3.35~3.55			0.76~0.82
Gap Voltage ((GV)	39~48	46~53	48~56	50~59			41~50
Finish Surface	μ mRmax	15~18	7~9	5~7	4~6			17~20
Roughness	μ mRa	2.8	1.4	1.1	0.9			3.0